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ON THE USE OF EXTREME
VALUE THEORY
IN ENERGY MARKETS

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SUMMARY

The thesis intent is to provide a set of statistical methodologies in the field of Extreme Value Theory (EVT) with a particular application to energy losses, in Gigawatt-hours (GWh) experienced by electrical generating units (GU's).

Due to the complexity of the energy market, the thesis focuses on the volume loss only and does not expand into the price, cost or mixes thereof (although the strong relationship between volume and price is acknowledged by some initial work on the energy price [SMP] is provided in Appendix B)

Hence, occurrences of excessive unexpected energy losses incurred by these GU's formulate the problem.

Exploratory Data Analysis (EDA) structures the data and attempts at giving an indication on the categorisation of the excessive losses. The size of the GU failure is also investigated from an aggregated perspective to relate to the Generation System. Here the effect of concomitant variables (such as the Load Factor imposed by the market) is emphasised. Cluster Analysis (2-Way Joining) provided an initial categorising technique. EDA highlights the shortfall of a scientific approach to determine the answer to the question at when is a large loss sufficiently large that it affects the System. The usage of EVT shows that the GWh Losses tend to behave as a variable in the Fréchet domain of attraction. The Block Maxima (BM) and Peak-Over-Threshold (POT), the latter as semi and full parametric, methods are investigated. The POT methodologies are both applicable. Of particular interest is the Q-Q plots results on the semi-parametric POT method, which yielded results that fit

the data satisfactorily (pp 55-56). The Generalised Pareto Distribution (GPD) models well the tail of the GWh Losses above a threshold under the POT full parametric method. Different methodologies were explored in determining the parameters of the GPD. The method of 3-LM (linear combinations of Probability Weighted Moments) is used to arrive at initial estimates of the GPD parameters. A GPD is finally parameterised for the GWh Losses above 766 GWh. The Bayesian philosophy is also utilised in this thesis as it provides a predictive distribution of (high quantiles) the large GWh Losses. Results are found in this part of the thesis in so far that it utilises the ratio of the Mean Excess Function (the expectation of a loss above a certain threshold) over its probability of exceeding the threshold as an indicator to establish the minimum of this ratio. The technique was developed for the GPD by using the Fisher Information Matrix (FIM) and the Delta-Method. Prediction of high quantiles were done by using Markov Chain Monte Carlo (MCMC) and eliciting the GPD Maximal Data Information (MDI) prior. The last EVT methodology investigated in the thesis is the one that uses the Dirichlet process and the method of Negative Differential Entropy (NDE). The thesis also opened new areas of pertinent research.

Keywords:

Extreme Value Theory, Energy Markets, Gigawatt-hours Losses, Cluster Analysis (2-Way Joining), Q-Q Plots, Generalised Pareto Distribution, GPD Fisher Information Matrix, GPD Jeffreys' Prior.

SAMEVATTING

Die doel van die skripsie is om 'n stel statistiese metodologië in die veld van Ekstreme Waarde Teorie te voorsien met 'n besondere aanwending van verlore energie in Gigawatt-ure en wat ondervind is deur elektries-ontwikkelde eenhede.

As gevolg van die kompleksiteit van die energiemark, fokus die skripsie alleenlik op die volume verlies en nie op die pryskoste of die verhouding daarvan nie, alhoewel die sterk verhouding tussen volume en prys erken word aan die beginstadium van werk op die energieprys wat in Aanhangsel B voorsien word.

Hierna word verspreiding van buitensporige onverwagte verlore energie deur hierdie ontwikkelde eenhede blootgestel wat die probleem formuleer.

Verkennde data ontleding struktureer die data en pogings om 'n aanduiding te gee op die kategorisering van die oormatige verliese. Die grootte van die mislukte ontwikkelde eenheid is ook ondersoek vanuit 'n gesamentlike perspektief om die Opwekkingstelsel in verband te bring. Hier word die effek van gepaardgaande veranderlikes (soos wat die Gelaai Faktor deur die mark voorgeskryf word) beklemtoon. Bondelontleding (2-Way Joining) het 'n aanvanklike kategoriserings tegniek voorsien. Verkennde data-ontleding lig die gebrek aan 'n wetenskaplike benadering uit om die antwoord op die vraag te bepaal wanneer 'n groot verlies groot genoeg is om die Stelsel te beïnvloed.

Die gebruik van Ekstreemwaarde-teorie toon dat die GW-ure verliese geneig is om as 'n veranderlike in te tree in die Fréchet gebied.

Die Blok-Maksima en “Peak-Over Threshold” (POT) metodes, laasgenoemde as half en vol parametrisiese metodes, is ondersoek. Die POT metodologië is beide bruikbaar. Uit besondere belangstelling lewer die Q-Q voorstellings van die half parametrisiese POT metode, goeie resultate. Die Veralgemeende Pareto-verdeling (GPD) modelleer die stert van GWh-verliese bokant a drempelwaarde onder POT goed. Verskillende metodologië was ondersoek deur die bepaling van parameters van die GPD. Die metode van 3-LM (lineêr kombinasies van die Waarskynlikheid-Geweegde-Momente-metode) is gebruik as 'n eerste skatting van die GPD parameters. 'n GPD is finaal geparameteriseer vir die GW-ure verliese bo 766 GW-ure. Die Bayes-filosofie is ook gebruik in hierdie skripsie en voorsien 'n voorspellingsfunksie van (hoë kwantiele) van groot GW-ure verliese. Nuwe werk is in hierdie gedeelte van die skripsie gedoen in soverre dit die gebruik van die verhouding van die gemiddelde-oorskrydingsfunksie relatief tot 'n oorskrydingswaarskynlikheid as 'n aanwysing om die minimum van hierdie verhouding te vestig. Die tegniek was ontwikkel vir die GPD deur die Fisher-informasiematriks en die Delta-metode te gebruik. Voorspelling van hoë kwantiele is deur die gebruik van MCMC gedoen en die MDI prior vir die GPD is gebruik. Die laaste Ekstreemwaarde metodologie wat in die skripsie ondersoek is, is die een wat die Dirichlet proses en die metode van Negatiewe-Afgeleide-Entropie gebruik.

Die skripsie open ook nuwe areas vir gepaste navorsing.

Sleutelwoorde:

Ekstreemwaarde-teorie, Energiemarkte, Gigawatureverliese, Bondelanaliese (2-Way Joining), Q-Q voorstellings, Veralgemeende Paretoverdeling, GPD Fisher-informasiematriks, GPD Jeffreys' prior.

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TABLE OF CONTENTS

Acknowledgements	i
Table of Contents	iii
List of Abbreviations	viii
EAGLE VIEW of the APPROACH taken on this	
Thesis	xi
Preface	xiii
Chapter 1 – Introduction	1
1.1 The Energy Market Environment	1
1.2 Basics of Extreme Value Theory	6
Chapter 2 – Exploratory Data Analysis (EDA)	14
2.1 Data Structure	14
2.2 Cluster Analysis	16
2.3 Number of Generating Units failing	24
Chapter 3 – Analysis of Extremes	
in GWh Losses	43
3.1 Introduction	43
3.2 Block Maxima	44
3.3 Peak Over Threshold	51
Chapter 4 – Bayesian Approach to the GPD Fit	78
4.1 Introduction	78
4.2 The Fit of the Tail – Log Normal and GPD	85
4.3 Predicting High Quantiles	98
4.4 Relationship between MEF &	
the Tail of the GPD	101
4.5 The Dirichlet Process	104
Chapter 5 – Conclusion	107
5.1 Categorisation	107

5.2 Fitting of the Tail	107
5.3 Bayesian Method	108
5.4 General	108
Appendix A	
1 Notation	110
2 Classical EVT	112
2.1 The Generalised Extreme Value Distribution an Index (GEV & EVI)	114
2.2 The Fréchet-Pareto Case: $\gamma > 0$	118
2.3 Methods of Block Maxima (BM) and Peak Over Threshold (POT)	120
2.4 Mean Excess Function	131
2.5 GEV Mean and Variance	133
Appendix B	
1 Modelling Returns	135
2 Stochastic Processes	139
3 Modelling Returns 2 nd Method	142
Appendix C	
1 Exploratory Data Analysis (EDA)	149
2 General Statistical Work	151
2.1 Bayes Theorem	151
2.2 Binomial Distribution	151
2.3 Poisson Distribution	152
2.4 Relationship between the Poisson and Binomial Distributions	152
2.5 Quantiles	155
2.6 Pickands Estimator	157
2.7 Gamma Series Functions	158
2.8 Entropy	162
2.9 Dirichlet Process	164
2.10 Wobbles	169
3 Bayesian Methods	170

3.1 The Fisher Information Matrix	170
3.2 The Delta Method (DM)	185
4 General Discussions and Remarks	187
4.1 Discussion on EDA	187
4.2 Steven's Theorem	191

List of Figures

1.1 Schematic Diagram of EVT with respect to GU's failures	3
1.2 Effect of Long Tails	8
1.3 Entropy of a GU failure rate	12
2.1 Cluster Analysis - Diagrammatic parameters selection	17
2.2 Joining Tree Method of Clustering	18
2.3 2-Way Joining Method of Clustering	19
2.4 Classification of Large MWh ('000), i.e. GWh, Losses	20
2.5 UCLF actuals 1990-2005	25
2.6 Effect of GU's increase onto the $B(n;q)$	26
2.7 Effect of UCLF improvement onto the $B(n;q)$	27
2.8 GWh Losses incurred by GU's in particular years	33
2.9 CDF of GWh Losses	34
2.10 Annual Total System GWh Losses	38
2.11 Relationship: System GWh Losses vs GU Max Loss	38
2.12 Distributional Fits of System GWh Losses	39
2.13 LogLogistic Fit to System GWh Losses	39
2.14 Relationship: System GWh Losses UCLF and Load Factor	40
3.1 Yearly Maximum GU GWh	45
3.2 Yearly Max Distribution: Gumbel	46
3.3 Return period of GWh Losses – Yearly Maxima	48
3.4 Weibull Q-Q Plot of the GWh Losses	53

3.5 Gumbel Q-Q Plot of the GWh Losses	53
3.6 Exponential Q-Q Plot of the GWh Losses	53
3.7 Generalised Pareto Q-Q Plot of the GWh Losses	54
3.8 GPD Q-Q Plot of the 11 th Largest Observations	55
3.9 GPD Q-Q Plot of the 11 th Largest Observations (Adjusted)	56
3.10 MEF vs GWh Losses	57
3.11 MEF vs k	57
3.12 Hill Estimator vs k	59
3.13 GU-GWh Losses Tail Model	62
3.14 GU-GWh Losses GPD Fit	63
3.15 GU-GWh Losses GPD Fit (zoomed)	65
3.16 a) EVI, γ at various threshold levels	72
3.16 b) EVI, σ at various threshold levels	72
3.17 EVI, σ at various threshold levels – 3LM (Known Threshold)	73
3.18 Upper Percentiles; re-parameterisation $N_t = 13$	74
3.19 Upper Percentiles; re-parameterisation $N_t = 11$	75
3.20 GWh Losses Quantiles	76
4.1 Log of variance vs Threshold: min @ 484 GWh Loss	89
4.2 Graph and Coding for the GPD – Min Variance β	94
4.3 Graphs and Coding for the GPD – Posterior	97
4.4 Q-Q Plot GPD $\hat{\gamma} = 0.5102$ $\hat{\sigma} = 272.75$ and $t = 550$	102
4.5 Minimum Variance found at $t = 878$	103
4.6 Graphic Result & Matlab Algorithm of NDE	106

Appendix A	
A1.1 Fréchet pdf (GEV with $\gamma = 1$)	117
A1.2 pdf of Weibull (GEV with $\gamma = -1$)	117
A1.3 pdf of Gumbel (GEV with $\gamma = 0$)	117
A1.4 Observations vs Exceedances (BM)	126
A1.5 Observations vs Exceedances (POT)	127
A1.6 CDF of X and Conditional Dist. Function on t	128

List of Tables

2.1 MWh Losses actuals 1990 to 2005	
– Sub-samples	15
2.2 Stations, Coding, GU's & Installed Capacity	16
2.3 Re-ordered MWh Losses from 2-way Method of Clustering	22
2.4 Categorised Large MWh Losses 1990-2005	23
2.5 Probability of more than 2 GU's failing	27
2.6 Table of Expectations in Categories	29
2.7 Table of Expectations (top) and Contingency Tables	30
2.8 Contingency Tables of Grouped Categories	31
2.9 Maximum GU loss and Total System loss	37
3.1 Quantiles, Block Maxima method	47
3.2 Quantiles, POTsp method	61
3.3 Mean Exceedance Rate	68
3.4 3-LM Parameter Estimates – Full Dataset	69
3.5 3-LM Parameter Estimates – Various Thresholds	70
3.6 Percentiles for GWh Losses – Final adopted Model	77

Appendix A	
A1.1 Mean Excess Functions based on threshold t	132
BIBLIOGRAPHY	194

LIST OF ABBREVIATIONS

EdF: Electricité de France, the largest electricity utility in France.

Eskom or **EHL**: Eskom Holdings (Ltd), the largest electricity utility in the African continent. It supplies approximately 95% of the electric energy needs in South Africa.

Extreme Value Theory (EVT): Theory that predicts the occurrence of rare events, outside the range of available data.

GenCo: Generating Company. Generally comprises of at least one power Station, and at most having no more than 33% of the total national Installed Capacity.

Generating Unit (GU): here a generating unit is defined as the industrial unit spanning from the fuel provision to the electricity generator. A set of GU's make up a Power Plant or Power Station.

Installed Capacity (IC): Nominal Capacity of a GU or total number of Megawatt installed in a Power Plant or System of Power Plants.

MW: Megawatts, one million Watts, the Watt being the unit of power.

MWh: Megawatt-hours, one million Watt-hours, the Watt-hour being the unit of energy [Gigawatt-hours

(GWh) = one billion Watt-hours; Terawatt-hours
(TWh) = one trillion Watt-hours]

V@R: The Value at Risk is a single estimate of the amount by which an institution's position in a risk category could decline due to general market movements during a given holding period. Developed by JP Morgan and referenced in RiskMetrics (registered trademark of JP Morgan). Other indicators in the Energy Markets are:

E@R: Earnings at Risk

CF@R: Cash Flow at Risk

P@R: Profit at Risk, and coined in this thesis,

Vol@R: Volume at Risk, pronounced "volar"

ROI: Return on investment.

Union of the Electricity Industry/Eurelectric (UEI/Eurelectric): International body based in Europe and HQ in Brussels (Belgium). After the creation of the European Union, it was formed by the amalgamation of UNIPEDE and EURELECTRIC.

UEI/Eurelectric Nomenclature

EAF: Energy Availability Factor, the generating unit availability after discounting the UCF with other losses. $EAF\% = UCF\% - OCLF\%$

EUUF: Energy Utilisation Factor represents the loading (in MW) imposed on a GU relative to that GU availability (EAF).

LF: Load Factor is the loading (in MW) imposed on a GU relative to its Installed Capacity during a specified period. $LF\% = EAF\% \times EUUF\%$

OCLF: Other Capability Loss Factor, this is other energy losses incurred by a generating unit, outside the management control (e.g. flooding of the coal mines), expressed as the energy lost divided by the total potential energy ($IC \times t$, where t is time in hours for the period).

PCLF: Planned Capability Loss Factor, energy losses of a GU due to maintenance, expressed as the energy lost divided by the total potential energy ($IC \times t$, where t is time in hours for the period).

UCF: Unit Capability Factor, the capability of the generating unit after discounting planned (PCLF) and unplanned losses (UCLF). $UCF\% = 100\% - UCLF\% - PCLF\%$

UCLF: Unplanned Capability Loss Factor, this is the forced outage rate incurred by a generating unit. This is the forced outages incurred by a GU, expressed as the energy lost divided by the total potential energy ($IC \times t$, where t is time in hours for the period).

EAGLE VIEW of the APPROACH taken on this Thesis

- Observations
 - The occurrence of excessive “unexpected” energy losses incurred by GU formulates the problem.
 - The Energy Market platform and its participants forms a complex environment
 - Relationships and linkage exist between prices, fuel, volume underlyings

- Problem setting
 - Limitations: field too wide, hence focus on energy volume losses, not on other underlyings.
 - What is the meaning of “excessive”?
 - Can these losses be categorised?
 - Can a scientific method be used to determine at what level is an energy loss “excessive”?
 - What are the latest statistical techniques that may be used to determine the probabilities of these “excessive” losses?

- Hypothesis*
 - Null Hypothesis: Utilisation of Extreme Value Theory (EVT) methods resolves the questions above
 - Alternate Hypothesis 1: EVT partially answers the questions above
 - Alternate Hypothesis 2: EVT does not answer the questions above

- Theory
 - Assumptions that the EVT techniques are sound and robust unless otherwise stated (by means of research)
 - This is an applied thesis; it utilises the academic theories already developed.
 - Research various EVT techniques (includes literature surveys)
 - Assure that replication of the experiment (within the sampled population) is possible when using these techniques.

- Experimentation
 - Data collection, formatting and filtering (MWh Losses per GU p.a.)
 - Exploratory Data Analysis (EDA) to understand data behaviour
 - Testing of Hypothesis on various EVT techniques
 - Prognosis

**** These Hypotheses are not to be confused with the Hypothesis Testing techniques in Inference; they are just part of the eagle-view process taken in the planning of the thesis.***

PREFACE

There are wide arrays of new issues facing today's energy analysts since the recent changes in the energy industry. To be able to understand these issues, it is necessary to understand well the Energy Market and its dynamics, in terms of its **platform** and the involvement of its **participants**.

The energy industry platform's restructuring and growing competition (internationally as well as in the Southern African market) elements are putting pressure on thorough analyses and prediction of market share, of market price, of fuel delivery and volume, of the competing generating companies' (GenCo's) costs. This type of market liberalization spawned different market domains that are inter-related: electricity, weather, coal, water, environment and ancillary services. The future challenge of this "new world" is their transformation from public service assets into commodities that can be traded in a similar manner as those in the capital and money markets. The impetus has sadly been slowed down by the unfortunate Enron (mankind's greed for money) saga in December 2001 and has undergone its own changing phases from speculative positions to hedging ones and to physical asset-based trading approaches. Volume and/or price exposures are some of the afflicting risks for these GenCo's. Limiting these exposures and trading to optimise profitability of the generators has become one of the GenCo's major goals.

To qualify the platform further, distinction is made in this thesis between a generating company (GenCo), a transmission company (TransCo) and a distribution company (DistCo). Whereby for some, e.g. in Eskom's case, as a Holdings company, it would see the three as integrated (Divisions). The platforms referred to above are rather more from a generic perspective than one particular to Eskom. In this thesis, the platform is from a GenCo viewpoint, in terms of its production of electricity and sale to various DistCo's or through a brokerage type company (e.g. Key Sales and Customers Division in Eskom), via a TransCo and possibly hedged over the counter or through a Power Exchange. When specifically addressing the Eskom case, the Generation perspective would be modelled as an integrated Company whereby the competing mode would be internal in terms of volume and cost-of-sale.

Participants in the energy markets can be characterised as operating between two diagrammatically opposite approaches: the trading-centric approach and the asset-centric approach.

The participant at the trading-centric extreme would tend to operate as in the money and capital markets. That is, to maximise their Mark-to-Market gains within the constraint of their trading limits. The GenCo's have inherent physical positions such as production and, hence, these positions turn into equivalent trading transactions and become part of the trading portfolio. In this case, the ability to deliver good sustainable results becomes generally the primary profit driver.

The asset-centric participant would tend to operate its assets with the objective to deliver a sustainable ROI. They support in sweating the physical operation as much as possible and back the GenCo's with effective hedging positions of volume risks (and at times regulated-price, by means of "claw-backs" contracts). Long term forward contracts, physical bi-laterals and the like, usually highlight their positions. These are at times boosted by option type derivatives which then induce them to operate in a similar fashion as the trading-centric participants. The asset availability of the core physical operation becomes its primary profit driver.

GenCo's participants, in this thesis, are essentially asset-centric.

Although recently the energy markets are taking far more prudent positions in shifting from being trading-centric towards being asset-centric (thanks to Enron's top management), this might be an extremist move from one side of the scale to the other. Indeed it could turn out a very hazardous affair. In Eskom's case the price is regulated therefore as a subset of an asset-centric participant, the primary drivers would then be the supply of primary-energy (fuel: coal, water, nuclear, kerosene, wind) and the volume produced to meet the demand.

The preceding paragraphs are given to illustrate that the business of producing electricity is quite complex in the interrelationship of offers, bids, price, fuel and volume available as well as the customers' demand for electricity.

After reflecting on different interesting aspects of extremes in the platforms given above, and before

hitting back on the subject of this thesis, I trust that the scene has been set to embark on the energy markets *oceans*, an analogy given to illustrate the vastness and depth of these platforms.

Hence, within this analogy, the liberty is taken with another illustration, namely, one of a large Armada standing as a fleet of generating units (GU's) subjected to the extreme storms (events), exposed to extreme drops in wind – no wind (energy volume losses – zero prices) and struggling to make it into harbor with the cargo (i.e. being business viable).

Therefore, it is the very nature of these extremes that originated the title of the thesis:

***“On the Use of Extreme Value Theory
in Energy Markets”.***

Extreme Value Theory, or EVT, a field in itself in the Statistical Sciences, required initial research, and hence from an historical statistical perspective, it is important to take a step back before leaping “the fleet” forward.

In 1902, Prof. K Pearson, wrote a “Note on Francis Galton’s Difference Problem” in *Biometrika* Vol. 1. on the problem of the range of samples. This seems to have engaged the interest of a young scientist working for the British Cotton Industry Research Association, a Mr. L.H.C. [35] Tippett, BSc London. But it wasn’t to end there, it was merely the beginning as the “Roaring Twenties” seem to have produced more than just the “Charleston”, namely: L. v. Bortkiewicz, “Variationbreite und mittlerer Fehler” Oct 1921; E. L. Dodd “The Greatest and Least Variate under General Laws of Error” Oct 1923, J. S-Nyman “Sur les valeurs théoriques de la plus grande des erreurs” 1924, J.O. Iawif “The Further Theory of Francis

Galton's Individual Difference Problem", 1925. In 1925, Tippett published an article titled "On the Extreme Individuals and the Range of Samples Taken from a Normal Population". There he mentions that the complete solution to the problem of the extreme values had not yet been resolved by Bortkiewicz, Dodd, Nyman and Lawif. In that paper, he publishes his attempts in closing the deficiencies.

It is my belief that the seed of Extreme Value Theory (EVT) originated with Tippett's publication in 1925, although later work with RA Fisher [15] published in 1928 is the most quoted reference (Fisher-Tippett Theorem); even though WE Fuller in 1914, on "Flood Flows" [16] and AA Griffith [18], in 1920 with "The phenomena of rupture and flow in solids" started to approach the EVT subject from an empirical position (see Chapter 3's Introduction).

Tippett remains, from the author's perspective, the "seed" originator of EVT in 1925.

Leaping the "fleet" forward: this thesis addresses EVT on the energy platforms with particular reference to the electricity market. Although the application of EVT is also applicable to energy prices, and some aspects are covered due to some interrelationship, this thesis primarily concentrates on the volume exposure within the generation of electricity platform as asset-centric participants. Due to the thesis being more of an applied nature rather than theoretical, [2] and [3] Beirlant is the favorite choice as a basis referential point.

Since EVT applies to extremes in the minimum and maximum domains, this thesis concentrates on the maximum aspect of EVT (unless otherwise stated).

As mentioned above, since the thesis is essentially structured from an applied perspective, most theories from respected sources are accepted within their assumptions. Hence the thesis reflects the application of these theories within the philosophy of extracting raw data, analyzing and modelling it to churn it from sterile data into *information* and packing it to distil the information into *knowledge* for decision making purposes, thereby adding value to the process.

The work in this thesis is structured in five Chapters and three Appendices containing the following elements.

In Chapter 1, an introduction of the electricity generation environment is given. It portrays a statement of the problem in terms of the type of events occurring in the generation of electricity by, illustrating the complexity of the energy market in which these types of events occur. In it, the Extreme Value Theory methodology as a possible solution to model the behaviour is discussed.

Chapter 2 begins with the process of exploratory data analysis, the intricacy of the data is illustrated and a starting point is given by using a multivariate method (Cluster Analysis) to get an indication various category losses. Large values of losses are then “binned” in these categories to explore further the data behaviour. The number of events in terms of GUs failing is discussed since this form the assets of the Company and expectations of number of GUs failing in the various bins are given.

Also in this Chapter, the Size of Volume failure, in the (GWh Losses), is investigated and portrayed as an EVT problem from a GU and a System (aggregation of GUs) perspective.

It highlights the importance of a concomitant variable (the Load Factor imposed by the Market) as it exercises its influence on the volume losses from System perspective.

In summary, the Chapter reflects the channeling (i.e. introduces, after exploring the behaviour of the data) into the modelling proposed for various stages of the proposed solution (in Chapter 3), and the research needed for validation of the hypothesis, that is the utilisation of Extreme Value Theory (EVT) methods to resolve the questions posed (see the Eagle View, page vii).

Chapter 3 is fully devoted to the application of EVT to the GWh Losses. It contains the application of EVT as described in Appendices A and C; it explores the application of the Block Maxima and the usage of the Gumbel Distribution. It then moves onto the Peak Over Threshold methodologies with particular reference to the Generalised Pareto Distribution as a model for the GWh Losses and explores if all the questions can be answered by this method.

Chapter 4 is dedicated to the Bayesian philosophy of tackling the questions and sees how this method approached the unanswered questions. It gives a different perspective of fitting the GPD in terms of the GWh Losses. It also provides “new” methodologies in the Energy sphere to predict the large values of the losses (High Quantiles). One of these methods, the Dirichlet Entropy one, gives an

innovative scientific way of determining the level at which the GWh Losses form part of the high extremes.

The Conclusion is given in Chapter 5, wherein the value of EVT's research into the GWh energy losses and its results are summarised.

Appendix A contains some essential statistical aspects of EVT that are used in the main body of the thesis.

Appendix B provides some statistical background on prices returns in the Energy Markets and may be used for further research in this area

Appendix C holds all kinds of statistical work encountered in the research incurred for this thesis; it also considers some important work on EVT. This Appendix takes into account some additional relevant remarks and observations.

CHAPTER 1

Introduction

1.1 The Energy Market Environment

Energy markets are increasingly being liberalised throughout the world. The introduction of competition, especially in the generating sector of the electricity supply industry has caused plant management to seek performance indicators that not only reflect technical excellence and commercial performance, but also the risk management aspect of the plant. A generating unit (here a unit is defined as the industrial unit spanning from the fuel provision to the electricity generator) could significantly improve its viability by managing its availability so as to be producing electricity when needed and at the right value. In other words, a unit's availability is worth more during certain hours than in others. Hence, of primary importance, is the technical availability of the energy generating plant. The failure of a generating unit (GU) in a GenCo affects this technical availability directly. The time frame by which this GU is out of production, can be classified in terms of its risk profile. In other words, it could be: as expected (tolerable), better than expected, exceptionally better than expected, or from the other side, worse than expected, much worse than expected, considered as a *Main/Major Event*, *Semi-Catastrophic* or *Catastrophic*.

Utilities consisting of large (>400 MW) generating units (numbering from 12 –as a GenCo to 100 –as EdF, say) are

subject to events that range from major (availability loss of a unit for approx. 1 to 3 months, say) to catastrophic (> 9 months, say). The impact of these events in missing opportunities or being not competitive in this market highlights the importance of the work that needs to be done.

Exposure to any of these events will cause a substantial knock on revenue to the utilities. Hence it is also of vital importance for utilities to hedge this position vis-à-vis these events (e.g. revenue or volume hedges, associated with E@R, CF@R and Vol@R).

In the Eskom Generation context, the smallest GU is a gas-turbine type with an Installed Capacity (IC) of 57 MW, the largest fossil fuel GU at 669 MW and the largest nuclear GU at 900MW, with a total Generation IC being 36 208 MW. In 2005, there were a total of 84 GU's commercially available for generating, 64 of which are considered as the "Coal Fired" fleet.

Hence, although the probability is very small, the maximum possible energy loss for any particular hour, summated over the GU's, is 36 208 MWh, the maximum possible energy loss for a day is 868 992 MWh (or 868.992 GWh) or for a year (leap) approximately 318 TWh. What this means is that for a particular window of time, the distribution is bounded in its true sense. However, because these boundaries are highly improbable relatively to the extreme events exposed to, for all practical purposes, the probability density functions utilised are considered unbounded in this thesis. Nevertheless, these GU's raise questions about these extreme events, from a worse than expected situation to a catastrophic one.

More of this part is expanded in paragraph 1.2; however to illustrate the inter-relationship and for the sake of completeness, the aspect of revenue exposure explanation is also given below

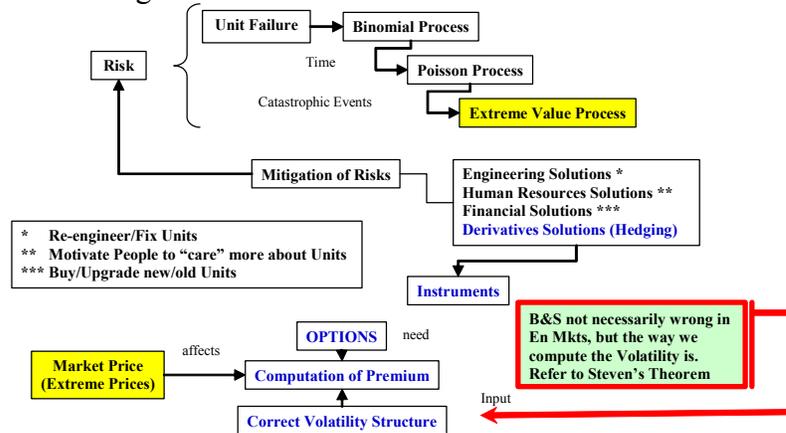


Fig 1.1: Schematic Diagram of EVT with respect to GU's failures

To exemplify how EVT maps onto the exposures of production (volume) and revenue, a diagram is produced and shown in Fig 1.1.

The top right hand side illustrates the risk of energy losses with its type of processes. The position of EVT is also indicated therein (in Yellow). It also shows possible avenues to mitigate this type of volume risk.

The bottom left hand side of Fig 1.1 shows the exposure to the financial losses due to extreme prices. In a price-response market, the customer would reject the purchase of energy, while in a captive market the GenCo's may reflect

revenue losses (due to unavailability of the GU's and missing the opportunity when the prices are high). The GenCo's may also lose their licence from a National Regulating body (such as FERC in the USA or NERSA in RSA) if found irresponsible in "spiking" the prices. The GenCo's might be also responsible for inducing high credit risks, as their customers might go bankrupt (due to electricity bills that are exorbitantly high) and hence reducing the GenCo to a loss in revenue. These can be mitigated (as shown) by means of derivatives, such as Options. However, the recurring random price shocks would induce the premiums to be very high if using the Black & Scholes (B&S) model to price the Option. This does not mean that the structure of the B&S model is necessarily wrong for the energy markets, but that the methodology to compute the volatility for returns in the energy markets needs to be fundamentally reviewed (see Appendix B – REMARKS, at the end of the 3rd paragraph).

Steven's Theorem [26] Micali, proposes that the Returns are Cauchy distributed under certain assumptions (see Appendix C paragraph 4.2). As the volatility increases to very high levels (to 40% as typical in the money markets, to 4000% in the energy markets), it makes this kind of property (Cauchy), in terms of the volatility definition, unreasonable for usage with the Black & Scholes (B&S) model to price Options in the energy markets. A similar discourse is also reflected in other works by [27] Moore, [1] Alexander, [5] Cootner and [24] Mandelbrot.

The treatment of EVT for electricity prices, merits a separate thesis in its own right; here, the mere linkage to

the volumetric losses is introduced from a statistical modelling approach (see Appendix B).

To limit the vastness of this platform, only the Coal Fired plant population is considered in this thesis. The Coal Fired stations form approximately 90% of the total Generation IC and unless specified, data is considered per GU over one-year window time periods. The data was collected in its raw form in terms of the records provided and filed in electronic format using Excel. It was filtered to a formatted spreadsheet to assess missing values or GU's not commissioned. The Excel working files names are given in Appendix C in the EDA paragraph.

As expressed above, this is where statistical modelling kicks-in and with appropriate statistical tools, scientific deduction (information) ought to be made from the data. Hence, [37] Tukey's Exploratory Data Analysis (EDA) finds its way in the beginning, even (or especially) in the Extreme Value Theory methodology used. EDA facilitates a researcher to use basic statistical techniques (such as scatter-plots, brushing, distribution fitting, contingency tables ...) in order to have a preliminary knowledge of the data behaviour. After having a clear understanding of such, using EDA, Multivariate Exploratory techniques (in this case, Cluster Analysis) would enhance the insight of how to organise the energy losses into meaningful structures. For instance, it would enable a researcher to classify the energy losses into categories that range from expected, main/major events, semi-catastrophic, and catastrophic, say. Particular care was taken in the data collection and

compilation of the statistical data files by using Data Mining methodology; this is given in Appendix C.

Further insight is given from a statistical perspective on the number of GU's failing and the size of the loss (see Fig 1.1 above top RHS). This forms an evolutionary research after having performed EDA (Cluster Analysis) to explore further the Poisson behaviour (number of GU's failing per year) and the size of large MWH Losses incurred. This work is covered in Chapter 2. This follows into the natural progression of the usage of EVT in Chapter 3 with a more classical frequentist approach. Since EVT forms the kernel of the thesis, a basic overview is already provided in that chapter, while further details are supplied in Appendix A and C. Chapter 4 is a must, with its Bayesian approach, as it reveals the answers that would be left unresolved, in the author's opinion, in Chapter 3.

Chapter 5 concludes the thesis with a summary describing if the questions posed were answered and what opportunities were uncovered.

1.2 Basics of Extreme Value Theory

EVT, albeit a new technique, has been used extensively in the Actuarial and Financial Sciences. Its particular usefulness in the Risk Management field is becoming more and more evident as time goes on. It is expected to provide management with robust risk measures in decision taking.

The EVT technique essentially concentrates at the behaviour of the tails of a distribution. Before introducing the EVT technique, it is important to understand that there are numerous ways other than EVT to resolve the problem of long (fat) tails. These are: Student's T [39] Wilson,

Mixture of Normals [22] Hull et al, Generalised Error Distribution (GED) [29] Nelson , however, in this thesis, EVT is the technique used to deal with the problem of fat tails. Fat tails are defined here as tails of a greater thickness than normal. Even so, some distributions with fat tails exhibit longer tails than others (see Fig. 1.2). The effect of these “longer” tails is important in estimating the frequencies as correctly as possible, especially in the understanding the effects of low frequency (small occurrences) but high impact events. For instance, in terms of the relative frequency difference, an excess frequency can be, say, 2000 times larger than the normally thought of frequency. Therefore, the consistent deficiency of the relative frequency (long tail), calls for different modelling and hence, EVT [32] Reiss and the risk costs could be high.

Classic EVT can be classified in at least two groups. Both these groups divide the data into consecutive windows. These groups are: the Block Method, which focuses on the maxima within these windows and the Peak Over Threshold (POT) method, which focuses on the events that exceed a certain threshold; these are then modelled separately from the events below the threshold [13] Embrechts.

The Central Limit Theorem (CLT) plays an important role in seeding the basis of EVT. The CLT tries to find constants $a_n > 0$ and b_n , such that $(S_n - b_n)/ a_n$ tends to a (non-degenerate) standard normal as $n \rightarrow \infty$. In this case, $S_n = \sum (X_i)$, $b_n = n.E(X)$ and $a_n = (n.Var(X))^{1/2}$.

In general, the Central Limit method can be applied to determine the distributions that may be obtained at the

limits. However when the parental (underlying) distribution has very long tails, the method may yield distributions with infinite variances and, hence, non-normal limits for the estimate of the expectation [2] Beirlant. These factors are important in the probabilistic aspect of EVT when considering maxima or minima (instead of the expectation mentioned in the previous phrase), whereby one would replace $M_n = \max\{X_1, X_2, \dots, X_n\}$ and replace the *Central Limit* method by the *Extremal Limit* method (see Appendix A for a more detailed rendition, Eq. A2.0).

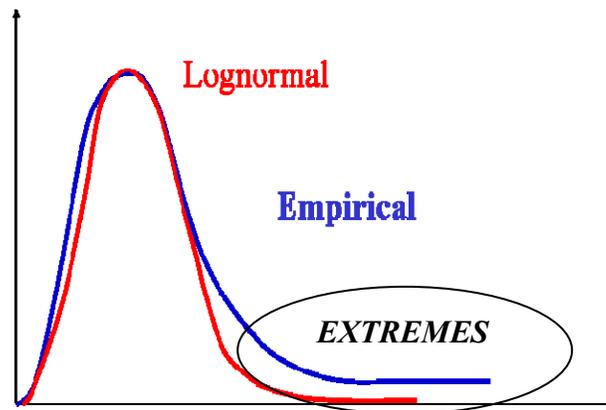


Fig 1.2: Effect of Long Tails

1.2.1 Maximum Domain of Attraction

A logical progression would now be to move onto the Maximum Domain of Attraction (MDA – see Appendix A for details, Eq A2.1) to link the parental (underlying)

distribution to EVT. This is better illustrated by means of an example.

For instance, if one has a variable X with a parental distribution that follows an exponential pdf (e.g. $X \equiv$ the mean time to fail for each year) what would be the extreme value distribution *attracted* to the pdf of X ?

An answer could be construed in the following manner:

The pdf of X is $f_X(x) = \lambda \cdot \exp(-\lambda x)$, for $\lambda > 0$ and $x \geq 0$.

Hence, its CDF (of X) is:

$F_X(x) = 1 - \exp(-\lambda x)$, as given (see Appendix A Eq. A1.0).

By taking $a_n = 1/\lambda$ and $b_n = \{Ln(n) / \lambda\}$ and substituting in A2.0 (in the Appendix), we get:

$$\begin{aligned} P((M_n - b_n) / a_n \leq x) &= P(\{\lambda M_n - Ln(n)\} \leq x) \\ &= P(M_n \leq \{x + Ln(n)\} / \lambda) = F^n(\{x + Ln(n)\} / \lambda) \\ &\rightarrow G_X(x), \text{ as } n \rightarrow \infty \text{ (see A2.0)} \end{aligned}$$

Now, $F_X(x) = 1 - \exp(-\lambda x)$

$$\therefore F^n(\{x + Ln(n)\} / \lambda) = [F_X(\{x + Ln(n)\} / \lambda)]^n$$

by substitution in the CDF above

$$= [1 - \exp(-\lambda \{x + Ln(n)\} / \lambda)]^n$$

$$= [1 - \exp(-\{x + Ln(n)\})]^n$$

$$\therefore P(M_n \leq \{x + Ln(n)\} / \lambda)$$

$$= [1 - \exp(-\{x + Ln(n)\})]^n \quad \text{Eq 1.0}$$

$$= [1 - \{\exp(-x) \cdot \exp(-Ln(n))\}]^n$$

$$= [1 - \{\exp(-x) \cdot 1/n\}]^n \quad \text{Eq 1.1}$$

But $\exp(a) = [1 + a/n]^n$ as $n \rightarrow \infty$,

hence let $a = -\exp(-x)$ and substitute in Eq 1.1, we get:

$$P(M_n \leq \{x + Ln(n)\} / \lambda) = [1 + \{a/n\}]^n = \exp(a),$$

but $a = -\exp(-x)$

$\therefore P(M_n \leq \{x + Ln(n)\} / \lambda) = G_X(x) = \exp(-\exp(-x))$
 which is of a Gumbel form (see A2.5 in Appendix)

Hence, the Exponential distribution lies in the domain of attraction of a Gumbel extreme value distribution.

The following distributions lie in the **Gumbel domain** [2] Beirlant:
 Benktander II, Weibull, Exponential, Gamma, Logistic, Normal, Log-Normal.

Following the same line of thought, for the other two families of the Generalised Extreme Value Distribution (GEV), see A2.2 in the Appendix, from [2] Beirlant, we get the following distributions in the **Weibull domain**:
 Uniform, Beta, Reversed Burr, Extreme Value Weibull.

And in the **Fréchet domain**:
 Pareto, Generalised Pareto, Burr (XII), Burr (III), Cauchy, F-distribution, Inverse Gamma, Log Gamma, Fréchet, T-distribution.

1.2.2 GEV Parametric Estimation

There are numerous methods in estimating the GEV distributions parameters; from the “Naïve” to the complex. The most important ones, especially in estimating the Extreme Value Index (EVI), are reflected below, (see Appendix A par. 2.1 and 2.3):

- ❖ Maximum Likelihood Estimation (MLE)
- ❖ Pickands Estimation (PE) method
- ❖ Hill Estimation (HE) method
- ❖ Regular Variation Approach (RVA)
- ❖ Dekkers-Einmahl-deHaan Estimation (DEHE) method
- ❖ Zipf Estimation (ZE) method
- ❖ Probability Weighted Moments (PWM) method
- ❖ L-Moments method
- ❖ Bayesian method

1.2.3 Entropy Method

The challenge in EVT is the determination of the probability density function from which the samples have been drawn. This determination is dependent on the EVT parameters which in turn depend on the threshold. However, once that aspect has been assessed, gauging the level(s) of threshold(s) becomes a new challenge. Here, one could use, say, the Mean Excess Function method or the Entropy method.

Entropy is more familiar in the world of thermodynamics, physics and chemistry, and although it has a certain mystique and cannot be directly measured, its occurrence can be inferred by changes in its variables. Maxwell, Boltzmann and Gibbs extended the work of thermodynamics in what today is termed Statistical Mechanics. In the latter, the macrostate variable is considered as an expression of a function of microstate variables, or expressed mathematically [33] Shannon:

$$\mathcal{H}(\mathbf{p}) = -\lambda \sum_i^k [p_i \cdot \text{Log}(p_i)] \quad \text{Eq 1.2}$$

Where, $\mathbf{p} = \{p_1, p_2, \dots, p_k\}$ is the probability density vector of element I (see Appendix C paragraph 2.8 for more details).

Equation 1.2 can be reduced to:

$$\mathcal{H}(\mathbf{p}) = \lambda \{\text{Log}(k)\} \quad \text{Eq 1.3}$$

As an example: Let $\lambda = 1$, in these cases,

Case 1: a GU has equal probability of failing or not

Case 2: a GU fails with a probability of 0.03 and operates with a probability of 0.97

In Case 1, $\mathcal{H}(\mathbf{p}) = 1.000$ (using Eq 1.3), and in

Case 2, $\mathcal{H}(\mathbf{p}) = 0.194$ (using Eq 1.2)

The larger the Entropy, the more unpredictable the outcome, as illustrated in Fig. 1.3

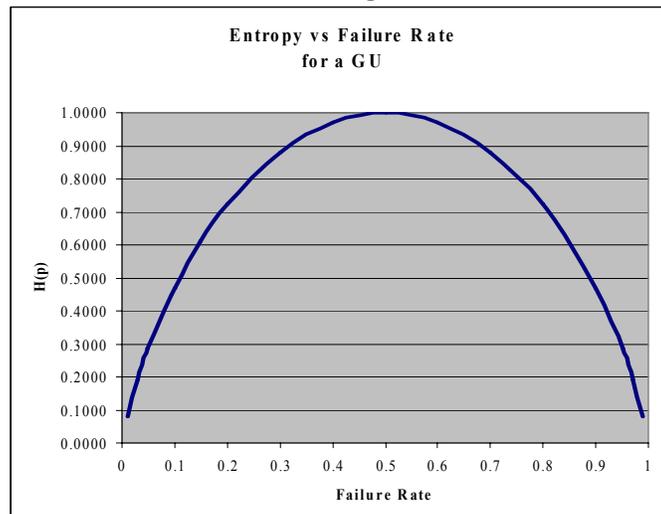


Fig 1.3: Entropy of a GU failure rate

In EVT, this type technique of using the statistical entropy with Dirichlet distributional properties is usually employed within the Peak Over Threshold (POT - see Appendix A) method. It uses different entropy values to estimate the number of points to be used in the tail of the distribution so as to assess the threshold level (the lower the entropy, the better the predictability of the threshold level). More on this methodology is reflected in Chapter 4 paragraph 4.5.

CHAPTER 2

Exploratory Data Analysis (EDA)

Multivariate exploratory techniques are included in this section. EDA is closely related to the concept of Data Mining. EDA is used to identify particular behaviours in variables when there are no prior expectations of those behaviours. When using EDA techniques, many variables are scrutinized, in the search for coherent patterns. Scatter plots techniques are included in the relevant paragraphs

2.1 Data Structure

The data was formatted according to Appendix C – EDA paragraph

The Table below (2.1), reflects a Sub-sample of the data set acquired it also shows the Power Station (PS) abbreviation code (e.g. Arnot PS: AR) and the GU's within that Station, e.g. Arnot has 6 GU's as well as Duvha PS, while Hendrina PS has 10 GU's. The 1st Row indicates the No. of hours in a year, taking into account leap years, this was used for the computation of the energy in MWh from the Capacity (in MW) loss.

The 2nd Row gives the years that the sample of the population reflected.

STAT UNIT	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005
AR_1	251788.7	768085.6	680909.3	180675	37580.8	63019.44	54785.81	99732.6	44518.32	74871.72	42611.18	27173.52	102234.3	266531.8	40292.31	347783.2
AR_2	272727.7	475825.7	311032.7	245139.8	161884.8	288501.8	119137.4	104068.8	44229.24	23704.56	126384.2	46252.8	218255.4	65910.24	246970.9	758835
AR_3	424080.4	492014.2	350455.2	117366.5	80942.4	62730.36	7536.672	39314.88	130375.1	13586.76	6087.312	6241.28	23993.64	17055.72	144356.3	346896
AR_4	91927.44	228084.1	324366.8						93661.92	18501.12	14493.6	41338.44	37869.48	122859	20291.04	89614.8
AR_5	225193.3	392809.7	82033.78									23415.48	33244.2	33533.28	155771.4	30135
AR_6	692635.7	379273	302046.6									53768.88	32087.88	51745.32	48698.5	15899.4
DU_1	679491.3	557092.2	241933.3	669921	277035	1591692	517201.9	44829.3	213568.8	529892.4	80307.72	23673.9	25688.7	33244.2	50002.92	32740.5
DU_2	370219.5	200472.6	551042.3	216591	80392	1188732	30809.88	15111	160176.6	337982.7	120714.1	20148	18636.9	4939786	7394371	86636.4
DU_3	304738.5	503700	111117.6	206517	347553	15111	133561.4	379286.1	123406.5	219109.5	74246.76	45333	19644.3	13096.2	52528.32	81599.4
DU_4	951993	356619.6	348505.2	347553	831105	191406	796006.1	23673.9	34755.3	72029.1	393962.4	114843.6	318338.8	27199.8	117683.6	36770.1
DU_5	952496.7	676469.1	866212.2	1395249	85629	166221	155059.6	140995.2	244798.2	139021.2	156069.7	10074	57421.8	32236.8	109097.3	23170.2
DU_6	223642.8	789297.9	600540.1	266961	25185	1405323	1296035	115347.3	116354.7	124413.9	56568.96	75555	4533.3	182399.4	67680.72	34251.6
HE_1	269965.7	261643.7	782408.4	88712.52	981996	120336.1	42224.69	10319.28	1497.96	64245.84	48733.63	3295.12	80556.96	89877.6	24366.82	41722.08
HE_2	306083.2	539598.5	162222.9	174262.7	163111.2	123165.6	131013.4	79391.88	12982.32	132819.1	36717.12	65078.04	110849	189741.6	103141.7	48660.48
HE_3	250325.8	191572.4	486001.2	95370.12	149796	29959.2	136520.9	113012.8	128325.2	121501.2	53406.72	33288	168270.8	76562.4	81779.04	120502.6
HE_4	196365.6	162944.8	359660.9	91542	81555.6	123165.6	38219.18	1830.84	6657.6	500651.5	46063.3	5492.52	68240.4	94704.36	91625.9	123498.5
HE_5	133152	289938.5	366386.7	317234.6	226358.4	190407.4	92961.07	101861.3	58420.44	66076.68	167396.7	65244.48	125995.1	54428.88	46583.88	19198.3
HE_6	175760.6	249660	185087.7	163111.2	213378.8	51929.28	131347.2	81555.6	10652.16	17975.52	82279.73	26963.28	7822.68	21803.64	47653.36	87381
HE_7	162944.8	553246.6	236658.5	620321.9	133152	76229.52	409229	35784.6	63413.64	29127	216964.8	18474.84	18474.84	24300.24	28372.32	123165.6
HE_8	315736.7	44005.92	153711.2	83053.56	53260.8	64245.84	101472.8	122499.8	10485.72	25631.76	6008.256	70903.44	61582.8	122999.2	43599.86	37372.92
HE_9	201099.5	155455	88454.88	74323.24	76562.4	79730.2	48733.63	30125.64	27296.16	33121.56	18525.46	17309.76	69101.24	52095.72	18358.56	44271.04
HE_10	269133.5	75230.88	229148.2		26630.4	38114.76	99303.12	58919.76	185072.5	392995.5	56226.38	70820.22	42297.66	31601.7	52976.3	41811.48
KE_1	718740.3	599324.2	638631.9	232105	347596.8	62231.04	79828.99	101475.8	69519.36	10652.16	65774.59	14016	37002.24	16482.82	69147.65	90263.04
KE_2		437299.2	555554.2	31956.48	30910.72	149130.2	87699.46	63912.86	62791.68	2242.56	44974.08	60288	22425.6	56064	13492.22	76247.04
KE_3			201259	13739.84	22425.6	91444.96	153474	151372.8	56064	7288.32	11243.52	12894.72	15137.28	134067.3	112977.4	113249.3
KE_4		469417	63912.96	28032	127265.3	145041.4	144084.5	27471.36	25228.8	28333.67	78489.6	1121.28	103157.8	82639.87	28592.64	
KE_5				46533.12	11211.8	37562.88	183269.4	103157.8	10091.52	120537.6	41601.02	3924.48	57185.28	159782.4	12930.05	173798.4
KE_6					22425.6	72322.56	56779.78	560.64	302745.6	31956.48	78450.6	21804.32	2242.56	250045.4	20238.34	24668.16
KR_1	563815.5	138561.3	132265.1	52844.7	815556	694470.9	35048.16	165191.7	15728.8	144802.8	71652.28	170601	70320.9	1090182	415571	186829.8
KR_2	760214.7	495159	640463.4	309578.4	557574	86548.8	35048.16	282531.9	28710.9	129823.2	0	80307.3	116924.1	177674.7	102165.1	155205.3
KR_3	755221.5	153957	186506.3	339953.7	618828	22053.3	78023.88	157701.9	98199.6	131071.5	180247.7	72401.4	20388.9	99031.8	155630.5	439817.7
KR_4	840105.9	915420	196937.3	119420.7	173762	64079.4	83865.24	64079.4	51596.4	86964.9	21123.4	76562.4	46603.2	815556	86368.68	148131.4
KR_5	734416.5	264223.5	388033.2	310410.6	449388	42026.1	110289	93622.5	182667.9	96951.3	58413.6	71985.3	151460.4	130655.4	969665.8	194318.7
KR_6	69518.5	79475.1	66758.4	175178.1	158118	42442.2	165227	148963.8	151460.4	74065.8	124754.8	43274.4	91125.9	116924.1	941710.7	256317.6

Table 2.1: MWh Losses actuals 1990 to 2005 -Sub-sample

The matrix contains the MWh Losses for every GU for every year. The “black” blocks, originally missing data, were investigated further. These yielded the following information. The large ones at the top & bottom, were not missing information, but legitimate behaviour of the population viz. the GU’s at Arnot PS were “mothballed” for 5 years and then gradually brought back into service. The GU’s at Kendal PS were new GU’s being commissioned gradually into the system. Hendrina GU 10 was truly a missing value for 1993 and unfortunately valid records were not available (this was the only true missing value – the others could be explained in a similar fashion as above). The data matrix of 16 yrs x 64 GU’s = 1024 data points of which 929 could be used in univariate mode (approx 91%).

STATION	STAT Code	UNIT	IC	STATION	STAT Code	UNIT	IC	STATION	STAT Code	UNIT	IC
AR	C1	Ar1	330	KE	C23	Ke1	640	MB	C47	Mb1	615
AR	C2	Ar2	330	KE	C24	Ke2	640	MB	C48	Mb2	615
AR	C3	Ar3	330	KE	C25	Ke3	640	MB	C49	Mb3	615
AR	C4	Ar4	330	KE	C26	Ke4	640	MB	C50	Mb4	615
AR	C5	Ar5	330	KE	C27	Ke5	640	MB	C51	Mb5	615
AR	C6	Ar6	330	KE	C28	Ke6	640	MB	C52	Mb6	615
DU	C7	Du1	575	KR	C29	Kr1	475	ML	C53	Ml1	575
DU	C8	Du2	575	KR	C30	Kr2	475	ML	C54	Ml2	575
DU	C9	Du3	575	KR	C31	Kr3	475	ML	C55	Ml3	575
DU	C10	Du4	575	KR	C32	Kr4	475	ML	C56	Ml4	575
DU	C11	Du5	575	KR	C33	Kr5	475	ML	C57	Ml5	575
DU	C12	Du6	575	KR	C34	Kr6	475	ML	C58	Ml6	575
HE	C13	He1	190	LE	C35	Le1	593	TU	C59	Tu1	585
HE	C14	He2	190	LE	C36	Le2	593	TU	C60	Tu2	585
HE	C15	He3	190	LE	C37	Le3	593	TU	C61	Tu3	585
HE	C16	He4	190	LE	C38	Le4	593	TU	C62	Tu4	585
HE	C17	He5	190	LE	C39	Le5	593	TU	C63	Tu5	585
HE	C18	He6	190	LE	C40	Le6	593	TU	C64	Tu6	585
HE	C19	He7	190	MJ	C41	Mj1	612				
HE	C20	He8	190	MJ	C42	Mj2	612				
HE	C21	He9	190	MJ	C43	Mj3	612				
HE	C22	He10	185	MJ	C44	Mj4	669				
				MJ	C45	Mj5	669				
				MJ	C46	Mj6	669				

Table 2.2: Stations, Coding, GU's & Installed Capacity

Table 2.2 gives the coding used for each GU with its relevant information used in multivariate techniques, e.g. Stat Code C8 corresponds to GU 2 at Duvha PS with an Installed Capacity (IC) of 575 MW.

2.2 Cluster Analysis

Cluster Analysis (CA) helps in organising the MWh Losses of the GU's into meaningful categories. This multivariate method uses distances (dissimilarities) between GU's MWh Losses when forming the Clusters. The usual statistical way used to calculate the distances is the Euclidean method or essentially the geometric distance in a multidimensional space:

$$\delta(x;y) = [\sum_i (x_i - y_i)^2]^{0.5}$$

The Chebychev distance was the one chosen as one would want to detect the GU's MWh Losses if they were

different on anyone of the years in question, in this case the distance is modelled as: $\delta(x;y) = \text{Max } |x_i - y_i|$

Once these distances have been computed a linkage rule is required to link the Clusters which are sufficiently similar. The most common one is called Single Linkage or Nearest Neighbour; in this case, the distance between the Clusters is determined by the distance of the closest GU's MWh Losses (Nearest Neighbours) in the different Clusters.

The rule of Complete Linkage (Furthest Neighbour) was used here whereby the distance between the Clusters is determined by the greatest distance between any two MWh Losses in the different Clusters. This technique is particularly useful if the MWh Losses would tend to bunch-up.

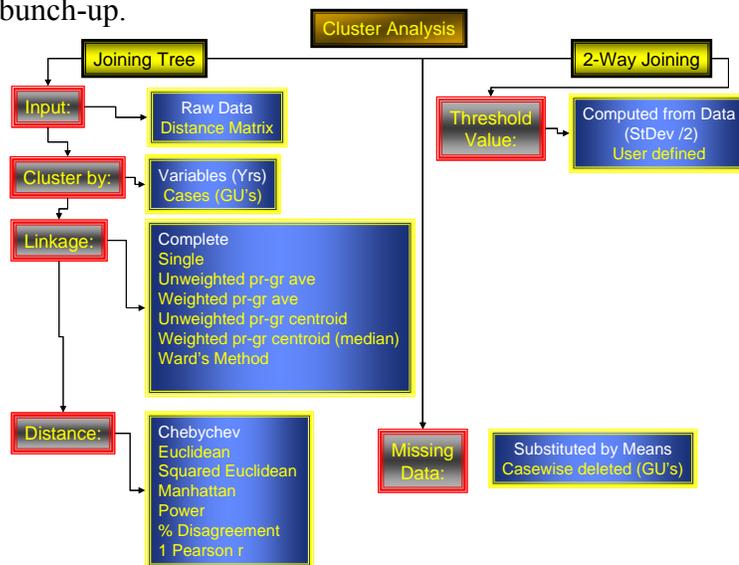


Fig 2.1: Cluster Analysis-Diagrammatic parameters selection

Case wise (Row) deletion could have been used to handle Missing Data. However, the substitution by Means methods was deployed in order not to reduce the data matrix size. Both methods were tested and no difference was detected at the nodes; there was a marginal change in the cluster selection at the lower end (“the better years”).

First Step was to use the Joining Tree method and Fig 2.1 above illustrates the parameters selected (in White over the Blue background) for the analysis. The software used was STATISTICA. The outputs are shown in Figs 2.2 and 2.3 below as well as Table 2.3.

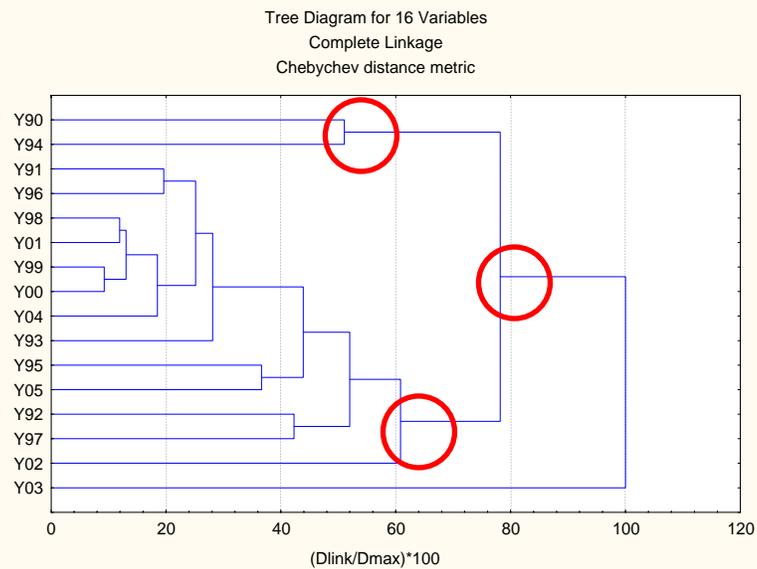


Fig 2.2: Joining Tree Method of Clustering

In the hierarchical tree of Fig 2.2 above three nodes (in red) can be identified. This tends to imply that Y03 (Year 2003) stands on its own i.t.o. the GU's MWh Losses. The next links are Y02 (2002) and both Y90 (1990) and Y94 (1994). This kind of categorisation invoked interest and a more detailed method of 2-Way Joining in Cluster Analysis was used (see Fig 2.1 above). In this analysis the same pattern was observed but more information was now available (see Fig 2.3 and Table 2.3 below)



Fig 2.3: 2-Way Joining Method of Clustering (Legend in MWh)

From the re-ordered table (Table 2.3 below) and Fig 2.3 (highlights in red circles) above, it can be deduced that large MWh Losses incurred in those particular years (values highlighted in the Table); this was not evident from

Fig 2.2 that the nodal clustering was due to these very large values.

This was an enabling finding as it was now providing a basis for categorising these extreme events. After inspecting the data, there seemed to be a natural 900 000 MWh (or 900 GWh) spread amongst the categories.

The reasons for the high losses in 2003 were due to a catastrophic event due to fire at one 575 MW GU.

The GWh Losses were then classified into six categories ranging from Sub-critical to Catastrophic and these are illustrated in Fig 2.4 below.

It must be noted, from the legend in Fig 2.3, the following GWh categorical values:

449; 899; 1348; 1797; 2246; 2695; 3144; 3593; 4042; 4491

The values highlighted in red will bear significance later in Chapter 3 in the analysis of Extremes.

CATEGORIES in MWh '000	Catastrophic	>4500
	Semi-Catastrophic	3600<x<4500
	Major Events	2700<x<3600
	Main Events	1800<x<2700
	Critical Events	900<x<1800
	Sub-Critical Events	400<x<900

Fig 2.4: Classification of Large MWh ('000), i.e. GWh, Losses

The results of the data classification are given in Table 2.4 below.

However caution needs to be exerted in the interpretation of the losses within the classification. For instance a GU out for a whole year at Hendrina Power Station would be classified differently from a GU out for the same period at Majuba Power Station as shown below.

	HE	MJ
Normal Year	1,620,600	5,860,440
Leap Year	1,625,040	5,876,496

This means that for a catastrophic event to occur at Hendrina (equivalent to 1 GU out at Majuba), 3 GU's would be out for a year and 1 GU for half a year. This is according to the statistical Classification; however from a managerial perspective, 1 GU out at Hendrina, although it would classify as Critical, it might actually be just as "Catastrophic", since Hendrina is one of the "cheap" and base-loaded Power Stations.

This may be rectified after the management/executive would decide on the severity of the impact of the loss and then assign weights to different GU's or/and Power Stations. Using the example above, if the management, say, felt that 1 GU at Hendrina lost for 1 year is equivalent to 1 GU loss at Majuba also for 1 year, whatever reason given, then the "Loss Score" would be Loss @ Hendrina x 3.5. These can then be classified in the table illustrated in Fig 2.4.

These weights (e.g. 3.5) can also be normalised for all the GU's so that the Loss Score for the System be determined.

	Le3			Le2			Du2			Mb2					
	Y90	Y93	Y96	Y91	Y94	Y96	Y95	Y98	Y04	Y97	Y03	Y95	Y90	Y00	Y02
C_1	251789	680909	180675	768986	37590	54786	347508	44118	40292	89753	266532	63819	74872	42611	27174
C_12	223643	600540	268061	789798	21185	1296035	14252	116255	67481	115347	182389	1405323	124414	56569	75555
C_39	161035	375042	25973	72726	93504	76571	1560482	166749	14064	161555	473233	98699	105971	38025	25973
C_48	600665	1027491	548515	59800	37712	1139886	35018	589382	71849	295748	1592516	172397	111519	95078	85121
C_10	951993	348505	347553	356620	831005	796006	36770	34755	117684	23674	27200	191406	72029	393962	114844
C_36	420086	411640	206517	79781	87401	144453	30222	651788	66165	76562	73540	520826	99229	9091	131969
C_27	710217	334868	171258	350900	312294	123240	350427	629114	118189	787283	82067	175273	100740	87379	40800
C_9	302739	111118	206517	503700	347553	135361	81599	234007	32528	379286	13096	15111	219110	74247	45331
C_22	249133	229148	268169	75231	26630	99303	41811	185073	52976	59920	31602	38115	392996	56226	70820
C_14	306683	162223	174263	539599	163111	131013	48600	12982	103142	79392	189742	123166	132819	46717	65078
C_20	315737	153711	83054	44606	53261	101473	73733	10486	43560	122500	122999	64246	25632	6008	70003
C_11	952487	866212	1895248	676469	85629	155060	23170	244798	109097	148095	32237	166231	139021	158070	10074
C_49	538740	2277011	1082867	634697	1093642	82653	20472	103438	103181	194485	108287	209031	174552	49700	36634
C_37	3724866	645965	467521	374654	1210161	107220	31888	126619	32295	83641	287266	249345	212462	38881	87271
C_50	252372	217707	48487	237584	85322	39456	19399	143305	61585	101822	278259	183172	24479	10446	45582
C_52	576091	675810	53874	414435	373534	69688	17778	89431	62665	663650	481095	148770	47848	72929	41183
C_2	277228	311033	245140	475826	161885	119137	758835	44229	246971	104069	65910	288502	23705	136384	46253
C_51	576091	398679	506416	572681	177784	82113	83505	82427	466747	94818	67841	28014	44177	23689	54413
C_40	576091	697994	192203	706477	664919	41150	43194	122075	303680	163115	594271	993223	719	80738	40519
C_5	225193	82034	268169	492860	373534	148121	36135	124795	155871	169872	37531	252572	115632	32774	31244
C_43	576091	481091	268169	414435	373534	148121	44497	124795	162887	169872	126522	252572	174773	188153	375815
C_41	576091	481091	268169	414435	373534	148121	321217	7506	101065	64333	36456	252572	6969	21503	516
C_42	576091	481091	268169	414435	373534	148121	33775	10722	120418	169872	42889	252572	2681	10373	13939
C_44	576091	481091	268169	414435	373534	148121	205115	124795	42311	169872	15237	252572	107011	14691	50966
C_45	576091	481091	268169	414435	373534	148121	60563	124795	32908	169872	24028	252572	107011	81998	2930
C_46	576091	481091	268169	414435	373534	148121	11721	124795	25269	169872	13479	252572	107011	81998	69515
C_24	576091	556554	31956	437299	26911	87699	76547	62792	13492	65913	56064	149130	2245	44974	60268
C_38	155077	487402	800883	390368	374749	171222	17126	89155	45457	128444	42311	199925	74548	48488	61451
C_28	576091	481091	268169	414435	373534	148121	24668	302746	20238	561	250043	73233	31956	73645	21304
C_25	576091	201259	17380	414435	22426	153474	113249	56064	112997	151373	1360673	91945	7288	11244	12895
C_26	576091	469417	63913	414435	28032	145041	28593	27471	82640	144084	103158	127265	25229	283337	78480
C_27	576091	481091	268169	414435	373534	148121	182369	173798	10092	12940	103158	159782	37563	120538	41601
C_3	424080	356454	117366	492914	80942	7537	348896	130375	144556	39315	17056	62730	13587	6087	62441
C_38	130867	156267	166230	472716	86609	1563	1823072	23274	931	34285	63375	79479	131425	39588	54544
C_13	269966	782408	88713	261644	80200	42225	81722	1498	24567	10319	89878	120336	64246	48724	32953
C_21	201060	88455	74232	155455	76562	48734	44273	27296	18359	30126	52096	75730	33122	18523	13105
C_16	108366	359861	91342	162943	81536	38219	123498	6638	91626	1831	94704	123168	200652	40663	3493
C_8	370220	551042	216591	200473	80592	20810	86636	160177	759437	15111	4939786	1188732	237983	120714	20148
C_7	879491	241935	869921	573992	277033	317002	35741	215469	50003	44829	34344	1391892	259892	80308	23874
C_25	1038926	1969804	909699	1106467	254529	212234	283110	50188	3123	77401	42296	45713	129773	40109	24924
C_36	1449316	1552256	168827	394796	3884453	146891	1133479	200515	367749	73764	18181	2183844	22317	67195	22317
C_34	659519	66758	175178	79475	158118	165227	256318	151460	941711	148964	116924	42442	74066	124755	43274
C_63	47859	154159	139002	25623	153738	25693	79944	177811	482518	65595	109666	19473	98392	28263	17421
C_64	576091	158784	133240	16399	97367	103287	12299	33310	172658	137325	76357	68670	74307	44706	427904
C_15	250326	488001	95370	191572	149796	186521	120501	128425	81779	113013	76562	29959	21501	53407	31288
C_33	789802	348990	43333	307174	821105	105842	74548	99229	112128	43827	83111	663373	17273	30305	4030
C_62	330537	409036	51246	126405	450965	20555	74819	113254	154159	72282	88143	43559	234184	24665	76357
C_31	755222	188508	339934	133957	815828	78024	439818	98200	153691	137702	99032	22053	131072	180248	72401
C_60	757416	1862243	179561	142976	169112	155187	431491	95310	139771	24847	50221	124528	52271	9250	41509
C_18	175761	183088	163111	249680	211379	131347	87881	10652	47585	83536	21804	51929	17976	82280	28963
C_61	721021	59094	148612	220258	118264	141826	94293	31773	46762	12299	107104	32822	16599	43678	46634
C_19	162945	236659	826323	553247	131852	499239	123166	63414	28372	35785	24480	76260	29127	216965	18475
C_55	276531	191425	50370	635166	122925	109097	353094	10074	31315	164710	6548	27704	41955	156411	24252
C_32	840106	166917	119423	915420	117462	83865	148132	51596	88469	64079	815556	64079	86965	211123	76562
C_4	91927	324367	268169	220804	373534	148121	89615	95662	20291	169872	122859	252572	18301	14494	41338
C_6	662366	802047	268169	379273	373534	148121	15899	124795	48698	169872	51745	252572	107011	81998	53769
C_17	133132	366337	317235	289938	226358	92961	191905	58420	46564	101861	54426	190407	66077	167397	65241
C_23	718741	638632	232105	299324	347297	79829	90263	69219	69148	104476	164828	62231	10652	63725	14016
C_30	802123	640483	309778	495159	575774	35048	152203	28711	120483	282522	17873	86549	129923	0	83097
C_29	563816	132265	52845	128561	815556	25048	168629	157286	415571	165192	1090182	494471	144803	71765	170601
C_34	938823	220720	281109	40943	2231391	43487	128444	130962	548317	143051	383331	143051	131110	80813	138318
C_33	724417	388033	210411	264224	449388	210289	194219	182668	969666	93623	120655	42026	96951	59414	71985
C_59	467364	357135	160912	357697	261355	139771	462239	144001	326304	126065	250080	47146	111204	143882	109666
C_47	1297286	636915	614184	276374	199334	234994	143305	411597	328451	2607502	196640	81350	49025	56723	47948

Table 2.3: Re-ordered MWh Losses from 2-Way Method of Clustering

		UNIT Years	1990	1991	1992	1993	1994
CATEGORIES in MWh '000	930		49	53	56	53	55
	Catastrophic	>4500					
	Semi-Catastrophic	3600<x<4500	3,724,586				3,854,453
	Major Events	2700<x<3600					
	Main Events	1800<x<2700			2,277,010		2,231,391
	Critical Events	900<x<1800	1,449,316		1,552,256	1,395,249	
	Sub-Critical Events	400<x<900		768,086	782,408	620,322	
				539,598	486,001		
			553,247				

1990 - 1994

		UNIT Years	1995	1996	1997	1998	1999
CATEGORIES in MWh '000	930		55	55	56	58	60
	Catastrophic	>4500					
	Semi-Catastrophic	3600<x<4500					
	Major Events	2700<x<3600					
	Main Events	1800<x<2700	2,183,843		2,607,502		
	Critical Events	900<x<1800	1,591,692	1,296,035			
	Sub-Critical Events	400<x<900	1,405,323				500,652

1995 - 1999

		UNIT Years	2000	2001	2002	2003	2004	2005
CATEGORIES in MWh '000	930		61	63	64	64	64	64
	Catastrophic	>4500				4,939,786		
	Semi-Catastrophic	3600<x<4500						
	Major Events	2700<x<3600			3,030,951			
	Main Events	1800<x<2700						1,883,072
	Critical Events	900<x<1800				1,592,515	969,666	1,560,482
	Sub-Critical Events	400<x<900				1,090,182	941,711	1,133,479
							739,437	758,835
						548,517	462,239	
						482,518	439,818	
						466,747	431,491	
						415,571		

2000 - 2005

Table 2.4: Categorized Large MWh Losses 1990 - 2005

2.3 The Number of GU's failure and Loss Size Exposures

In the Introduction, the statement of the problem was presented and the GU's losses (or Volume losses) were highlighted as the prominent issue. From this part of the Chapter onward, the topic of these exposures is analysed statistically for the Generation Division of EHL, in two parts: the number of GU's failing and the size of the failure. The data used for the risk exposure spanned for every GU from 1990 to 2005. Prior to 1990, the forced outages (UCLF) for the Generation System averaged approx. 11%, oscillating between 8% and 14%. However, one ought to consider that in 1994 a management strategy (called the "90:7:3") was put into effect to purposefully reduce the forced outages (UCLF) to a value of 3%, with realisation as soon as possible, but definitive before the turn of the millennium (i.e. by 1999). This target was considered accomplished in 1996 (see Fig. 2.5 below).

Therefore, given that this strategy is into effect, and observing its behaviour, the data from 1996 may be considered as stationary for other type of analyses (such as in Performance Management). This is particularly important for the analysis in paragraph 2.2.1, while for paragraph 2.2.2 the whole data set is used.

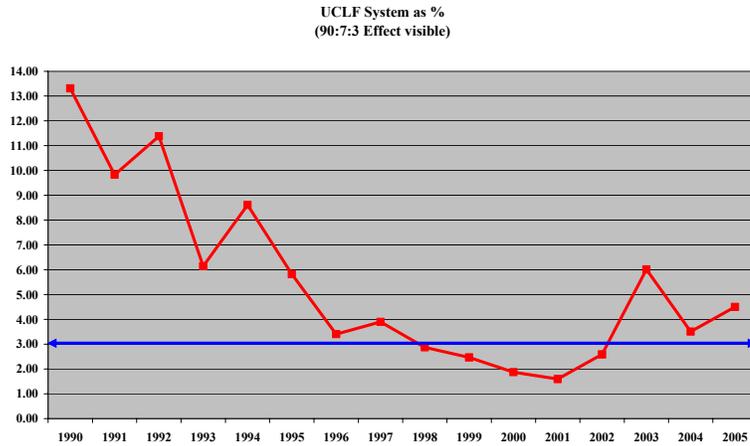


Fig 2.5: UCLF actuals 1990 to 2005

2.3.1 Number of Generating Units failing

Following up from Fig. 1.1 the GU failure (X) can be characterised from a Binomial distribution. Assume n identical GU of equal installed capacity (this kind of assumption can be valid for a Power Station: say a six-pack like Duvha PS, however Majuba has different IC's for its GU's – see Table 2.2, hence caution); each of these units has an expected forced outage rate (UCLF) q , then by characterising these GU with a Binomial distribution $B(n; q)$, one would get the probability, $P(X_i)$, of i GU's failing being:

$$P(X_i) = C_i^n q^i (1-q)^{n-i}, \quad \text{Eq 2.1}$$

where C represents the Combination function of i elements into n within the $B(n; q)$ – see paragraph 2.2 (and equation C2.2 in Appendix C).

As seen in the equation above, a clear understanding of the forced outages on the system is necessary.

Another effect comes into play as well: due to the customers demand (or/and economic growth) the augmentation of installed capacity necessitated the number of GU's to increase (see Table 2.4 the Unit Years row, the No. of GU's per year increases from 1990 to 2005). This has an interesting effect on the modelling of the GU failures as a $B(n;q)$

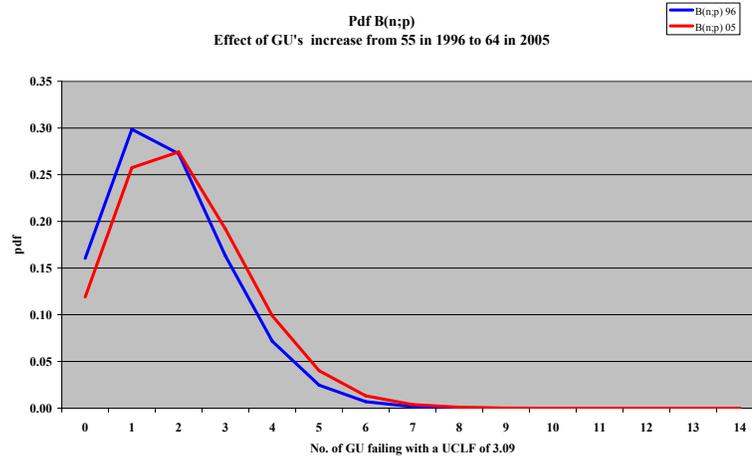


Fig 2.6: Effect of GU's increase onto the $B(n;q)$

Fig 2.6 indicates the effect of the increase of 9 GU's on the system (under the assumption of equal GU's – here we could be more accurate and convolute the Binomial for each installed capacity category and weight it accordingly to arrive at the Total System value). One can see that for 2 GU's the probability of failure is about the same but, for less than 2 GU's, the probability of failure is less for 64 GU's on the System than 55 GU's. However, the

probability of failure of 3 units or more has increased from 1996 with the installation of more capacity.

Therefore to maintain the same characteristics for the system (with respect to the probabilities of failure), the system would have to improve the forced outage rate (UCLF). This is shown in Fig 2.7 below where an improvement of 0.49% in UCLF, rebalanced the probabilities to the 55 GU basis (shift from the “red” pdf to the “orange” pdf).

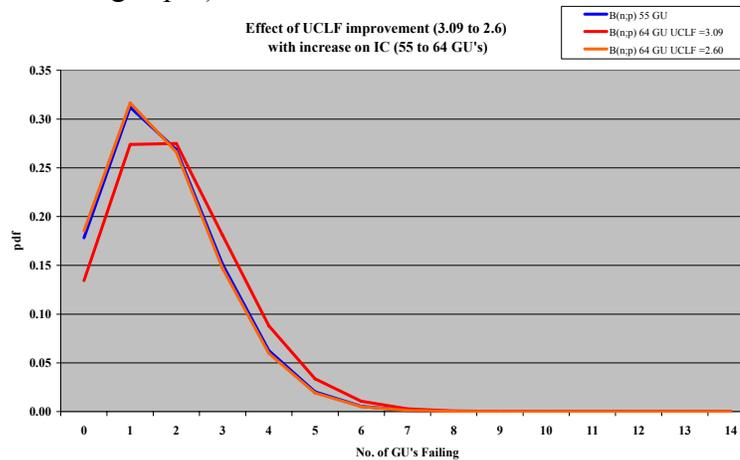


Fig 2.7: Effect of UCLF improvement onto the $B(n;q)$

UCLF	3.09%	3.09%	2.60%
GU's	55	64	64
$P(x>2)$	0.24	0.32	0.24

Table 2.5: Probability of more than 2 GU's failing

As shown in Table 2.5, the system would be expected to operate at an improved UCLF (say 2.6%), given the increased capacity (to 64 GU's), so as not to worsen the probability of failure of more than 2 GU's (0.24).

However GU's tend to obey the laws of Reliability Theory, and as such when new they have high failure rates (also called "infant mortality" period or early period) then the GU tend to follow a period of stationarity (also called occasional period) and after that the failure rate tends to increase as the plant is getting old (called the degenerative period). This behaviour is often referred to as the "bath-tub" curve of the hazard rate.

Hence, bringing in new GU's not only increases the probability of GU's failing but it also increases the failure rate (due to the teething problems of the bath-tub), compounding the effect as it would be difficult to bring down the UCLF with new GU's coming in.

By the end of 1995, most of major GU's were now operational, hence one might ask whether the drop in UCLF was due to the 90:7:3 initiative, was it due to usual Reliability Theory behaviour, a bit of both and maybe some luck? From a personal perspective, it was both, and, having been involved in the 90:7:3 initiatives, the 90:7:3 with considerably more weight than the Reliability Theory one.

The Binomial process above can now be expanded further. Let us illustrate this expansion by the compilation of Table 2.6 below. The 930 value reflects the total number of Unit Years (i.e. the sum of however many GU's were in the fleet every year) over the 16 years period.

CATEGORIES in MWh '000	UNIT Years	930	No. of GU Cumulative	Rate in Category	E[x]
	Catastrophic	>4500	1	0.0010753	0.0688172
	Semi-Catastrophic	3600<=s<=4500	3	0.0032258	0.3064516
	Major Events	2700<=s<=3600	4	0.0043011	0.2752688
	Main Events	s<2700	11	0.0118280	0.7569892
	Critical Events	900<=s<=1800	23	0.0247312	1.5827957
	Sub-Critical Events	400<=s<=900	39	0.0419355	2.6838710

Unitary rate (i.e. for any population N in a particular year). This means that for a year with a Tot fleet of 64 units, we would multiply this rate by 64 to get the E[x]

Expected No. of GU's failing in these Categories (or higher Categories) in any year.

Table 2.6: Table of Expectations in Categories

The next column gives No. of GU's for each Category accumulated from the previous one (e.g. in Semi-Catastrophic there are 2 Events + 1 Event in the Catastrophic Category; in the Major Events there is 1 Event + the previous 3 accumulated ones, etc...). The "Rate" can be interpreted as the "q" in Eq 2.1.

Since the Poisson model $[Psn(\lambda)]$ (see Appendix C paragraph 2.3) is derived as the limit of the Binomial as $n \rightarrow \infty$ and $q \rightarrow 0$ and $nq = \lambda$ being constant, the $E[x] = n \cdot q$ (see comments on the Rate in Table 2.6 above), this may be used to compute the expectations in each category (refer to Appendix C paragraph 2.3 for the calculations in the table).

The expectation in the last column of Table 2.6 above can be interpreted as follows: on average, one would expect, in a year, to have 2.7 GU's failing in the Sub-Critical category, 1.6 in the Critical, 0.8 GU in the Main Events category, and skipping the other categories but going straight to the Catastrophic, one would expect such an event once every 14.5 years ($= 1 / 0.0688$).

Furthermore, the Poisson Distribution may now be used to compute the probabilities in each of the categories given in the top table of Table 2.7

GU's in Category failing	0	1	2	3	4	5	6
Catastrophic	0.933497304	0.0642407	0.002210432	5.07052E-05	8.72348E-07	1.20065E-08	1.37709E-10
Semi-Catastrophic	0.813465622	0.1679413	0.017335875	0.001193006	6.15745E-05	2.54243E-06	8.74815E-08
Major Events	0.759367965	0.2090303	0.028769765	0.002639806	0.000181664	1.00013E-05	4.58841E-07
Main Events	0.469076577	0.3550859	0.134398113	0.033912642	0.006417876	0.000971653	0.000122588
Critical Events	0.205400	0.3251063	0.257288449	0.135745017	0.053714157	0.017003707	0.004485566
Sub-Critical Events	0.068298261	0.1833037	0.245981768	0.220061108	0.147653905	0.079256806	0.035452507

Expected Events in Categories	0	1	2	3	4	5	6
Catastrophic	15	1	0	0	0	0	0
Semi-Catastrophic	13	3	0	0	0	0	0
Major Events	12	3	0	0	0	0	0
Main Events	8	6	2	1	0	0	0
Critical Events	3	5	4	2	1	0	0
Sub-Critical Events	1	3	4	4	2	1	1

Observed Events in Categories	0	1	2	3	4	5	6
Catastrophic	15	1	0	0	0	0	0
Semi-Catastrophic	14	2	0	0	0	0	0
Major Events	15	1	0	0	0	0	0
Main Events	11	4	0	1	0	0	0
Critical Events	8	4	4	0	0	0	0
Sub-Critical Events	10	2	1	1	1	1	0

Table 2.7: Table of Expectations (top) and Contingency Tables

These may be used further to compute the expected frequencies in each class. This is done as follows. For example, in the 16 years, we have **observed** 15 years with 0 catastrophic events and 1 year with a catastrophic one. We would have **expected** $0.933497 \cdot 16 \approx 15$ and $0.0642 \cdot 16 \approx 1$ events according to the Poisson model. The other frequencies for the rest of the classes in the middle and bottom tables of Table 2.7 are computed in a similar fashion.

Validation of the Poisson model for the Categories:

More Contingency tables are compiled for the various categories and the χ^2 test used to validate the Poisson model.

GROUPED		
Semi-catastrophic	0	1
EXPECTED	13	3
OBSERVED	14	2
χ^2 :	0.250	
df= 1		
Prob signif.	χ^2 :	0.6170

GROUPED		
Major Events	0	1
EXPECTED	12	3
OBSERVED	15	1
χ^2 :	2.312	
df= 1		
Prob signif.	χ^2 :	0.1284

GROUPED				
Main Events	0	1	2	3
EXPECTED	8	6	2	1
OBSERVED	11	4	0	1
χ^2 :	4.661			
df= 3				
Prob signif.	χ^2 :			0.1984

GROUPED					
Critical Events	0	1	2	3	4
EXPECTED	3	5	4	2	1
OBSERVED	8	4	4	0	0
χ^2 :	10.073				
df= 4					
Prob signif.	χ^2 :				0.0392

GROUPED					
Sub-Critical Events	0	1	2	3	4
EXPECTED	1	3	4	4	2
OBSERVED	10	2	1	1	1
χ^2 :	77.680				
df= 4					
Prob signif.	χ^2 :				0.0000

Table 2.8: Contingency Tables of Grouped Categories

As the results were a bit sparse, Grouping from Sub-Critical Events to Semi-Catastrophic was performed. The “bins” were reduced [e.g. from 7 to 5 (i.e. spanned from 0 to 4 Events)]. Catastrophic had almost a perfect fit, so the table was excluded as redundant.

From Table 2.8, it is significant to note the following:

- The top table can be considered as a 2 x 2 Contingency table
- That the χ^2 test indicated that the model fitted well in the categories from Main Events to Catastrophic
- It did not fit well for the other 2 categories, probably due to the interval limits for the two categories Critical and Sub-Critical events.

2.3.2 Size of Volume failure

In terms of the energy loss (power x time) in MWh, in theory it would be quite possible to determine that the total maximum loss is 318 TWh in a year (given that it is a leap year); however this kind of loss would be cataclysmic for South Africa which would be similar to the probability of a global nuclear warfare and the annihilation of a country. For all practical purposes, the asymptotic properties of the distributions are assumed in this thesis. From the other end, there were 2 very small losses (0.1 MWh) that were excluded from the analyses in Chapter 3, reducing the total GU-Years from 930 to 928.

Plotting the size of the losses that every GU incurred in any year is shown in Fig 2.8 below, indicating that over a period from 1990 to 2005 the max size of the loss was 4939.79 GWh, 1.6% of the total maximum potential loss. However, this kind of loss is considered catastrophic as it represents one large GU out of action for one whole year, resulting in losses of revenue approximating R 550 million (in 2003 Rands). If one adds up the repair to damage that would put a GU out for such a time, the costs would be over a billion Rand.

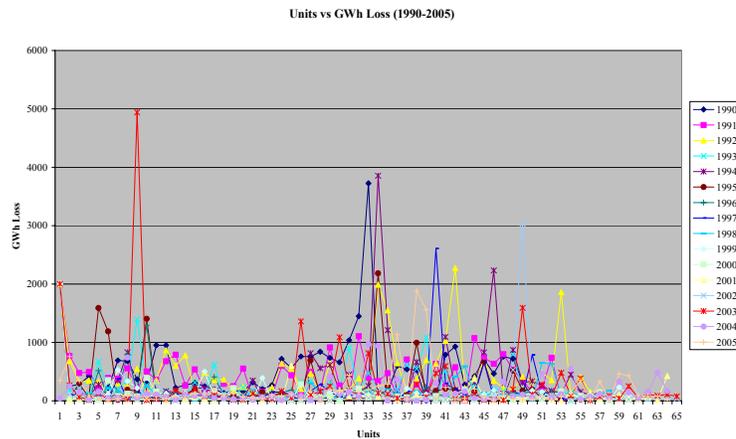


Fig 2.8: GWh Losses incurred by GU's in particular years

Let us assume that the MWh losses can be expressed as an essentially positive random variable (energy losses $\equiv X$) expressed by a particular distribution function having a pdf $f_X(x)$ and a CDF $F_X(x)$. Here it is also assumed that F is continuously differentiable and that the following applies:

$$F_X(x) = \int_0^x f_X(x).dx$$

(see A1.0 and related issues in Appendix A)

Since empirical quantiles open the way to tail estimation, let $\hat{F}_X(x)$, the empirical CDF be derived by ordering X_i 's in such form: $X_1^* \leq X_2^* \leq \dots \leq X_n^*$ and associating each X_i^* with its percentile $p = i/(n+1)$, $i = 1, 2, \dots, n$.

This $\hat{F}_X(x)$ is depicted below, in Fig 2.9. Here, the very long tail of the distribution is evident.

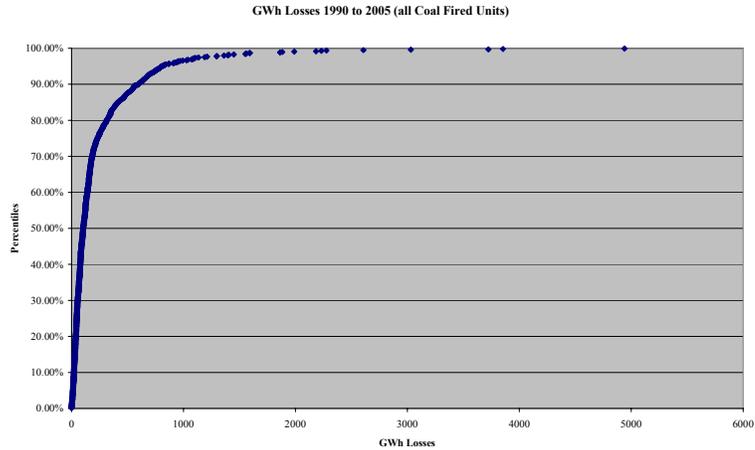


Fig 2.9: CDF of GWh Losses

Having looked at the individual GU's energy losses, and the maximum loss that an individual GU could incur in a year, one could also ask **what is the maximum sum of all the GU losses in a year**. Another relevant question could be **how the values of the maximum GU losses affect the value of the maximum sum of the GU losses**, over a threshold t ; in other words how do these individual losses affect the System. Referring to [13] Embrechts it is shown there that:

$$\lim_{t \rightarrow \infty} \frac{P(X_1 + \dots + X_m > t)}{P(\max(X_1, \dots, X_m) > t)} = 1$$

, for every $m \geq 2$ Eq 2.2

Hence the tails of the distributions, either of the sum or the individual GU's losses of the first m GU's losses that would exceed the threshold t , are asymptotically of the same order. **This indicates the strong influence that the maximum individual GU energy loss has on the system.**

One could model further this aspect of total losses using the classical risk model:

$$U(\tau) = u + \alpha \tau - S(\tau)$$

Where u is the initial capacity, α is the available capacity @ time τ and $S(\tau)$ is the sum of the GU losses (i.e the Generation System Total Losses) until time τ .

Then, $S(\tau) = \sum_{i=1}^{N(\tau)} X_i$, where $N(\tau)$ is the number of GU's

that have failed until time τ and is a homogeneous Poisson process independent of X_i , the GWh Losses.

Taking this modelling aspect one further step ahead onto the Poisson process (see Fig 1.1). The Poisson approximation provides the basic essentials for the analysis of infrequent extremes from a sample. It is also the key to the Weak Limit Theory of upper order statistics as well as for the Weak Convergence of Point Processes, [13] Embrechts.

Usage of the Cramér-Lundberg model:

a] The GU's losses size process:

The sizes X_i are positive iid rv's having common non-lattice F , finite mean

$$\mu = E[X_i] \text{ and variance } \sigma^2 = \text{var}[X_i] < \infty$$

b] Times at which the GU losses occur are random instances of time:

$0 < T_1 < T_2 < \dots$ a.s. (almost sure [i.e. with probability of almost 1])

c] The arrival process

The number of GU's in the interval $[0, \tau]$ is denoted by

$$N(\tau) = \sup \{n \geq 1: T_n \leq \tau\}$$

d] The inter-arrival times of losses

$Y_1 = T_1, Y_k = T_k - T_{k-1}, k = 2, 3, \dots$ are iid exponentially distributed with finite mean $E[Y_1] = 1/\lambda$.

A consequence of the definition above is that $N(\tau)$ in a homogeneous Poisson process with intensity $\lambda > 0$ and $N(\tau) > 0$ hence:

$$P(N(\tau) = k) = e^{-\lambda\tau} (\lambda\tau)^k / k!, \text{ for } k = 0, 1, 2, \dots$$

Here the loss size X and inter-arrival time Y of losses are independent of each other [13] Embrechts. See Appendix C (equation C2.4) for an extension on this aspect.

When looking at $S(\tau)$ from a distributional aspect and express it as:

$G_\tau(s) = P[S(\tau) \leq s]$, [3] Beirlant (p117) showed that, using the independence assumption between $\{N(\tau); \tau \geq 0\}$ and $\{X_i; i \geq 1\}$ and a conditioning argument on $N(\tau)$:

$$G_\tau(s) = \sum_{n=0}^{\infty} p_n(\tau) \cdot F^{*n}(\tau), \text{ where } *n, \text{ refers to the}$$

distribution of the total loss,

$S_n(\tau) = X_1 + X_2 + \dots + X_n$, the n -th convolution of F with itself. Considerable research is being done in this compound distribution function, [3] Beirlant (p117) and pp 13, 37-49, 571-576 [13] Embrechts.

In this field Super- and Sub-exponential distributions play an important role, for instance if the largest of the GU losses ($\max [X_i]$) influences the stochastic behaviour of $S_n(t)$, then the Sub-exponential distributional properties ought to be used.

The number of GU's incurring a loss, has a distribution considered "light" if:

$$E[z^{N(\tau)}] = \sum_{n=0}^{\infty} p_n(\tau) \cdot z^n < \infty, \text{ for some } z > 1$$

Hence a light “GUs-Losses-number” distribution has exponentially small probabilities. If we believe or can verify this statement, then according to [3] Beirlant, Cline’s (1987) and (for more precise estimates) Willekens-Teugels’ (1992) results can be used for the computation of quantiles of $S(\tau)$. Caution ought to be exercised since the inversion of Cline’s model yields conservative results on the computation of high quantiles. Much more research is needed in this field and therefore the results are limited to the EDA for this topic.

Year	Max Loss	Total Loss
1996	1296.0	8147
1997	2607.5	9513
1998	651.8	7238
1999	529.9	6421
2000	394.0	5002
2001	602.7	4379
2002	3031.0	7270
2003	4939.8	16885
2004	969.7	9876
2005	1883.1	12647

Table 2.9: Maximum GU loss and Total System loss

The subset 1996 to 2005 was used as this window is considered a more stationary period.

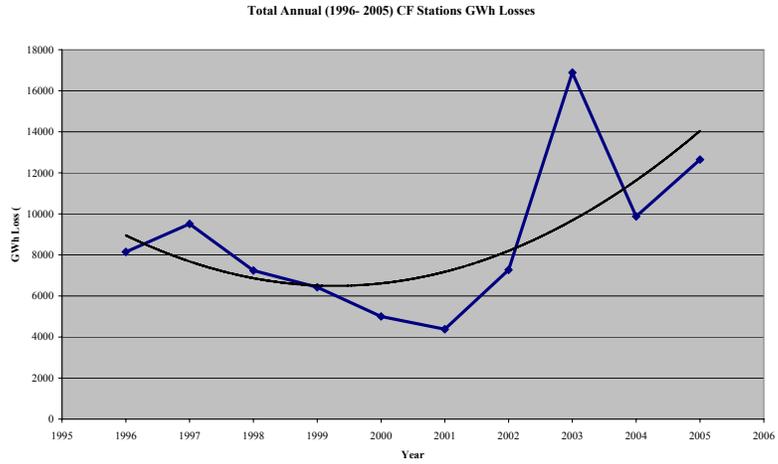


Fig 2.10: Annual Total System GWh Losses

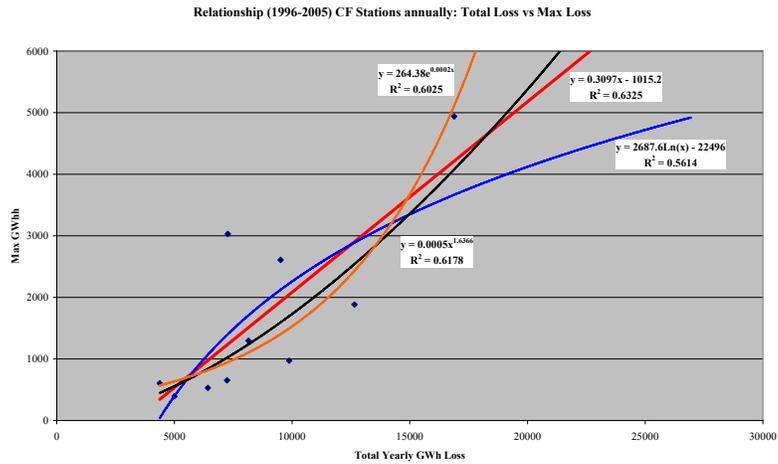


Fig 2.11: Relationship: System GWh Losses vs GU Max Loss

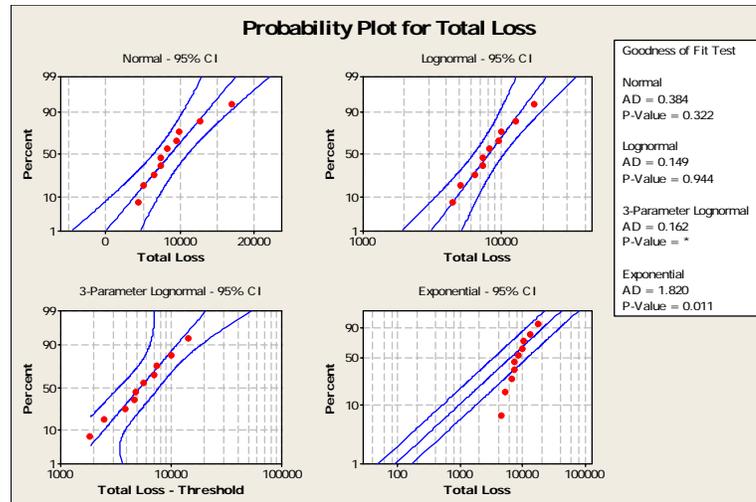


Fig 2.12: Distributional Fits of System GWh Losses

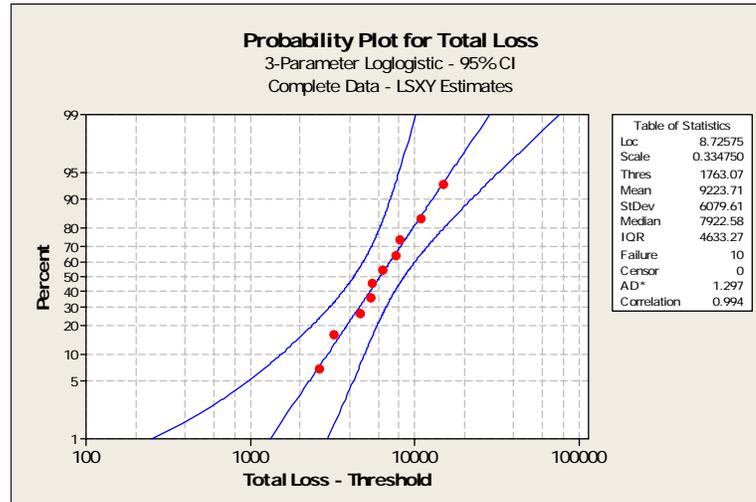


Fig 2.13: LogLogistic Fit to System GWh Losses

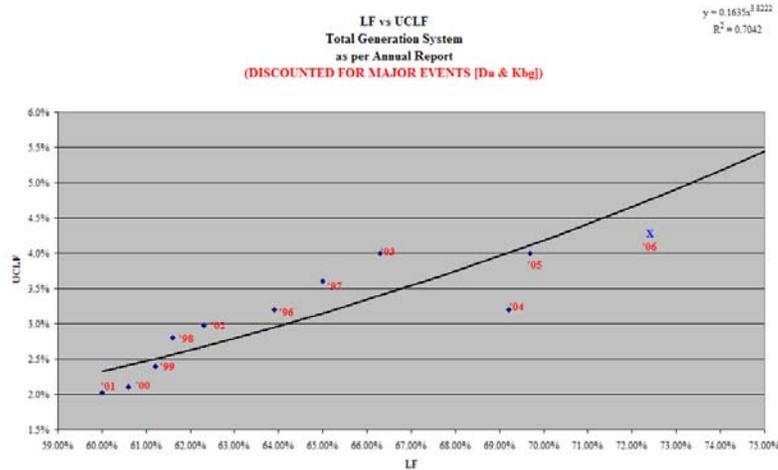


Fig 2.14: Relationship: System GWh Losses UCLF and Load Factor

The Total System Losses in GWh (TSL) for the period 1996 to 2005 are depicted in Fig 2.10. The TSL shows an increasing upward trend, or possibly a cyclic behaviour as time increases. Fig 2.11 shows the relationship between the GUs' max loss in a particular year associated with its corresponding TSL. Even though the Logarithmic model $y = b.Ln(x)+a$ has the lowest R^2 (blue line), from an engineering perspective it makes more sense for the following reason: the Max GWh loss (y-axis) is limited to the IC x Hours p.a. (say 5270.4 GWh for a 600 MW GU in a leap year), hence one would expect the relationship to be asymptotic towards that value; the limit of the TSL being approximately 318 000 GWh (x-axis, 10 time more to the right than the value illustrated).

If not trended, and distributional fits are performed on the TSL, the results are shown in Fig 2.12 and 2.13, with the

LogLogistic distributional fit being the “best”. This indicated a “threshold” (shift parameter) of 1763.07 GWh. Although this analysis bodes well, it is somewhat limited as it is not leveraging the nature of the trend, cyclical or curvy-linear relationship, seemingly with time. Further work by the author indicates that another concomitant variable plays an important role, i.e. the Load Factor (LF). The LF is time related and a function of the energy demand imposed by the market on the IC. The more demand is imposed on the GUs’ the higher the stress on the GUs’ the higher the losses at System level (the model shown in Fig 2.14 is only valid at System level, though, and not at GU level: as the LF increases, at GU level, the GU fails and hence the LF at that GU is 0, however another GU “picks-up” the load, hence the LF at System level is seen as increasing with the corresponding loss at System level increasing). This relationship is illustrated in Fig 2.14 (the 2006 value is shown by **X**). Further studies were performed by the author on this issue to validate the relationship, with positive results. This also involved experimental work on the Cobb-Douglas production model: $e^{kY}.Y = A.X^b.Z^c.\varepsilon$ or in linear form:

$$kY + \ln(Y) = a + b.\ln(X) + c.\ln(Z) + \varepsilon,$$

where $Y = \text{UCLF}$, $X = \text{LF}$ and Z the lagged (5year) PCLF or, most likely, the cost of production; a simplified version is shown in Fig 2.14.

It would also be appropriate to utilise the property of the losses conditional to the load when estimating the TSL and its expected extremes. To do that, appropriate forecasting techniques ought to be used to forecast the energy demand with its appropriate credible set (or confidence region; the Bayesian “confidence interval”), say the High Posterior

Density (hpd) credible set. This could then be used to infer the TSL losses on the logarithmic model proposed above. A contour of TSL given a region of LF can then be constructed.

Delving into EVT, a recent method developed by [28] Nel et al using the Logistic Copula can be used to estimate the joint probability of the annual GU maximum loss and the annual TSL by considering the joint distribution of the of the GU and TSL marginals through the Logistic Copula. Should the annual values be too small of a sample to consider, the quarterly max GU and TSL values could be utilised; this might be of interest to determine the winter and summer risk exposure to maximum losses and the provision of reserve capacity in those periods.

To return to the focal point of this thesis, i.e. the GUs' extreme losses incurred in a year, the above topic as well as this Chapter is ended here but certainly gives a background for further research.

CHAPTER 3

Analyses of Extremes in GWh Losses

3.1 Introduction

The risk associated with extreme events has and is intriguing management more and more. In the energy platform this aspect is no different and the implementation of risk models that allow for rare but damaging events is starting to become more intrinsic in the running of the electricity business under the umbrella of Risk Management.

It is envisaged that an energy Vol@R in the form of GWh and provision for reserve capacity, would become part of NERSA legislature for utilities in South Africa.

The approach in this thesis is in attempting to model these types of risks in such a way that the GUs' extreme losses are addressed. Eventually, this is foreseen to provide a measure for risk as mentioned above (Vol@R).

Although the research indicated that [16] Fuller in 1914 and [18] Griffith in 1920 played a role in describing extreme events, it is still the author's belief that the seed of EVT results from [35] Tippett.

Fig 1.2 portrayed a visual of the occurrence of extremes in a distribution. In paragraph 1.2 the basics and an outline of

EVT have been mentioned in terms of the history, Maximum Domains of Attraction (MDA), various methodologies to estimate the parameters of the distributions in the extreme values domain. It also gives a short introduction to using the method of “Entropy” to, say, assess an optimal level of the threshold given the distribution parameters estimates. The entropy concept is also used in EVT in stochastic modelling so that modelling is not done just heuristically and informally, but a more general approach is taken so that a simplistic, explicit and reproducible manner is used, [43] Zellner

The extremes of the GUs’ losses in GWh for the period 1990 to 2005 in the form of the empirical CDF, are illustrated in Fig 2.9. From there the “long” tail of the losses behaviour is clearly visible. What is also visible is that, at the tail, the set consists of very few data points relative to the rest of the set.

3.2 Block Maxima

Even though in this part of the modelling, two approaches are used, the Block Maxima (BM) and the Peak-Over-Threshold (POT), the BM was explored but the POT approach was eventually adopted.

The idea was to model the extreme yearly GU GWh loss. The methodology consisted in taking the maximum GWh loss for each year over all the GUs’, $Y_i = \text{Max} \{X_j\}$, for $i=1,2,\dots,n$ -th year and $j=1,2,\dots,m$ -th GU. Hence for year 2005, the max loss over 64 GUs’ was $Y_{16} = 1883$ GWh loss for the 16th year since 1990, Fig 3.1 below shows the data points for Y_i .

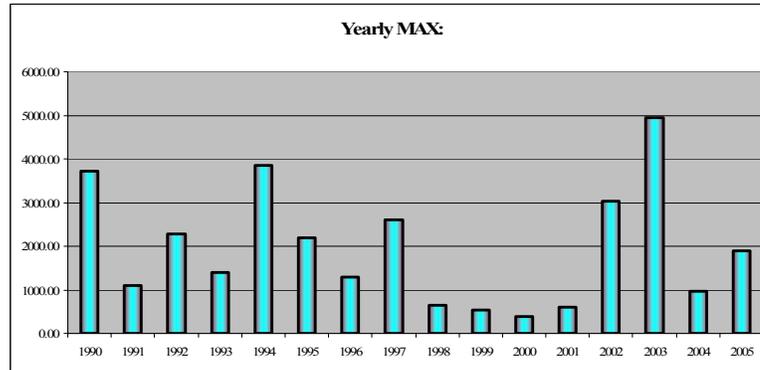


Fig 3.1: Yearly Maximum GU GWh

From EVT, the distribution of $Y_i = \text{Max} \{X_j\}$, as $m \rightarrow \infty$ converges to a GEV or more specifically to a *SGEV*:

$$G_{\gamma}(x) = \begin{cases} \exp \{ -(1 + \gamma[(x-\mu)/\sigma]^{-1/\gamma}) \} , & \text{if } \gamma \neq 0 \\ \exp \{ -\exp\{-(x-\mu)/\sigma\} \} , & \text{if } \gamma = 0 \end{cases} \quad \gamma \in \mathfrak{R} \quad \text{Eq 3.1}$$

where γ is the *shape* parameter, μ the *location* parameter and σ the *scale* parameter.

By using the PWM method the parameters were estimated as:

Shape	0
Scale	995.04
Location	1358.55

With these estimates, Eq 3.1 reduces to:

$G_{\gamma}(x) = \exp \{ -\exp\{-(x-\mu)/\sigma\} \}$ which is of the Gumbel type (see Appendix Eq. A2.5)

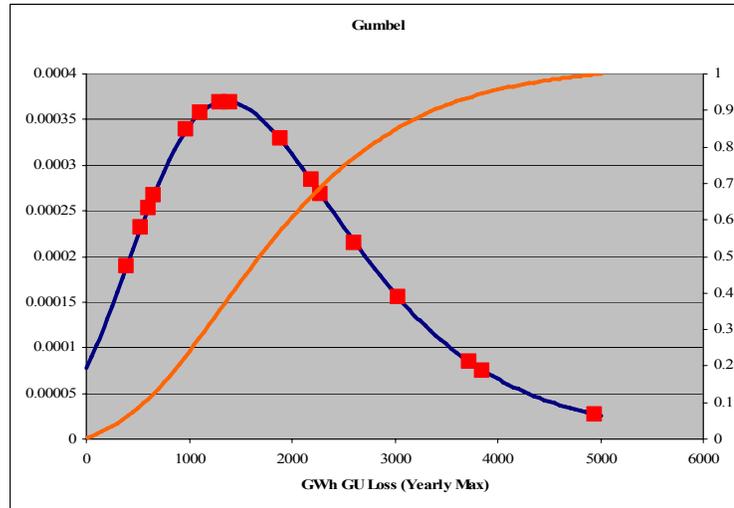


Fig 3.2: Yearly Max Distribution: Gumbel

The Gumbel pdf is given by:

$$g(x) = (1/\sigma) \cdot \exp \{-(x-\mu)/\sigma\} \cdot \exp \{-\exp \{-(x-\mu)/\sigma\}\} \quad \text{Eq 3.2}$$

for $x \in \mathfrak{R}$ (see Eq. A2.8)

Using the estimates above, the pdf illustrated in Fig 3.2 is obtained. The actual yearly maxima are shown by the red blocks when entered into the pdf equation above.

The interpretation of Fig 3.2 is quite useful.

Over a similar window period the expectation is to see values of 1359 GWh losses more often than other values as a yearly maximum. Half of the time, over a similar window period, the system is expected to incur yearly maxima greater than 1700 GWh.

What is also of interest is the return period.

One could be interested what value could be exceeded in any particular year with a chance of one in twenty (i.e. $p=1/20 = 0.05$). By using:

$$Q_{Y;p} = \mu - \sigma \text{Ln}(-\text{Ln}(1-p)) \quad \text{Eq 3.3}$$

(see Appendix A, paragraph 2.3.1), and the estimates above, we get $Q_{Y;0.05} = 4314$ GWh.

Let us assume that the management needs to know what is the yearly maximum GWh loss that we expect to exceed every 10 years, i.e. $P(Y > {}_{10}y) = 0.1$

\therefore from Eq 3.3 above, ${}_{10}y = 3598$ GWh; i.e. the company should expect the maximal annual GWh loss to exceed 3598 GWh every 10 years.

p0	p	Qy;p	
0.85	0.150	3166.5	
0.875	0.125	3362.0	
0.9	0.100	3597.8	
0.925	0.075	3897.4	
0.95	0.050	4314.0	
0.975	0.025	5016.6	
0.980	0.020	5241.1	
0.985	0.015	5529.9	
0.990	0.010	5935.9	
0.9375	0.0625	4085.45	1/16
0.97302	0.02698	4939.789	1/37

Table 3.1: Quantiles, Block-Maxima method

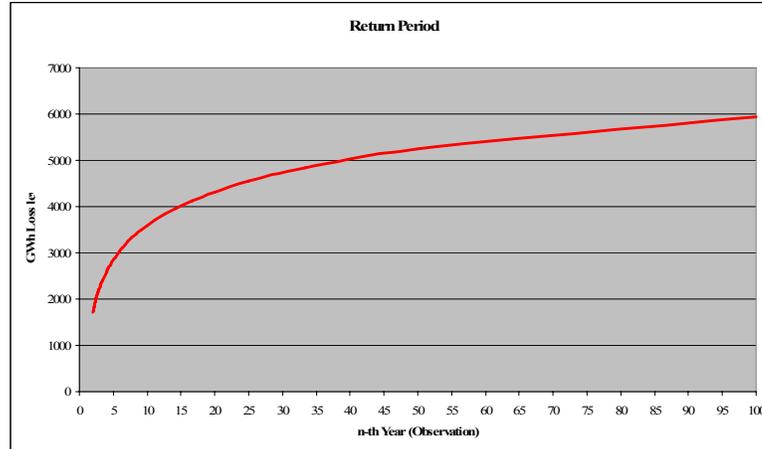


Fig 3.3: Return period of GWh Losses – Yearly Maxima

The GWh loss levels can be expressed in the form of Fig 3.3 above. This may be interpreted as follows: by entering the expected year one reads off the value on the y-axis (the values are computed by means of Eq. 3.3). For instance, the management can expect every 20 years to exceed the value of 4314 GWh loss. These quantiles refer to the Stress Loss, for instance, $p_0 = 0.95$ yields the 20 year return level of a GU GWh loss. It may also be considered as a kind of unconditional quantile estimate for the unknown underlying distribution of F (which is in the MDA of the Gumbel, see Appendix A – Classical EVT).

However, the quantiles in Table 3.1 are based on limited information and inferences are made upon the parental distribution based on 16 values out of 928. If one had to then be even more prescriptive and invoke stationarity, then even less observations (see Table 2.9 in Chapter 2, the data spans from 1996 instead of 1990) can be used (i.e. that the block maxima are invariant under time shifts – this

was relaxed when doing the analysis). Comparing Table 3.1 results from the fitted pdf, the expectation of the quantile for 1/16 years is 4085.5 GWh, however within this period, a value of 4939.8 GWh was observed; by computing the inverse, for a value of 4939.8 GWh we get a return period of 0.02698 or 1/37 years, over than twice the span!

Clearly, this method seems not to be yielding the expected results. This might be that for the next 21 years we won't observe such a high value, although unlikely; it might also be that there is not enough history. Or this might well be that, even with a limited dataset, by making use of the relationship of the losses within the categories, one could obtain better results.

For instance, assume that X is the random vector of the GUs' losses falling in different categories, such as those illustrated in Table 2.4 in Chapter 2.

Then, $\mathbf{X} = (X_1, X_2, \dots, X_d)$ for each of the d different categories, assume that the X 's have a joint distribution

$F_X(x_1, x_2, \dots, x_d) = P(X_1 \leq x_1, X_2 \leq x_2, \dots, X_d \leq x_d)$ and assume that the individual losses have continuous marginals $F_i(x) = P\{X_i \leq x\}$, then by [25] McNeil p111,

$$F_X(x_1, x_2, \dots, x_d) = C[F_1(x_1), F_2(x_2), \dots, F_d(x_d)] \quad \text{Eq 3.4}$$

where C is the Copula of F and measures the dependence structure of \mathbf{X} . For the GEV in the Block Maxima application these are referred to as MEV (Multivariate Extreme Value) Copulas.

In the BM methodology used, the Gumbel Copula would be given by Eq 3.5 below:

$$C_{\beta}^{Gu}(v_1, v_2) = e^{-[\{-Ln(v_1)\}^{\beta} + \{-Ln(v_2)\}^{\beta}]^{\beta}}, \quad 0 < \beta < 1 \quad \text{Eq 3.5}$$

The Copula would show the tail dependence, i.e. the tendency of extreme values to occur together in the different categories.

Let $d=2$ (i.e. only two categories of losses):

If $\beta = 1$, $C_{\beta}^{Gu}(v_1, v_2) = v_1 \cdot v_2$, which models the independence of $(X_1, X_2)'$

For $\beta =]0;1[$, then the Copula models the dependence between X_1 and X_2 .

At $\beta = 0$, the process would have perfect dependence between X_1 and X_2 i.e. $X_1 = g(X_2)$.

In Chapter 2 Table 2.4 exhibited 6 categories. As it may be seen, the modelling of 6 dimensions in amalgamating Eq 3.5 into Eq 3.4 becomes very complex. This is a typical problem when d becomes large in the usage of Copulas in the BM methodology. This problem is usually referred to as the “curse of dimensionality”; a usual solution is to collapse the model from a Multivariate into a Univariate one.

NB: In the parameter estimation for the BM pdf above, the PWM method was used. The reason for this is that the value for γ was not known. Seen that the GEV applies to the BM method, if one were to choose MLE to estimate the parameters, one ought to exercise caution as a condition for using MLE is that the data must be free of the parameters we are trying to estimate, this is usually referred to as regularity. The GEV is known to be “non-regular” for $\gamma \neq 0$.

Although the BM method provided an insight in the extremes and surely more research for the future in using

the Copulas, unfortunately, with all the data that was collected, it did not yield the needed information adequately (see Table 3.1 and comments in p.49 [top]).

This enticed further research into the Peak-Over-Threshold method as a different approach to analyse the GWh losses.

3.3 Peak Over Threshold (POT)

As described in the previous paragraph, the BM approach yielded possibilities, such as stress-loss assessment, usage of Copulas, but somehow lacked effective returns out of the analyses (see Table 3.1 above whereby that max loss should have predicted 1/16 and not 1/37). Somewhat lately, a more modern approach has been one of using large observations which exceed a relatively high threshold. This method is known as the Peak Over Threshold (POT) method. Because of the usually limited data sets, the POT method is generally considered, at present, the most effective applied approach to EVT. There are two further types of methods within POT: The semi-parametric (POTsp) and the full-parametric (POTfp). The POTsp concentrates around the Hill, Pickands, Zipf, Beirlant-Q estimators while the POTfp, is based on the GPD properties.

There is a further methodology that is gathering momentum and that is the one that applies itself to both the BM and POT methodologies: the Bayesian approach to EVT, Chapter 4 is devoted to this methodology.

In this Chapter, the analysis concentrates on the classical approach, and utilises the POTsp to narrow down the analysis; the POTfp is the avenue taken for the GUs GWh losses parametric estimation.

3.3.1 Semi-parametric method (POTsp)

As in the classics, it is said that a picture explains a thousand words; this approach follows that kind of philosophy. The Quantiles properties are leveraged to yield required results. For instance, Quantiles (of the sample and distribution) are linearly related if the drawn sample is derived from the hypothesised distribution. By utilising this property a power instrument called the Q-Q plot can be used to derive the goodness-of-fit of the GWh Losses (see Appendix C paragraph 2.5 on derivation of Quantiles from particular distributions).

Since we are dealing with extremes the first attempt is at plotting the classical ones that map onto the MDA: the Weibull, Gumbel and Fréchet distributions.

This was performed and the results are illustrated in Fig 3.4 to Fig 3.7 here below.

The Exponential Q-Q plot of Fig 3.6 was given as illustrative of a specific part of the Gumbel domain (note the kink between the 12th and 11th largest observations).

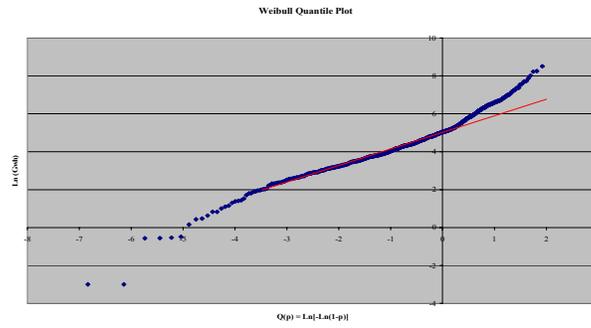


Fig 3.4: Weibull Q-Q Plot of the GWh Losses

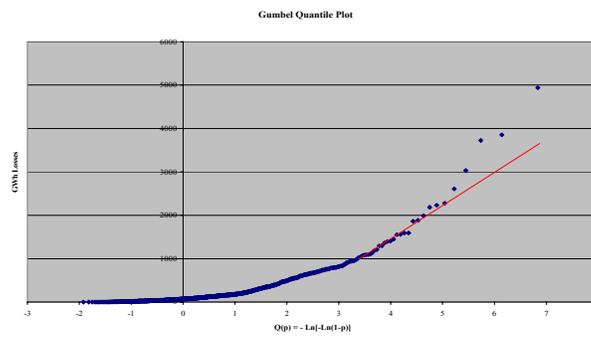


Fig 3.5: Gumbel Q-Q Plot of the GWh Losses

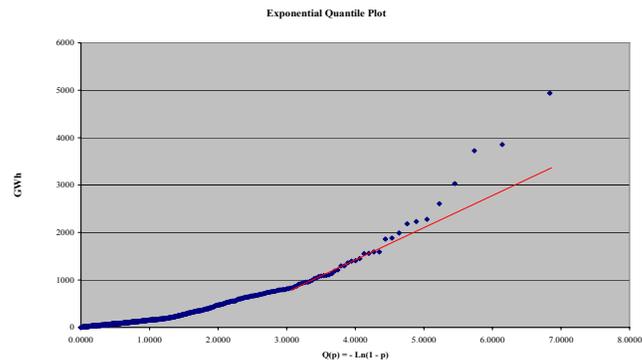


Fig 3.6: Exponential Q-Q Plot of the GWh Losses

Visually, Fig 3.4 to Fig 3.6 exhibit a significant departure at the tail (using the red straight line as a reference). Since the objective here is to narrow down to which population the GWh Losses belong to, the Gumbel and Weibull families already show that the tails from these families do not represent well the behaviour of the GWh losses. There remains one other class and that is the Fréchet class of distributions. When exploring this avenue, the Q-Q plot shown in Fig 3.7 was obtained. It is visually clear that this type of distribution seems more plausible than the others, as the linear tail trend fit well in the tail and well into the empirical on the left hand side.

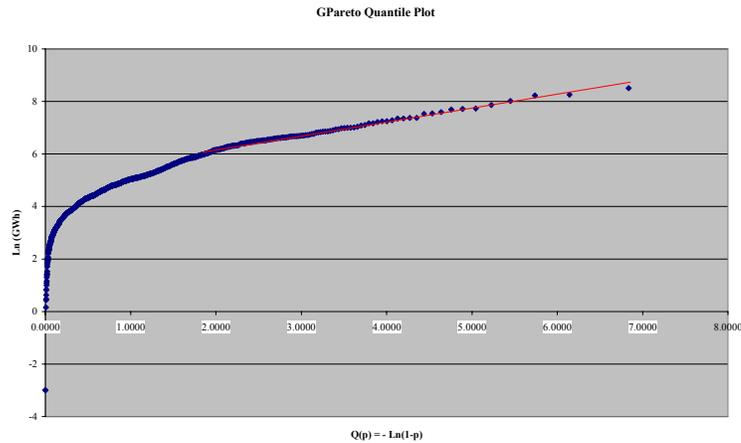
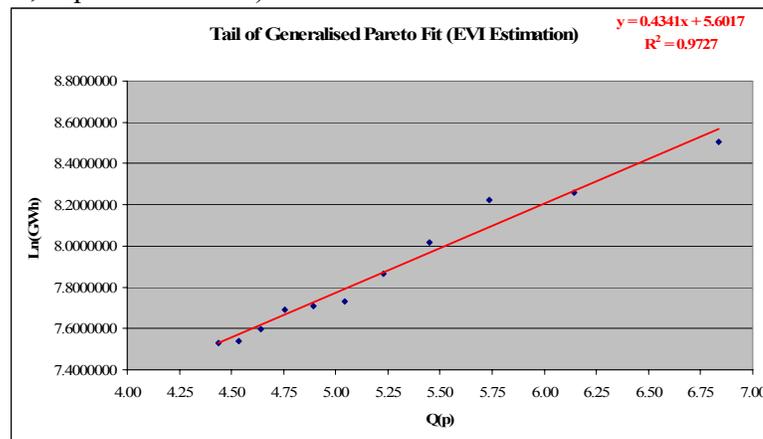


Fig 3.7: Generalised Pareto Q-Q Plot of the GWh Losses

The Q-Q plot of the GPD also indicates that there seems to be a kink between the 12th and 11th largest observations. Zooming in at this aspect of the tail and utilising the 11 largest observations in the Quantile domain, and applying a linear model fit to obtain the parameters, Fig 3.8 was

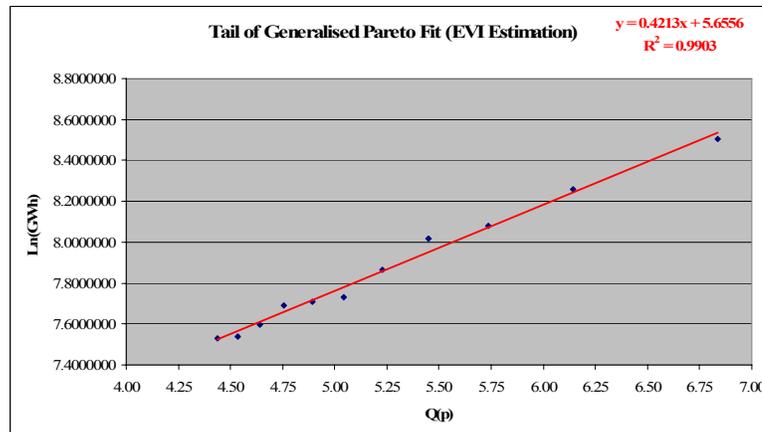
obtained. The EVI (see Appendix A paragraph 2.1) can be estimated from the slope of this fit namely 0.4341 with a 95% CI [0.3793 ; 0.4889].

This seems to give a reasonable result and prompted further investigation of this tail: the fit in Fig 3.8, indicated a “blip” in the 3rd largest observation. This loss was incurred at a GU3 of a particular power station in ‘90, if a “background loss” of approx. 500 GWh was removed, then a much better fit was obtained which is illustrated in Fig 3.9 yielding to an EVI estimate of 0.4213 with a 95% CI [0.3898 ; 0.4528]. With an $EVI > 0$, the process indicates that it not does not derive from a Gumbel Class (Appendix A, Eq A2.3 to A2.5).



$k=11$	Coefficients	Standard Error	t Stat	P-value	Lower 95%	Upper 95%
Intercept	5.6017	0.1282	43.698782	0.000000	5.3117	5.8916
X-Slope	0.4341	0.0242	17.924033	0.000000	0.3793	0.4889

Fig 3.8: GPD Q-Q Plot of the 11th Largest Observations



$k=11$ (Adj.)	Coefficients	Standard Error	t Stat	P -value	Lower 95%	Upper 95%
Intercept	5.6556	0.0737	76.736524	0.000000	5.4889	5.8223
X-Slope	0.4213	0.0139	30.256506	0.000000	0.3898	0.4528

Fig 3.9: GPD Q-Q Plot of the 11th Largest Observations (Adjusted)

[3] Beirlant has shown that if the behaviour can be expressed “when a non-decreasing continuous function g exists between Y and X , such as $Y = g(X)$, then the same relation exists between the corresponding quantiles of the respective distributions”, i.e.

$Q_Y(p) = g(Q_X(p))$, $\forall p \in (0;1)$, extensive work was also done by [12] Dierckx in this regard. Hence, having carried out the analyses that yielded Fig 3.4 to 3.9 (see [3] Beirlant pp 81-87, particularly top of p85), the Q-Q method emphasised the characterization of the behaviour of the GWh Losses at annual GU level, which can therefore be described by a Generalised Pareto Distribution.

Mean Excess Function (MEF) Diagnostic (see Appendix A paragraph 2.4)

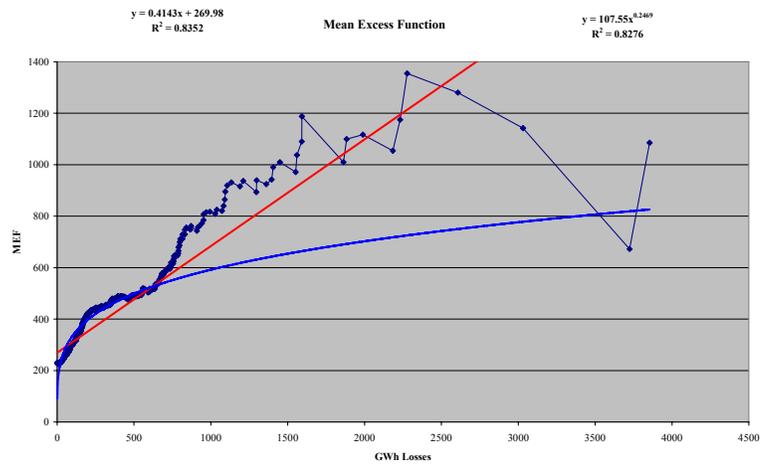


Fig 3.10: MEF vs GWh Losses

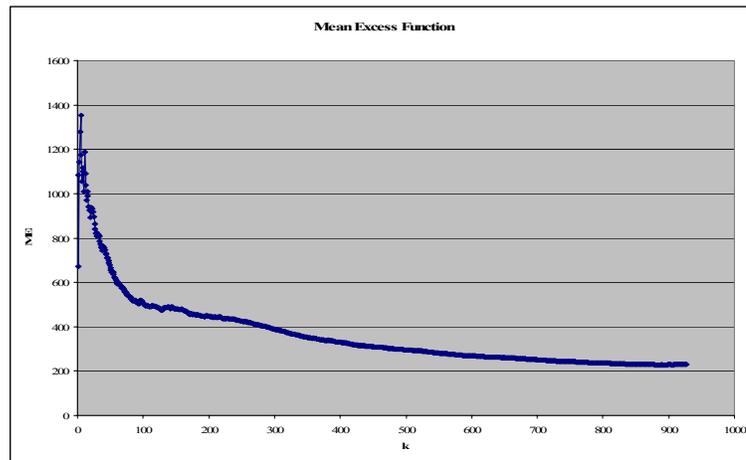


Fig 3.11: MEF vs k

In Fig 3.10, there is again substantiation that the GWh Losses derive from a distribution in the Fréchet class; the linear trend is more prominent than the curvy-linear one. [3] Beirlant, p39 Fig I15, shows that the linear behaviour belongs more to the Pareto type than the Gumbel or Weibull types (see also [3] Beirlant Fig I.18 p42, in comparing with Fig 3.10 and Fig 3.11).

Fig 3.11 shows the MEF versus k , the indicator that represents the largest observation, e.g. the largest observation would be the first, therefore $k=1$, the 2nd largest, $k=2$, etc..., this means that the set of k would span from 1 to $n-1$, where n is the total number of observations. Then

$$\text{MEF} = \hat{e}(k) = \frac{1}{k} \sum_{i=1}^k y_{n-i+1} - y_{n-k} \quad \text{Eq 3.6}$$

where y represents the ordered GWh losses

This instrument can be used in management circles when the mean GWh loss of say 20 GUs' might incur at the extremes. By using Fig 3.11 (or more specifically, computing the MEF thereof) the Mean Excess loss at $k = 20$ is 893 GWh.

Statement: The MEF is related to the Conditional Tail Expectation (CTE).

Let the goal be in estimating the CTE μ_p then,

$\mu_p = E [Y|Y>y_p]$, where y_p is the upper p^{th} quantile and not very small (e.g. 5%). Let $(k/n) \approx p$ and define

$$D_k = \frac{1}{k} \sum_{i=n-k+1}^n Y_i, \text{ then for large } n,$$

$$\sqrt{k} (D_k - \mu_p) \sim N [0 ; \sigma_p^2 + p(y_p - \mu_p)^2],$$

where $\sigma_p^2 = \text{var} [Y | Y > y_p]$.

The values of y_p , μ_p and σ_p^2 can be estimated from the sample by using the sample quantile Y_{n-k} , the computed D_k and $(S_D)^2$, respectively; where $(S_D)^2$ is the sample variance of the top-k order statistic.

The CTE and MEF are then related by:

$$E [Y | Y > c] = c + \hat{e}(c).$$

The MEF extends to the Hill estimator (this estimator is biased, p56 [3] Beirlant).

On the Q-Q plots of Fig 3.7 to Fig 3.9 it was mentioned that the slope is expected to be linear if the variable is behaving in the Fréchet class; further, this slope is defined as the EVI (see Appendix A paragraph 2.1) or the inverse of the *Pareto Index* (if the distribution is of the Pareto type).

The Hill estimator is given by:

$$H_{k;n} = \frac{1}{k} \sum_{i=1}^k \text{Ln}(y_{n-i+1}) - \text{Ln}(y_{n-k}) \quad \text{Eq 3.7}$$

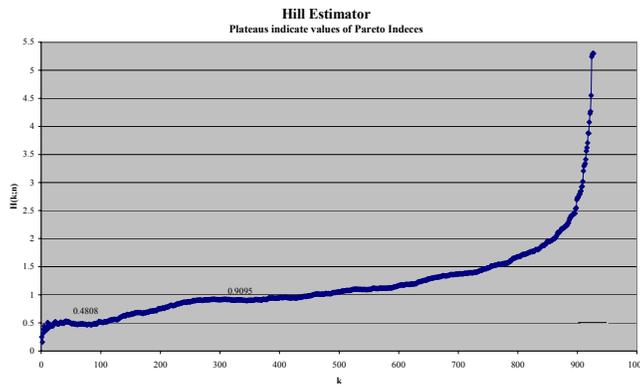


Fig 3.12: Hill Estimator vs k

As shown in Fig 3.12, the Hill estimator exhibits two plateaus, one at 0.4808 and another at 0.9095. If we compare this to the results obtained in Fig 3.8 (i.e. without the outlier adjustment), then the value for the EVI of 0.4808 is within the 95% CI, and this seems a plausible value.

A more thorough analysis by inspection yielded a value for the EVI of 0.47508.

The Pickands estimator result is given in Appendix C, paragraph 2.6.

Fig 3.12 is very similar to the one obtained by [3] Beirlant Fig I20 p 44 of a Burr distribution. Beirlant goes further in assessing an EVI by means of weighting the Hill estimator to arrive at an optimal k (pp 59-64).

This method yields an EVI of 0.4684 at $k = 61$, which is comparable to the one obtained in Fig 3.8; its CI's can be obtained by ([3] Beirlant p64):

$$\left[\frac{\hat{\gamma}}{1 + \frac{z_{\alpha/2}}{\sqrt{k}}}; \frac{\hat{\gamma}}{1 - \frac{z_{\alpha/2}}{\sqrt{k}}} \right], \therefore \text{ at 95\% two-sided,}$$

$$\hat{\gamma} = [0.3744 ; 0.6253]$$

Although this interval is wider from the upper side, than the one obtained from the Quantile regression (γ is adjusted for the outlier), the results remain relatively comparable.

From Fig 3.9's parameters the following model for the GWh losses was derived:

In a year:

$$\text{GU-GWh Losses} = t \cdot e^{-\gamma \cdot \text{Ln}(1-p)}, \quad 0 \leq p < 1 \quad \text{Eq 3.8}$$

Here the EVI may be interpreted as the probabilistic rate at which all GUs would tend to incur the losses and this rate would induce the losses to vary, non-linearly according to p (at least from $p \geq 93\%$), see Fig 3.13 below.

In Eq 3.8, t may be interpreted as the expected “background” losses or a possible threshold. For $p = 0$, Eq 3.8 reduces to $t = 285.89$ GWh.

The results of Eq 3.8 can essentially be summarised in the table below:

p	1-p	Q(p) = -Ln(1-p)	Ln(GWh)	GWh
0.95	5.0%	2.9957	6.9177	1010.02
0.955	4.5%	3.1011	6.9621	1055.86
0.96	4.0%	3.2189	7.0117	1109.58
0.965	3.5%	3.3524	7.0680	1173.79
0.97	3.0%	3.5066	7.1329	1252.55
0.975	2.5%	3.6889	7.2098	1352.55
0.98	2.0%	3.9120	7.3038	1485.88
0.985	1.5%	4.1997	7.4250	1677.34
0.99	1.0%	4.6052	7.5958	1989.79
0.995	0.5%	5.2983	7.8878	2664.60
0.996	0.4%	5.5215	7.9818	2927.25
0.997	0.3%	5.8091	8.1030	3304.43
0.998	0.2%	6.2146	8.2738	3919.98
0.999	0.1%	6.9078	8.5659	5249.38

Table 3.2: Quantiles, POTsp method

Practically, from Table 3.2, one may deduce that with a fleet of 64 units, the company expects to exceed 1010 GWh once in twenty years. Another way of interpreting the table above, is that since the expectation is in GU-Years, is that, $1 / [(1-p) \cdot 64] = \text{return period}$,

i.e. for $1-p = 0.1\%$, one would expect that a loss by a GU of 5249 GWh be equalled or exceeded every 15.63 Years (or 15 years and 8 months). Similarly, from another angle, with a $p = 99.8\%$, one would expect that a loss by a GU of 3920 GWh be equalled or exceeded every 7.8 Years (or 7 years and 10 months). If the fleet was to increase to, say 70 GUs, then with $p = 99.8\%$, one would expect that a loss by a GU of 3920 GWh be equalled or exceeded every 7.14 Years (or 7 years and 2 months). Also, the expectation to have the absolute maximal GWh Loss of 5935 GWh, is 0.07% or with a fleet of 64 GUs, once in 20.9 Years (or 20 years and 11 months). A comparison may be made with Fig 2.9, whereby from table 3.2 we get that there is a 5% chance that a value of 1010 GWh would be exceeded.

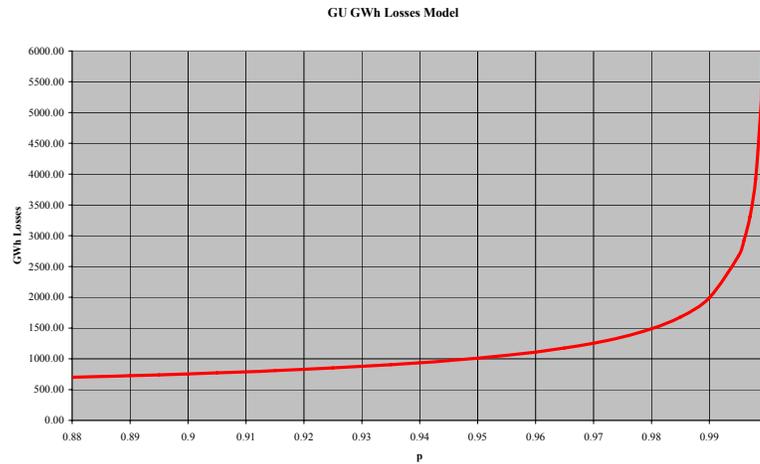


Fig 3.13: GU-GWh Losses Tail Model

The model may be inverted so as to derive the expected p 's :

$$p = 1 - e^{-[Ln(GWh)-Ln(t)] / \gamma} \quad , \quad \gamma \neq 0 \quad \text{Eq 3.9}$$

Using Eq 3.9 and keeping t constant (even though its 95% CI is [241.99 ; 337.76]), but letting γ be within its 95% CI, Fig 3.14 was obtained.

Scrutinising these results one may see that the empirical values do not fit well with a $t = 285.89$ GWh (the “black line” in Fig 3.14 tends to be outside the confidence bands). A choice criterion might be to choose $t = 1296$ GWh; that is the value at which the empirical crosses the level of significance, but the odds that this value would be the most likely t , are risky.

Another choice criterion might be a $t = 1591$ GWh; this being the value at which the empirical is close to the expectation (the “blue line” in Fig 3.15), here $k = 13$ largest values.

Or one may try to get even closer to expectation by using $t = 1862$ GWh while here $k = 11$ largest values. Although this is not surprising, as the Q-Q plot was fitted with $k = 11$ (see Fig 3.6 to 3.9 – kink level); what is surprising is that the fit extends up to $k = 21$ with a value of $t = 1296$ GWh.

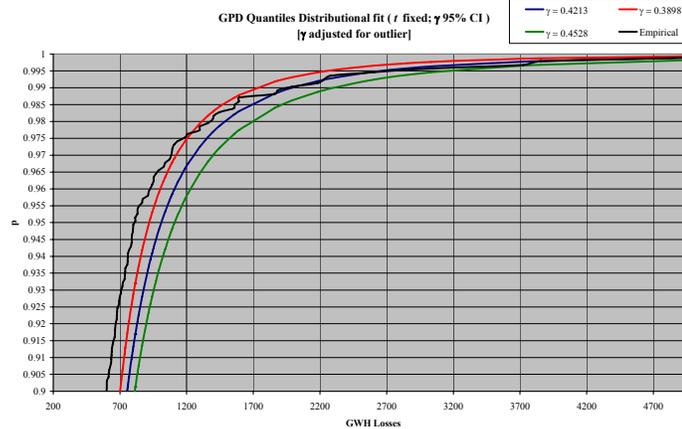


Fig 3.14: GU-GWh Losses GPD Fit

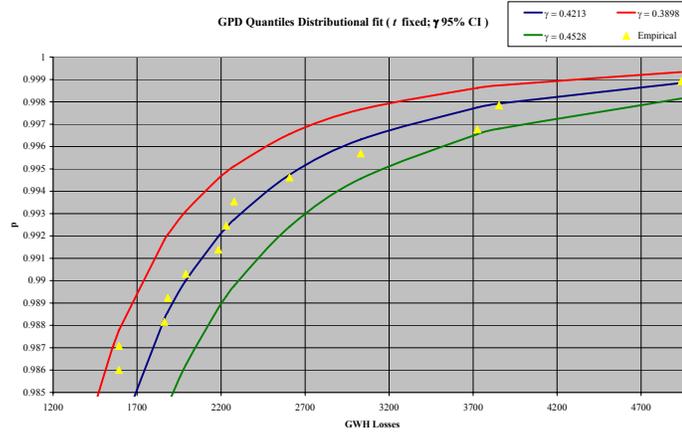


Fig 3.15: GU-GWh Losses GPD Fit (zoomed)

Fig 3.15 zooms-in to illustrate the fit up to $k = 13$ with a $t = 1591$ GWh

3.3.2 Full-parametric method (POTfp)

The POT_{sp} approach yielded very good results, and as it might have been perceived, raised a few more questions. The most fundamental one from the previous paragraph was “what should the value of t be?”, “how should it be chosen?” “can it be estimated effectively?”

It is already known (from paragraph 3.3.1, above) that the GWh losses follow a Fréchet type of distribution. Furthering the thought, from the works of [31] Pickands, the study pinpointed onto making use of the GPD properties (see Appendix A paragraphs 2.2 and 2.3.2) to model the GWh Losses behaviour in more detail.

Let X represent the ordered GWh losses and let t be the threshold, if $Y_i = X_i - t$,

for $X_i > t$, then for t – large, $Y \sim \text{GPD}$, whereby:

$$\text{GPD}_{\gamma,\sigma}(y) = \begin{cases} 1 - (1 + \gamma y / \sigma)^{-1/\gamma} & , \text{ if } \gamma \neq 0, \gamma y > -\sigma, y > 0 \\ 1 - \exp\{-y / \sigma\} & , \text{ if } \gamma = 0, y \geq 0 \end{cases}$$

Eq 3.10

When $\gamma > 0$, the GPD is heavy tailed, this means that the distribution does not have a complete set of moments (while the Normal, by contrast, has a complete set). Hence with the shape $\gamma > 0$, the moments are infinite for $k \geq 1/\gamma$, when $\gamma = 0.5$ the GPD has an infinite variance and when $\gamma = 0.25$ the GPD has an infinite 4th moment. This does not mean that there is no justification in a real market for infinite moments (like the 2nd and the 4th).

Usually the choice of \hat{t} should be such that it's high enough so that the asymptotic properties for the GPD can be satisfied and low enough so that there is sufficient data to estimate the parameters.

Given k exceedances above \mathbf{t} , two methods were used to estimate the location (\hat{t}), the shape ($\hat{\gamma}$) and scale ($\hat{\sigma}$) parameters: the L-Moments method and the Bayesian method (see paragraph 1.2.2 in the 1st Chapter). The Bayesian method is reflected in Chapter 4.

The estimation of percentiles may be computed as follows
Let $z_p =$ upper p^{th} percentile of $\text{GPD}_{\gamma,\sigma}(x-\mathbf{t})$, the estimate of z_p is:

$$\begin{aligned}\hat{x}_p &= t + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{P(X > t)}{p} \right)^{\hat{\gamma}} - 1 \right] \equiv \\ \hat{x}_q &= t + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{n(1-q)}{N_t} \right)^{-\hat{\gamma}} - 1 \right]\end{aligned}\quad \text{Eq 3.11}$$

where $P(X > t) > p$ and $P(X > t)$ is estimated by the sample proportion exceeding t .

That is $P(X > t) = N_t / n$ and $p = (1 - q)$ and inverting by making the exponent γ negative.

Let us say for instance that we would like to position our threshold at the 98.75th percentile, this means that the sample proportion $[(n - N_t) / n] = 0.9875$, since $n = 928$, $N_t = 928 \cdot (1 - 0.9875) = 11.6$, i.e. we ought to have 11 or 12 observations above our threshold. In Eq 3.11, say with $t = 1725$ (at the 98.75th percentile), then:

$$\hat{x}_{0.999} = 1725 + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{928(1-0.999)}{11} \right)^{-\hat{\gamma}} - 1 \right],$$

we still need to estimate $\hat{\gamma}$ and $\hat{\sigma}$

The reason of estimating the parameters of the tail using properties of the GPD under a threshold condition is usually because the data is very sparse at the tail end.

3.3.2.1 GPD Parameters Estimation

The usual preferred method is the MLE, however in this thesis a different approach is used. The first is the one of L-Moments (LM) and the second one, which is given in Chapter 4 is the Bayesian method.

Whenever using these methods, the cautionary statement (underlined) made in the paragraph above must be kept in mind.

The LM method (see Appendix A paragraph 2.3, aspect **IV**) resulted as an excellent method, particularly for the assessment of the threshold. The PWM is the precursor to the LM but with significant advantages, notably the ability to summarise a statistical distribution in a more meaningful way: they are linear functions of the sample values, they are virtually unbiased and have relatively low sample variance. LM ratio estimators have also a small bias and variance especially in comparison with the classical coefficients of skewness and kurtosis. LM estimators are relatively insensitive to outliers

The LM method has shown its power in the case of heterogeneous data sets; the quantile estimation for a Pareto distribution gives the smallest bias and RMSE when compared with MLE, LS and classical Moments [40] van Gelder.

Assuming a threshold t , and the GWh Losses represented by X with a distribution function $F_X(x)$, consider $Y = X - t$, [31] Pickands has shown that asymptotically, the distribution of Y (i.e. the X 's conditional on t), follows a GPD, given in Eq 3.10, above.

This distribution is **unbounded** (i.e. $0 < y < \infty$), if $\gamma \geq 0$ and **bounded** (i.e. $0 < y < \{\sigma/\gamma\}$), if $\gamma < 0$ (Eq 3.10).

Eq 3.10 has a unique threshold property, i.e. if $X \sim \text{GPD}$ then Y , the conditional distribution of the excesses, also follows a GPD with the same γ in X 's GPD.

Computations of quantiles of exceedances from Eq 3.11 of a value x_r , based on a r -year period, corresponds to a period $N_t \cdot r / n$, where $\xi = \hat{N}_t$ is the Mean Exceedance

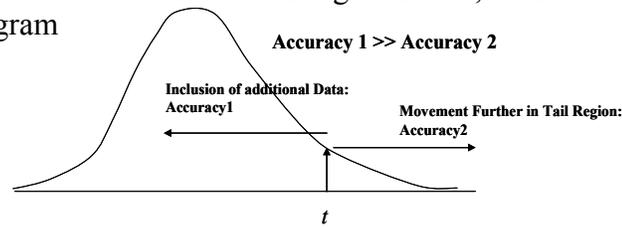
rate per year. From Table 2.4 in Chapter 2, Table 3.3 below was obtained,

	No. Exceedances over a threshold of $t =$ 400
2005	7
2004	7
2003	3
2002	1
2001	0
2000	0
1999	1
1998	0
1997	1
1996	1
1995	3
1994	2
1993	2
1992	6
1991	3
1990	2
Total	39
Tot Years	16
Mean Exceedance Rate	2.44

Table 3.3: Mean Exceedance Rate

The table above shows that, should threshold of 400 GWh be used then, ξ , the Mean Exceedance rate is 2.44 GUs p.a. That is one would expect 2.44 GUs each year to exceed the threshold of 400 GWh (derived from a total of 39 GUs over a period of 16 years). The recurrence period would be $1/\xi = 0.41$, i.e. one would expect one GU every (0.41×12) approx. 5 months, to exceed a loss of 400 GWh. Again this aspect shows the importance of not only of estimating the shape and scale but also of the threshold.

Eq 3.11 reveals an interesting trade off, as shown in this diagram



Hence an optimal threshold might exist that would result in a minimal trade off of accuracies

[7] Davison et al, have also shown that the distribution of the maximum excesses,

$Z = \text{Max} \{Y_i\}, i = 1, 2, \dots, k$ follows a GEV, provided that the exceedances over the threshold are generated from a Poisson process.

Returning to L-Moments, the method of 3-LM was used so as to get an indication of the threshold estimate. The 3-LM was initially applied to the full dataset and yielded to following result (refer to Appendix A paragraph 2.3, aspect IV):

r	1	2	3
b(r)	186.1983	161.1779	144.0855
b(0)	229.6999		

λ_1	229.6999
λ_2	142.6968
λ_3	79.57717
λ_4	51.0534

L-CV	τ
	0.621231
	τ_3 0.557666
	τ_4 0.357775

Shape	γ	0.432056
Scale	σ	127.0721
Location	t	5.959328

Table 3.4: 3-LM Parameter Estimates - Full Dataset

The indicator for the Threshold is 6 GWh as expected from the Full dataset; comparing it to the one obtained by the Two-Way Joining method in Cluster Analysis: 449.1 GWh (Fig 2.3 the lowest value in the Legend) it indicates that further selection is required. The shape parameter, with the full dataset, shows that the full distribution, if of the Pareto type, would be unbounded ($\gamma > 0$).

As suggested by [30] Pandey et al, when the 3-LM is applied on a $Y = X - t$, type of variable, it is very efficient under the GPD domain (but still exercise caution as mentioned above).

Under this premise, the moments were computed and the results are tabulated here below.

Threshold values were selected according to various criteria, for instance, the value of 484 was chosen as this seemed the expected background average GWh loss, resulting primarily from the work in Chapter 4.

	Shape	Scale	Location			
t	γ	σ	u	k	MEF	
150	0.30693345	253.959047	-14.532722	351	359.99	
375	0.34645987	288.806697	31.8118215	155	458.78	
403.4	0.36770832	280.830467	39.9049166	143	467.35	
449.1	0.38927422	272.856838	30.3970655	132	466.15	
484	0.40434481	271.215555	32.7506348	120	477.55	
878	0.36912826	429.504954	74.3137793	39	724.29	
1076	0.48827845	419.759019	-3.7451523	27	816.71	
Q-Q Plot	1296	0.40722789	436.672533	114.265318	21	815.16
Q-Q Plot	1591	0.44453959	414.14702	261.011381	13	954.48
	1796	0.53903737	311.70399	308.219593	11	1036.63
Q-Q Plot	1862	0.53903737	311.70399	242.219593	11	959.45
	1917	0.58509384	268.114843	418.941368	9	1236.99
	2252	0.67061101	185.041956	591.941207	6	1766.92

Table 3.5: 3-LM Parameter Estimates–Various Thresholds

The value of 403.4 GWh was obtained visually from the full distribution Q-Q plot of Fig 3.7 in Chapter 3 (giving an intercept of 6 and calculating $e^6 = 403.4$). The values of 449.1 and 1796 were obtained from the lowest threshold in the two-way joining Cluster Analysis results of Fig 2.3. The value of 1076 was arbitrarily chosen (almost as a midpoint), while the value of 2252 was taken from the results of the entropy method (see Chapter 4 and Appendix C) at $k = 6$. The values of 1296, 1591 and 1862 were as a direct result from the POTsp methodology.

Using Table 3.5, the following graphs were produced:

Fig 3.16 a) indicates the γ increases after $t > 878$ GWh, with a marked kink at 1862 GWh, before rising.

The kink is also evident in Fig 3.16 b) with a decrease in MEF at $t = 1862$ GWh

The location parameter also drops at this level. These kinds of effects seem to be indicative that the parameters yielded from using $t = 1862$ GWh would be the ones to use as a preferred choice, i.e.

Shape	Scale	Location
γ	σ	u
0.53903737	311.70399	242.219593

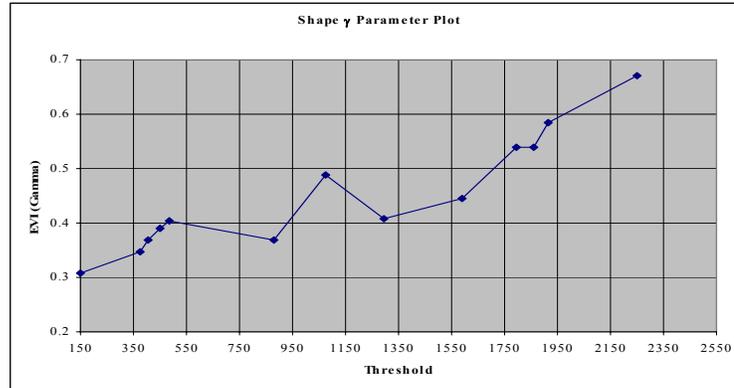


Fig 3.16 a) : EVI, γ at various threshold levels

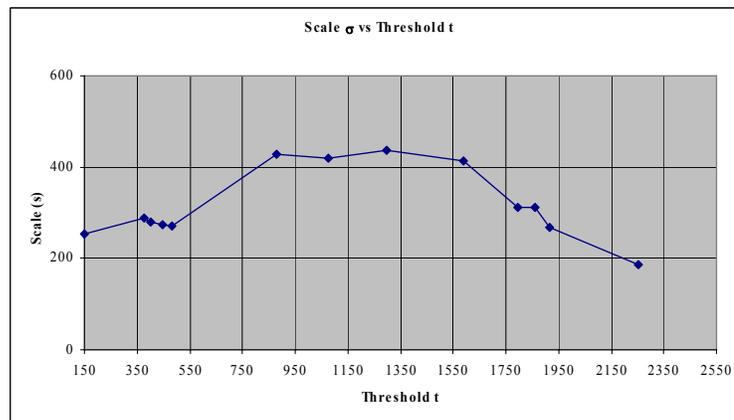


Fig 3.16 b): EVI, σ at various threshold levels

3.3.2.2 GWh Quantile Model

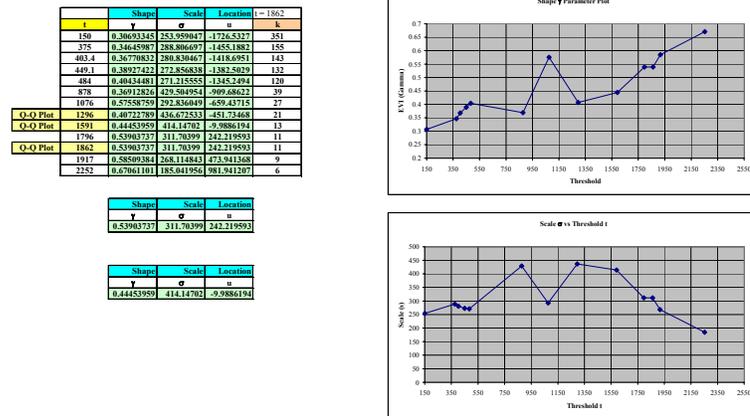


Fig 3.17: EVI, σ at various threshold levels – 3LM (Known Threshold)

Fig 3.17 indicates that the parameter estimates, when the thresholds are known, differ substantially, but are still in concordance with results obtained from the POTsp. The shift occurs in that thresholds below 1000 GWh do not seem plausible, and that parameters associated with a threshold of 1591 GWh (also a value from the Q-Q plot) seem more plausible. Therefore the following values were adopted:

Shape	Scale	Location
γ	σ	u
0.44453959	414.14702	-9.9886194

Now, one may make usage of Eq 3.11:

$$\hat{x}_q = t + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{n(1-q)}{N_t} \right)^{-\hat{\gamma}} - 1 \right]$$

where $P(X > t) > p$ and $P(X > t)$ is estimated by the sample proportion exceeding t .

Unfortunately, the parameters above yielded a poor fit. The parameters were solved by a squared error (keeping the threshold constant and adding the last percentile) minimizing algorithm that yielded the following new parameters:

n	928			
		Shape	Scale	Location
Nt		γ	σ	u
13		0.3964544	756.88837	1591
		0.4445396	414.14702	1591

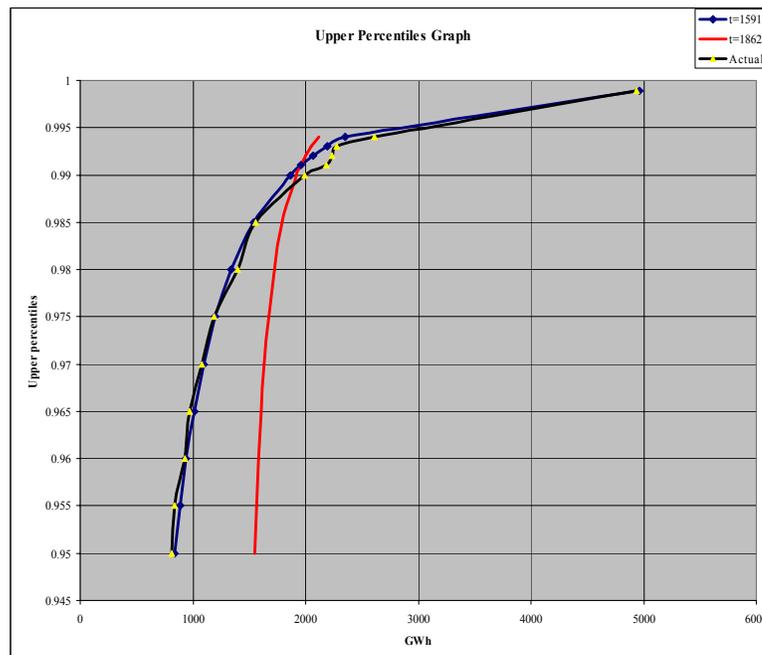


Fig 3.18: Upper Percentiles; re-parameterisation $N_t = 13$

	Shape	Scale	Location
N_t	γ	σ	u
11	0.2801847	908.44831	1841.8416
	0.5390374	311.70399	1862

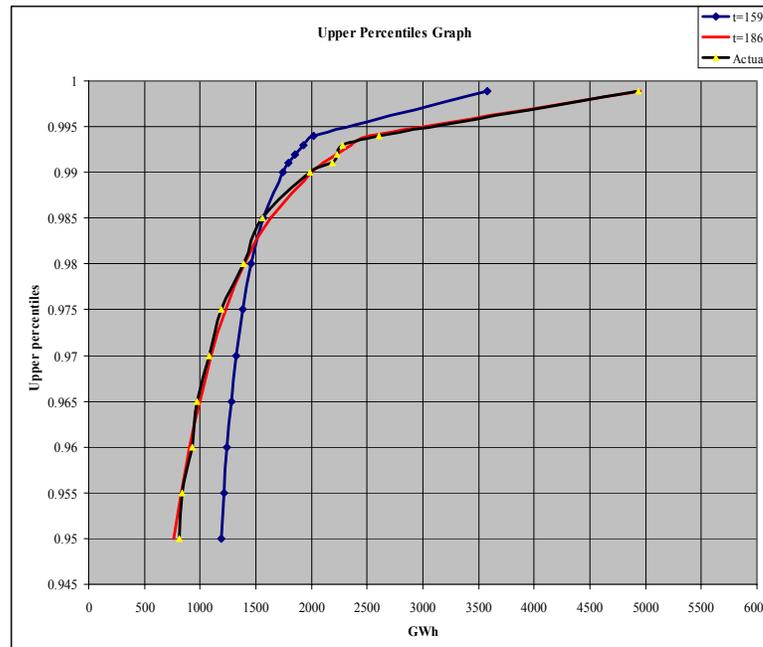


Fig 3.19: Upper Percentiles; re-parameterisation $N_t = 11$

For $N_t = 13$ (giving a min of 756.8 GWh), the fit for the model with a threshold of 1591 when re-parameterised is shown in Fig 3.18 (blue line) while the model with a threshold of 1862 was kept with the original parameters (red line), for comparative reasons. The actual, empirical percentiles are given by the black and yellow curve. The

necessity for adjusting the parameters is evident. Using the same algorithm, the model with the 1862 threshold did not perform as well. By contrast when reducing N_t to 11, it (the red line) performed much better (Fig 3.19) than the model with the 1591 threshold; the latter was then fixed with its original parameters for comparative reasons. From Eq 3.10, the final adopted model for the GWh Loss quantiles is:

$$\hat{x}_q = 1841.8 + \frac{908.5}{0.2802} \left[\left(\frac{928(1-q)}{11} \right)^{-0.2802} - 1 \right]$$

Eq 3.12
for GWh Losses above 765.8 GWh.

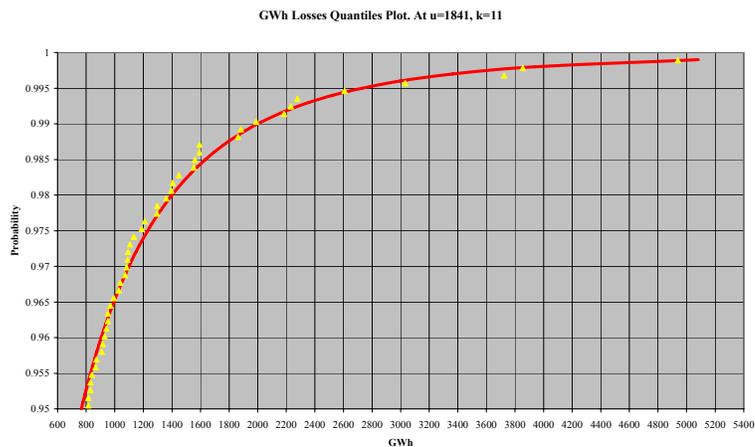


Fig 3.20: GWh Losses Quantiles

The Eq 3.12 can be expressed in graphical form as shown in Fig 3.20 and may be used as follows: for a GWh Loss greater than 2700 GWh, reading off the graph (or using Table 3.6 below for more exact values), there is a $(1 - 0.995) = 0.005$ chance of occurrence; now, for a fleet of 64 GUs one would expect to see a GU with such a loss, or greater, once every 3.125 years $(1/[0.005 \times 64])$. On the average, this seems consistent with the observations in Table 2.4.

γ	σ	u
0.28018471	908.448309	1841.84157

Percentile	GWh Loss	Percentile	GWh Loss	Percentile	GWh Loss
0.95	765.76	0.967	1033.22	0.984	1580.47
0.951	778.05	0.968	1054.29	0.985	1634.87
0.952	790.67	0.969	1076.23	0.986	1694.11
0.953	803.64	0.97	1099.08	0.987	1759.04
0.954	816.96	0.971	1122.94	0.988	1830.70
0.955	830.66	0.972	1147.87	0.989	1910.44
0.956	844.75	0.973	1173.97	0.99	2000.05
0.957	859.26	0.974	1201.34	0.991	2101.93
0.958	874.21	0.975	1230.09	0.992	2219.44
0.959	889.62	0.976	1260.35	0.993	2357.44
0.96	905.51	0.977	1292.27	0.994	2523.30
0.961	921.93	0.978	1326.01	0.995	2728.95
0.962	938.90	0.979	1361.79	0.996	2995.37
0.963	956.44	0.98	1399.81	0.997	3364.37
0.964	974.60	0.981	1440.34	0.998	3937.62
0.965	993.42	0.982	1483.70	0.999	5081.85
0.966	1012.95	0.983	1530.26		

Table 3.6: Percentiles for GWh Losses–Final Adopted Model

These satisfactory findings conclude the work in this Chapter.

CHAPTER 4

Bayesian Approach to the GPD Fit

4.1 Introduction

The workings in this Chapter utilise extensively de Waal's contribution in [2] Beirlant, Chapter 11.

After using LM method to estimate the GPD parameters, such as the EVI and estimating the threshold t , one ought to consider that the EVI would have a confidence interval (in the classical frequentist terminology) and hence the results obtained in Chapter 3, paragraph 3.3.2.2, would not be sufficient: a confidence band or region ought to be determined.

However, with reference to the classical sense, in obtaining a $(1 - \alpha)\%$ confidence interval, one might be solving a different issue, since, from the author's philosophical perspective, it is difficult to conceptualise repeatability when events are supposed to be rare; in this classical sense the "IF the experiment could be repeated" is a big "if", and in the author's belief, an assumption on the prior is far more plausible than a big "IF".

One might need to answer what is the probability distribution of the worst GWh losses that would be observed in 20xx. This refers to a predictive distribution of an unobserved variable. Hence a predictive probability

would have to be constructed for 20xx conditional on the event of, say, a “new” catastrophic loss would happen. It is not evident that this issue may be solved by a classical approach; however by using a Bayesian approach, one may define the issue as follows.

Let the GWh Loss be represented by the dataset $X = (x_1, x_2, \dots, x_n)$ and be modelled by the conditional predictive distribution $f_X [x|(\gamma, \sigma)]$, essentially this is what was done in Chapter 3 and $f_X [x|(\gamma, \sigma)]$ is also referred to as the Likelihood of (γ, σ) .

Let $\pi [(\gamma, \sigma) | X]$ be the posterior density of the parameters (γ, σ) given the past data X .

Let $\pi (\gamma, \sigma)$ be the prior denoting the density of the parameters.

Now, the Likelihood of (γ, σ) ,

$$f_X [x|(\gamma, \sigma)] = \prod_{i=1}^n f_X [x_i|(\gamma, \sigma)], \text{ assuming that the GWh}$$

losses are independent. According to Bayes' Theorem:

$$\pi [(\gamma, \sigma) | X] = \frac{f_X(x | \gamma; \sigma) \pi(\gamma; \sigma)}{\int_{\Omega} f_X(x | \gamma; \sigma) \pi(\gamma; \sigma) d(\gamma; \sigma)}, \quad \text{Eq 4.1}$$

where Ω is the parameters' space

Now the denominator:

$$\int_{\Omega} f_X(x | \gamma; \sigma) \pi(\gamma; \sigma) d(\gamma; \sigma) = \text{constant}$$

Therefore Eq 4.1 can be expressed as (the symbol \propto means "proportional to"):

$$\pi [(\gamma, \sigma) | X] \propto \pi (\gamma; \sigma) \times f_X [x|(\gamma, \sigma)] \quad \text{Eq 4.2}$$

i.e. **Posterior Density \propto Prior Density x Likelihood**

Estimates of γ , σ can be obtained from the mode, median or mean of the Posterior.

The credibility around these estimates can be described by the Posterior itself in terms of the “**highest posterior density (hpd) region**”, according to a certain probability $(1 - \alpha)$, being the hpd region which will contain $100(1 - \alpha)\%$ of the values, with no need to fall back into asymptotic theory (as in the classical way when obtaining confidence intervals).

Another attractive aspect is the ease of prediction: if X_{n+1} is a future prediction with density $f_X [x_{n+1} | (\gamma, \sigma)]$, then the predictive distribution, over the parameter space Ω , is given by:

$$f_X [x_{n+1} | X] = \int_{\Omega} f_X [x_{n+1} | (\gamma, \sigma)] \cdot \pi [(\gamma, \sigma) | X] d(\gamma, \sigma),$$

Hence this predictive density reflects its uncertainties through the future observations’ uncertainties and the ones of the Posterior.

This is excellent logic in approaching the challenge, measures ahead than the classical approach, however the million dollar question hinges around the Prior: which prior one chooses á-priori? When calling onto a prior density by some means of information or supposition, the process is called elicitation.

For the estimation of the γ and σ parameters and in the elicitation of the prior, the variance-covariance matrix of $(\hat{\gamma}, \hat{\sigma})$ is approximated by using the sample Fisher-Information Matrix (FIM), which in turn is used to define Jeffreys’ prior, $J(\gamma, \sigma)$.

$$J(\gamma, \sigma) \propto \sqrt{|I(\gamma, \sigma)|}, \text{ where } I(\gamma, \sigma) \text{ is the FIM with}$$

$$I(\theta) = E \left\{ \frac{\partial^2 \ln f_X(X|\theta)}{\partial^2 \theta} \right\}, \text{ where } \theta \text{ is the distribution's}$$

parameters vector.

Jeffreys' prior is considered the standard starting rule for an objective Bayesian analysis.

Another prior is the Maximal Data Information (MDI) prior by [43] Zellner, designed to provide maximal average data information on the γ and σ parameters, and is defined as:

$$\pi(\gamma; \sigma) \propto \exp \{ E[f_X(X|\gamma; \sigma)] \}$$

In this chapter we will address the fit of the Log-Normal and the GPD to the GWh losses using MCMC. The prior on the two parameters that we will consider will be an objective prior, namely the MDI prior by Zellner (1977) (see bottom of page 447). A big advantage of the Bayesian approach is that confidence intervals on the parameters are easily to establish and also the prediction of high quantiles with confidence limits are easy to compute.

Let us begin with a preamble resulting from the works of [23] Kedem et al.

Let X represent the GWh Losses and let $X(\omega)$ be the r.v. with a distribution that indicates a GU not failing with probability $1 - p$ and within this event, it admits a continuum of GWh Losses. Therefore, if $G_X(x)$ denotes the distribution function of X , then it is of the mixed type resulting in the following:

$$G_X(x) = (1 - p) H_X(x) + p F_X(x),$$

where $H_X(x) = 1$ and $F_X(x) = 0$ if $x = 0$ and

$$H_X(x) = 0 \text{ and } F_X(x) = F_X(x) \text{ if } x > 0$$

with $H_X(x)$ being discrete and $F_X(x)$ being continuous and p representing the probability of a GU failing.

To establish a linear relationship between X 's expectation **and** the expected value of an integrable function of X , we proceed as follows:

Let $\varphi(X)$ be an arbitrarily integral function of X . Then:

$$E[\varphi(X)] = (1 - p) \varphi(0) + p E[\varphi(X) | X > 0] \quad \text{Eq 4.3}$$

In particular for $\varphi(X) = X$, Eq 4.3 results in:

$$E[X] = p E[X | X > 0] \quad \text{Eq 4.4}$$

$$\text{from Eq 4.4, } p = E[X] / E[X | X > 0] \quad \text{Eq 4.5}$$

substituting p in Eq 4.3 :

$$E[\varphi(X)] = \left(1 - \frac{E[X]}{E[X | X > 0]}\right) \varphi(0) + \frac{E[X]}{E[X | X > 0]} E[\varphi(X) | X > 0]$$

Solving for $E[X]$, we get:

$$E[X] = \frac{E[X | X > 0]}{E[\varphi(X) | X > 0] - \varphi(0)} \{E[\varphi(X)] - \varphi(0)\}$$

$$E[X] = \beta_\varphi \{E[\varphi(X)] - \varphi(0)\} \quad \text{Eq 4.6}$$

whereby β_φ now becomes the slope of the linear relationship between $E[X]$ and $E[\varphi(X)]$; this slope only depends on the continuous part of the distribution of X and $\varphi(0)$, hence the slope is independent of the probability of a GU failing, it depends only on the GWh Losses' distribution i.e. $F_X(x)$, assuming that it exists, and if $\varphi(0) = 0$, which means that then there is no intercept in Eq 4.6.

Let us now fix a time τ and let $X_\tau(a)$ be a r.v. that yields a GWh Loss at time τ . Again, $X_\tau(a)$ would have a mixed distribution governed by p_τ the probability of a GU failing at time τ and its losses behaving as $f_{X_\tau}(x_\tau)$.

Equation Eq 4.6 can now be modified as:

$$E[X_\tau] = \beta_\phi(\tau) \{E[\phi(X_\tau)] - \phi(0)\}, \quad \text{Eq 4.7}$$

$$\text{where, } \beta_\phi(\tau) = \frac{E[X_\tau | X_\tau > 0]}{E[\phi(X_\tau) | X_\tau > 0] - \phi(0)} \quad \text{Eq 4.8}$$

But now, $\beta_\phi(\tau)$ depends on τ . By making use of the simplifying homogeneity assumption, we assume that $\beta_\phi(\tau)$ is independent of τ . The homogeneity assumption would state that the continuous part of the distribution of the GWh Losses is homogeneous in the time dimension: i.e. $\forall \tau, f_{X_\tau}(x) = f_X(x)$. No similar assumption was made on p_τ .

$$p_\tau \Rightarrow \beta_\phi(\tau) = \beta_\phi. \quad \text{Eq 4.9}$$

However, there is an underlying assumption that the failure rates (linked to p_τ) are not homogeneous with time, i.e. p_τ might be smaller than $p_{\tau+\kappa}$.

Let \bar{X}_τ and $\overline{\phi(X_\tau)}$ represent the sample averages obtained at time τ , and let t represent a threshold such that:

$$\begin{aligned} \phi(x) &= 1, & x > t \\ \phi(x) &= 0, & x \leq t \end{aligned} \quad \text{Eq 4.10}$$

then, $\phi(0) = 0$, $E[\phi(X_\tau)] = P(X_\tau > t)$

From Eq 4.7, Eq 4.8 and Eq 4.9

$$E[X_\tau] = \beta_\phi(t) P(X_\tau > t) \quad \text{Eq 4.11}$$

and under homogeneity conditions,

$$\beta_\phi(t) = \frac{E[X | X > 0]}{P(X > t) | X > 0} \quad \text{Eq 4.12}$$

This means that now $\beta_\phi(t)$ depends only on $f_X(x)$ and t and not on time τ .

Let $I[X_\tau > t]$ be the indicator function of the event $X_\tau > t$, then $\langle I[X_\tau > t] \rangle$ is denoted as the average number of GUs failing per period τ above a critical level t of the GWh Losses (this can be estimated by counting the cells with an event from table 2.4 in Chapter 2, after choosing a certain critical level t and dividing it by the ave. No. of total GUs p.a.).

Since \bar{X}_τ is the approximation of $E[X_\tau]$ and $\langle I[X_\tau > t] \rangle$ is the approximation of $P(X_\tau > t)$, then from Eq 4.11

$\bar{X}_\tau \cong \beta_\varphi(t) \langle I[X_\tau > t] \rangle$, where $\beta_\varphi(t)$ is a constant for each critical level t .

The linear relationship in Eq 4.12 indicates that one may expect a high correlation between the average GWh Losses and the average number of GUs failing, then the question arises “but at what level of t ?”.

Eq 4.12 starts to offer a direction in the provision of an answer. If t can be chosen so as to minimise the variance of the MLE of $\beta_\varphi(t)$ under an appropriate choice of $f_X(x)$ then the answer to the question above would be provided. As noted in [23] Kedem et al, since the study centers on Eq 4.10, the notation on the slope changes to focus more on the vector parameter θ stemming from the choice of $f_X(x)$. In this case $\beta_\varphi(t) \equiv \beta_\theta(t)$. Eq 4.13

The process would then be to fix a threshold t and then derive the MLE of $\beta_\theta(t)$ under the choice of $f_X(x)$. Note the change in the notation from φ to θ . From the MLE theory:

$$\sqrt{n} (\hat{\theta} - \theta) \xrightarrow{L} N[\mathbf{0}; \mathbf{I}^{-1}(\theta)] \quad \text{Eq 4.14}$$

where $\mathbf{I}(\theta)$ is the Fisher Information Matrix (see Appendix C, paragraph 3.1 and paragraph 3.2 for the Delta-Method) and assessed with the choice of $f_X(x)$.

The asymptotic distribution of $\beta_{\hat{\theta}}(t)$ is obtained by invoking the Delta-Method and is expressed by:

$$\sqrt{n} (\beta_{\hat{\theta}}(t) - \beta_{\theta}(t)) \xrightarrow{L} N[\mathbf{0}; \nu_{\theta}(t)] \quad , n \rightarrow \infty \quad \text{Eq 4.15}$$

where for a 2-parameter pdf (i.e. $\theta = (\theta_1; \theta_2)$ see Eq C3.26 Appendix C),

$$\nu_{\theta}(t) = \begin{pmatrix} \frac{\partial \beta}{\partial \theta_1} & \frac{\partial \beta}{\partial \theta_2} \end{pmatrix} \mathbf{I}^{-1}(\theta) \begin{pmatrix} \frac{\partial \beta}{\partial \theta_1} \\ \frac{\partial \beta}{\partial \theta_2} \end{pmatrix} \quad \text{Eq 4.16}$$

4.2 The Fit of the Tail – Log Normal and GPD

4.2.1 Log Normal

Let us assume that as a choice of pdf for the GWh Losses, the Log-Normal distribution is selected (this is not an Extreme Value distribution). As expressed in the paragraph above Eq 4.3, the GWh Losses represented by X are essentially positive; hence the assumption of Log-Normal behaviour in this variable is not far-fetched; the example here is used to illustrate the position of the threshold if using this assumption (see Fig 1.2).

In this case then: $\theta = \begin{pmatrix} \theta_1 = \mu \\ \theta_2 = \sigma \end{pmatrix}$ and

$$f_X(x; \theta) = \frac{1}{\sqrt{2\pi} \sigma x} e^{-\frac{(\ln(x)-\mu)^2}{2\sigma^2}}, x > 0, -\infty < \mu < \infty, \sigma > 0$$

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n \ln(X_i) \quad \text{and} \quad \hat{\sigma}^2 = \frac{1}{n-1} \sum_{i=1}^n \{\ln(X_i) - \hat{\mu}\}^2$$

$$E[X | X > 0] = e^{\left(\mu + \frac{\sigma^2}{2}\right)} \quad \text{and} \quad P(X > t) = 1 - \Phi\left[\frac{\ln(t) - \mu}{\sigma}\right]$$

and $\phi\left[\frac{\ln(t) - \mu}{\sigma}\right]$ is the density of the Standard Normal

distribution. While $\Phi\left[\frac{\ln(t) - \mu}{\sigma}\right]$ is the distribution function of the Standard Normal.

In essence, as mentioned in the paragraph above, the derivation of an “optimal” t , that gauges the average GWh Losses and the average number of GUs failing, can now be assessed. To enable us to do that we need to derive the MLE $\beta_{\hat{\theta}}(t)$ from the GWh Losses data set. From Eq 4.12 and Eq 4.13 above:

$$\beta_{\theta}(t) = \frac{E[X | X > 0]}{P(X > t) | X > 0} = \frac{e^{\left(\mu + \frac{\sigma^2}{2}\right)}}{1 - \Phi\left[\frac{\ln(t) - \mu}{\sigma}\right]} \quad \text{Eq 4.17}$$

or, as estimates from the dataset:

$$\beta_{\hat{\theta}}(t) = \frac{E[X | X > 0]}{P(X > t) | X > 0} = \frac{e^{\frac{(\hat{\mu} + \hat{\sigma}^2)}{2}}}{1 - \Phi\left[\frac{\text{Ln}(t) - \hat{\mu}}{\hat{\sigma}}\right]}$$

The matrix $\mathbf{I}^{-1}(\theta)$ derived from inverting Eq C3.6 in Appendix C yields:

$$\mathbf{I}^{-1}(\theta) = \begin{bmatrix} \sigma^2 & 0 \\ 0 & \frac{\sigma^2}{2} \end{bmatrix}$$

Then from the Delta Method (see Appendix C & paragraph 3.2) and Eq 4.15, Eq 4.16:

$$\begin{aligned} v_{\theta}(t) &= \begin{pmatrix} \frac{\partial \beta}{\partial \mu} & \frac{\partial \beta}{\partial \sigma} \end{pmatrix} \mathbf{I}^{-1}(\theta) \begin{pmatrix} \frac{\partial \beta}{\partial \mu} \\ \frac{\partial \beta}{\partial \sigma} \end{pmatrix} \\ &= \sigma^2 \left[\left(\frac{\partial \beta}{\partial \mu} \right)^2 + \frac{1}{2} \left(\frac{\partial \beta}{\partial \sigma} \right)^2 \right] \end{aligned} \quad \text{Eq 4.18}$$

from Eq 4.17:

$$\begin{aligned} \frac{\partial \beta_{\theta}(t)}{\partial \mu} &= \\ &= \frac{e^{\frac{(2\mu + \sigma^2)}{2}}}{\left(1 - \Phi\left[\frac{\text{Ln}(t) - \mu}{\sigma}\right]\right)^2} \cdot \left\{ 1 - \Phi\left[\frac{\text{Ln}(t) - \mu}{\sigma}\right] - \frac{1}{\sigma} \phi\left[\frac{\text{Ln}(t) - \mu}{\sigma}\right] \right\} \end{aligned}$$

$$\begin{aligned} \therefore \left(\frac{\partial \beta_\theta(t)}{\partial \mu} \right)^2 &= \\ & \left(\frac{e^{\frac{(2\mu+\sigma^2)}{2}}}{\left(1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right]\right)^2} \right)^2 \cdot \left\{ 1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right] - \frac{1}{\sigma} \phi\left[\frac{Ln(t)-\mu}{\sigma}\right] \right\}^2 \end{aligned}$$

Eq 4.19

Similarly,

$$\begin{aligned} \frac{\partial \beta_\theta(t)}{\partial \sigma} &= \\ & \frac{e^{\frac{(2\mu+\sigma^2)}{2}}}{\left(1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right]\right)^2} \cdot \left\{ 1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right] - \frac{1}{\sigma} \left\{ \frac{Ln(t)-\mu}{\sigma} \right\} \phi\left[\frac{Ln(t)-\mu}{\sigma}\right] \right\} \\ \therefore \left(\frac{\partial \beta_\theta(t)}{\partial \sigma} \right)^2 &= \\ & \left(\frac{e^{\frac{(2\mu+\sigma^2)}{2}}}{\left(1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right]\right)^2} \right)^2 \cdot \left\{ 1 - \Phi\left[\frac{Ln(t)-\mu}{\sigma}\right] - \frac{1}{\sigma} \left\{ \frac{Ln(t)-\mu}{\sigma} \right\} \phi\left[\frac{Ln(t)-\mu}{\sigma}\right] \right\}^2 \end{aligned}$$

Eq 4.20

Hence, now $\nu_\theta(t)$ may be computed from Eq 4.18, by using Eq 4.19 and Eq 4.20

In [23] Kedem et al, the authors have show that the minimum of $\nu_\theta(t)$ exists, hence from the computations' results, Fig 4.1 was obtained.

The graph is similar to the one of [23] Kedem et al. It reflects that the minimum is at $t = 484$ GWh Loss.

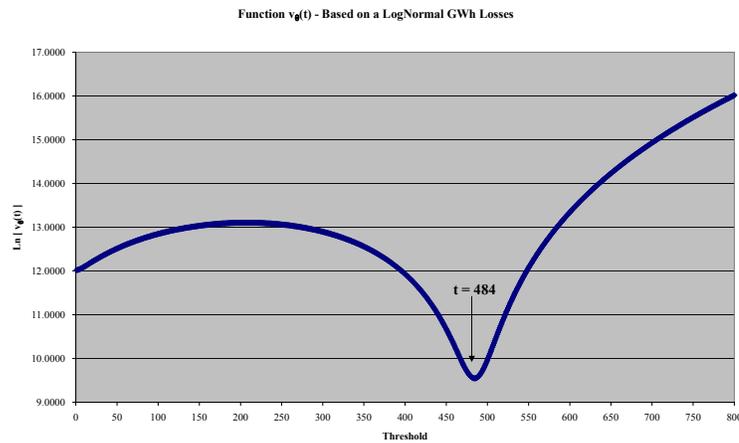


Fig 4.1: Log of variance vs Threshold: min @ 484 GWh Loss

$$\begin{aligned} \mu &= 4.6640 \\ \sigma &= 1.2725 \\ E[X] &= 238.34 \\ P[X > t] &= 0.1163 \\ \text{Min Ln } v_{\theta} &= 9.55 \\ \text{Min } v_{\theta} &= 14,004 \\ t_{\min} &= 484 \\ \beta_{\theta}(t) &= 2049 \end{aligned}$$

This value of 484 GWh answers the question posed in Chapter 2, just above and in relation to Eq 2.2, i.e. on how the individual GU's Losses affect the System. It seems that

according to this method and results, the individual GUs' losing more than 484 GWh in a year affect the System in that year. This has a bearing on fig 3.2 of the System Yearly Maxima (Gumbel), in Chapter 3.

The GWh losses at or below 484 GWh may be considered as "background-noise" losses.

As a subjective interpretation, the analysis appears to indicate that the slope "stretches" to a value of 2049 GWh (see Eq 4.17). This value could also indicate that the tail deviates from the Log-Normal after the 9th largest observation.

4.2.2 Generalised Pareto Distribution (GPD)

In a similar way as in paragraph 4.2.1, let us now assume that after using an initial threshold of 484 GWh we wish to fit a distribution to the tail. We can use the method by [23] Kedem et al.

In this case then: $\theta = \begin{pmatrix} \theta_1 = \gamma \\ \theta_2 = \sigma \end{pmatrix}$ and $y = t - u > 0$ for $\gamma > 0$

$$F_Y(y; \theta) = 1 - \left[1 + \frac{\gamma(t-u)}{\sigma} \right]^{-\frac{1}{\gamma}}, \quad y > u, \quad \sigma > 0$$

Since

$$P(Y \leq t | y > u) = F_Y(y; \theta) \quad P(Y > t | y > u) = 1 - F_Y(y; \theta)$$

$$\therefore P(Y > t | y > u) = \left[1 + \frac{\gamma(t-u)}{\sigma} \right]^{-\frac{1}{\gamma}} = \mathcal{P} \quad \text{Eq 4.21}$$

$$\begin{aligned}
\text{Ln } \mathcal{P} &= -\frac{1}{\gamma} \text{Ln} \left\{ 1 + \frac{\gamma(t-u)}{\sigma} \right\} \\
\Rightarrow \frac{\partial}{\partial \mathcal{P}} \text{Ln } \mathcal{P} &= \frac{1}{\mathcal{P}} \quad \Rightarrow \partial \mathcal{P} = \partial \text{Ln } \mathcal{P} \cdot \mathcal{P} \\
\frac{\partial}{\partial \gamma} \mathcal{P} &= \frac{\partial}{\partial \gamma} \text{Ln } \mathcal{P} \cdot \mathcal{P} = \frac{\partial}{\partial \gamma} \left[-\frac{1}{\gamma} \text{Ln} \left\{ 1 + \frac{\gamma(t-u)}{\sigma} \right\} \right] \cdot \left[1 + \frac{\gamma(t-u)}{\sigma} \right]^{-\frac{1}{\gamma}} \\
\therefore \frac{\partial}{\partial \gamma} \mathcal{P} &= \left[1 + \frac{\gamma(t-u)}{\sigma} \right]^{-\frac{1}{\gamma}} \cdot \left[-\frac{1}{\gamma} \frac{(t-u)}{\sigma} \left[1 + \frac{\gamma(t-u)}{\sigma} \right]^{-1} + \frac{1}{\gamma^2} \text{Ln} \left\{ 1 + \frac{\gamma(t-u)}{\sigma} \right\} \right]
\end{aligned}$$

Eq 4.22

$$E[Y > 0 | y > u] = \xi = \frac{\sigma + \gamma u}{1 - \gamma} \quad \text{Eq 4.23}$$

(see Table A1.1 in Appendix A)

$$\therefore \frac{\partial \xi}{\partial \gamma} = \frac{\partial}{\partial \gamma} \left(\frac{\sigma + \gamma u}{1 - \gamma} \right) = \frac{\sigma + u}{(1 - \gamma)^2} \quad \text{Eq 4.24}$$

By using equations Eq 4.21 to Eq 4.24 and the quotient rule of differentiation on

$$\beta_{\theta}(t) = \frac{E[Y > 0 | y > u]}{P(Y > t | y > u)} \quad (\text{see Eq 4.17 above}) \quad \text{to get the}$$

partial derivative $\frac{\partial \beta_{\theta}(t)}{\partial \gamma}$, we obtain:

$$\frac{\partial \beta_{\theta}(t)}{\partial \gamma} = \left(1 + \gamma \frac{t-u}{\sigma} \right)^{\frac{1}{\gamma}} \left[\frac{\sigma + u}{(1 - \gamma)^2} - \frac{\sigma + \gamma u}{1 - \gamma} \left\{ \frac{1}{\gamma^2} \text{Ln} \left\{ 1 + \gamma \frac{t-u}{\sigma} \right\} - \frac{1}{\gamma} \left(\frac{t-u}{\sigma} \right) \left(1 + \gamma \frac{t-u}{\sigma} \right) \right\} \right]$$

Eq 4.25

and

$$\frac{\partial \beta_{\theta}(t)}{\partial \sigma} = \left(1 + \gamma \frac{t-u}{\sigma}\right)^{\frac{1}{\gamma}} \left[(1-\gamma)^{-1} - \frac{\sigma + \gamma u}{1-\gamma} \left\{ \left(\frac{t-u}{\sigma^2}\right) \left(1 + \gamma \frac{t-u}{\sigma}\right)^{-1} \right\} \right]$$

Eq 4.26

The FIM for the GPD is (See Appendix C Eq 3.19)

$$[I(\gamma; \sigma)] = \begin{bmatrix} \frac{2}{(1-\gamma)(1-2\gamma)} & -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} \\ -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} & \frac{1}{\sigma^2(1-2\gamma)} \end{bmatrix} \quad \text{Eq 4.27}$$

$$[I(\sigma; \gamma)] = \begin{bmatrix} \frac{1}{\sigma^2(1-2\gamma)} & -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} \\ -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} & \frac{2}{(1-\gamma)(1-2\gamma)} \end{bmatrix} \quad \text{Eq 4.28}$$

The matrix $\mathbf{I}^{-1}(\theta)$ derived from inverting matrix Eq 4.27 above yields:

$$\begin{aligned} & \mathbf{I}^{-1}(\gamma; \sigma) \\ &= \begin{bmatrix} 2\sigma^2(1-\gamma) & -\sigma(1-\gamma) \\ -\sigma(1-\gamma) & (1-\gamma)^2 \end{bmatrix} \\ &= \sigma^2(1-\gamma)^2 \begin{bmatrix} \frac{2}{(1-\gamma)} & -\frac{1}{\sigma(1-\gamma)} \\ -\frac{1}{\sigma(1-\gamma)} & \frac{1}{\sigma^2} \end{bmatrix} \end{aligned}$$

Then from the Delta Method (see Appendix C & paragraph 3.2) and Eq 4.15, Eq 4.16:

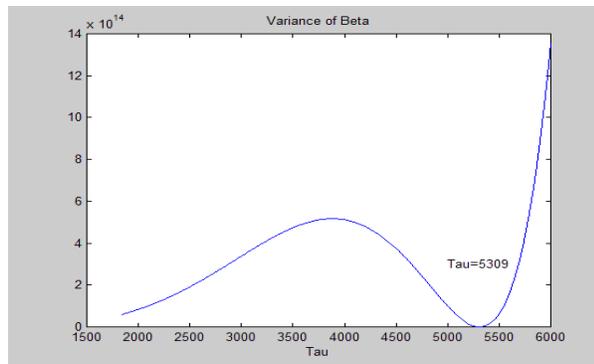
$$v_{\theta}(t) = \begin{pmatrix} \frac{\partial \beta}{\partial \gamma} & \frac{\partial \beta}{\partial \sigma} \end{pmatrix} \mathbf{I}^{-1}(\theta) \begin{pmatrix} \frac{\partial \beta}{\partial \gamma} \\ \frac{\partial \beta}{\partial \sigma} \end{pmatrix} \quad \text{Eq 4.29}$$

Corresponding to the variance of t .

Care ought to be taken when choosing the FIM on the sequence of the parameters, otherwise the threshold associated with the minimum variance level, might be underestimated. For instance if using Eq 4.28 the equation from the Delta Method becomes

$$v_{\theta}(t) = \begin{pmatrix} \frac{\partial \beta}{\partial \sigma} & \frac{\partial \beta}{\partial \gamma} \end{pmatrix} \mathbf{I}^{-1}(\theta) \begin{pmatrix} \frac{\partial \beta}{\partial \sigma} \\ \frac{\partial \beta}{\partial \gamma} \end{pmatrix} \quad \text{Eq 4.30}$$

Now if we consider taking the parameters for the GPD given in Table 3.6 (Chapter 3) and utilise the coding given in Fig 4.2 below, we obtain the graph shown in the same Fig 4.2; the results produce a threshold of 5309 GWh close to the maximum absolute expected loss of a 669 MW GU (5876.5 GWh, see p. 30).



```

%gpdtail2.m Mean of the GPD related to the tail probability
sig=908.5;xi=.2802;
T=[];
for u=1841
x=u:1:6000;
S=(1+xi*(x-u)/sig).^(-1/xi);
I=[1/sig^2/(1+2*xi) -1/sig/(1+2*xi)/(1+xi)
  -1/sig/(1+2*xi)/(1+xi) 2/(1+2*xi)/(1+xi)];
V=[];
for tau=u:1:6000
w=(sig+xi*u)/(1-xi);
v=(1+xi*(tau-u)/sig)^(-1/xi);
dwdg=((1-xi)*u+sig+xi*u)/(1-xi)^2;
dvdg=(1+xi*(tau-u)/sig)^(-1/xi)*(log(1+xi*(tau-
u)/sig)/xi^2-(1+xi*(tau-u)/sig)^(-1)*(tau-u)/sig/xi);
dwds=1/(1-xi);
dvds=(1+xi*(tau-u)/sig)^(-1-1/xi)*(tau-u)/sig^2;
c1=(v*dwdg-w*dvdg)/v^2;
c2=(v*dwds-w*dvds)/v^2;
varb=[c1 c2]*inv(I)*[c1 c2]';
V=[V varb];
end
tau=u:1:6000;
[d1 d2]=min(V);
P=(1+(tau(d2)-u)*xi/sig)^(-1/xi);
mef=(sig+xi*u)/(1-xi);
beta=mef/P;
T=[T; u tau(d2) beta V(d2)];
end
plot(tau,V)
title('Variance of Beta')
text(5000,3*10^14,['Tau=',num2str(T(:,2))])
xlabel('Tau'); text

```

Fig 4.2 Graph and Coding for the GPD–Min Variance β

The fit of the tail of a distribution onto a GPD depends on selecting a threshold t . A simple method of selecting the threshold is by inspecting the Pareto quantile plot (Fig 3.7) where the graph tends to be linear. A possible candidate seems to be $e^6 = 403.43$. The threshold from the lognormal fit in paragraph 4.2.1 gave a threshold of $t = 484$ where the variance of the estimate of the regression of the mean on the tail probability is at minimum. This is close to visual selected threshold (6.1821 vs 6).

When dealing with the tail of the distribution of a r.v. behaviour over a threshold, the GPD is usually the model of choice. The minimum variance value, derived from the GPD using [23] Kedem methodology, namely $t = 2126$ is chosen with $\gamma = 0.2802$ and $\sigma = 512.3$

The joint posterior density of the two parameters γ and σ is given by:

$$\pi(\gamma, \sigma | \text{data}) \propto \text{Likelihood} \times \text{prior}$$

where the Likelihood and MDI prior are respectively given by [2] Beirlant et al p 447:

$$L(\gamma, \sigma | \text{data}) = \prod_{i=1}^n \left(\frac{1}{\sigma} \right)^n \left(1 + \frac{\gamma y_i}{\sigma} \right)^{-\frac{1}{\gamma}-1} \text{ and}$$

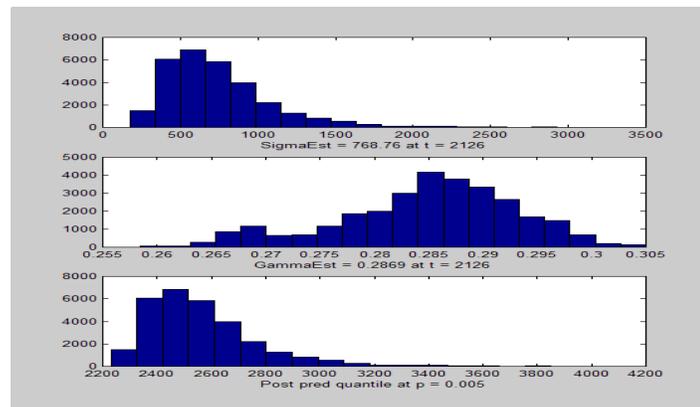
$$p^*(\gamma; \sigma) = \frac{1}{\sigma} e^{-\gamma}$$

A subjective prior can be elicited from experience, but we will stick to the objective prior. Other priors such as Jeffreys prior (see Eq C3.20 in Appendix C) is a popular prior, but it is restricted to $\gamma < 0.5$ and tends to pull the estimate of γ towards zero, hence the choice of the MDI prior.

Starting the Markov process with initial values $\gamma = 0.2802$ and $\sigma = 908.5$, the process was run for 30000 iterations. The convergence was found to be good. The final posterior distributions are given in Fig 4.3 below, which includes the code. The estimates from the simulations are obtained as $\hat{\gamma} = 0.2869$ $\hat{\sigma} = 768.76$.

The 95% hpd region for the GWh Losses based on a GPD with the parameters estimates above and on a threshold of 2126 GWh is: [2343.3 ; 3090.5]

The methodology used and the coding supplied in Fig 4.3 provide the technique in the paragraph following, i.e. the prediction of High Quantiles through Markov Chain Monte Carlo (MCMC).



```
%gpdvnce1.m Fit a GPD to GU energy loss data GHWloss1.m
```

```
GHWloss1
t=2126;r=find(L2>t);
n=length(r);ntot=length(L2);
x=sort(L2(r))-t;alpha=512.3;xi=.2802;
I=0;X=[];
for i=1:30000
    lpost=-(1+1/xi)*sum(log(1+xi*x/alpha))-(n+1)*log(alpha)-
    xi;
    alphas=exp(.04*randn(1,1)+log(alpha));xis=.0004*randn(1,1)+
    xi;
    lposts=-(1+1/xis)*sum(log(1+xis*x/alphas))-
    (n+1)*log(alphas)-xis;
    if rand(1,1)<exp(lposts-lpost)
        alpha=alphas;xi=xis;
        I=I+1;
    end
    X=[X;[alpha xi]];
end
alpha=mean(X(5000:30000,1))
xi=mean(X(5000:30000,2));n;ntot
p=0.005;m=n/(ntot.*p)
subplot(3,1,1); hist(X(:,1),20)
xlabel('Sigma');subplot(3,1,2)
hist(X(:,2),20);xlabel('Gamma')
U=X(:,1).*(m.^X(:,2)-1)./X(:,2)+t;
subplot(3,1,3)
hist(U,20);xlabel('Post pred quantile at p=.005')
G=zeros(length(x),1);subplot(111)
```

Fig 4.3 Graphs and Coding for the GPD – Posterior

4.3 Predicting High Quantiles through MCMC

The prediction of high quantiles forms a very necessary part of an extreme value analysis.

Assume that one would like to make inferences about future values of high quantiles. The predictive distribution is given below (see paragraph 4.1 above)

$$f_X(x_{n+1} | X) = \int_{\Omega} f_X(x_{n+1} | \gamma; \sigma) \pi(\gamma; \sigma | X) d(\gamma; \sigma) \quad \text{Eq 4.31}$$

This shows that the predictive density consists of the integration of the likelihood (of a single x , i.e. x_{n+1} , multiplied by the posterior.

From paragraph 4.2 above,

$$L(\gamma, \sigma | \text{data}) = \prod_{i=1}^n \left(\frac{1}{\sigma} \right)^n \left(1 + \frac{\gamma y_i}{\sigma} \right)^{-\frac{1}{\gamma}-1} \quad \text{and}$$

$$p^*(\gamma; \sigma) = \frac{1}{\sigma} e^{-\gamma}$$

Therefore using the two equations above, the following posterior is obtained:

$$\pi(\gamma; \sigma | X) = \prod_{i=1}^n \left(\frac{1}{\sigma} \right)^n \left(1 + \frac{\gamma y_i}{\sigma} \right)^{-\frac{1}{\gamma}-1} \cdot \frac{1}{\sigma} e^{-\gamma}, \quad \text{hence,}$$

taking logs:

$$\text{Ln} [\pi(\gamma; \sigma | X)] = -n \text{Ln}(\sigma) - \left(\frac{1}{\gamma} + 1 \right) \sum_{i=1}^n \text{Ln} \left[1 + \frac{\gamma y_i}{\sigma} \right] - \text{Ln}(\sigma) - \gamma$$

and re-arranging:

$$\text{Ln}[\boldsymbol{\pi}(\boldsymbol{\gamma}; \boldsymbol{\sigma} | X)] = (n+1) \text{Ln}(\boldsymbol{\sigma}) \left(\frac{1}{\boldsymbol{\gamma}} + 1\right) \sum_{i=1}^n \text{Ln} \left[1 + \frac{\boldsymbol{\gamma} y_i}{\boldsymbol{\sigma}}\right] - \boldsymbol{\gamma} \quad \text{Eq 4.32}$$

This equation of the log-posterior distribution is equivalent to the line “lpost” in the code in Fig 4.3 above.

The equation: $\hat{x}_q = t + \frac{\hat{\boldsymbol{\sigma}}}{\hat{\boldsymbol{\gamma}}} \left[\left(\frac{n(1-q)}{N_t} \right)^{-\hat{\boldsymbol{\gamma}}} - 1 \right]$ is re-arranged

as

$$\hat{x}_q = t + \frac{\hat{\boldsymbol{\sigma}}}{\hat{\boldsymbol{\gamma}}} \left[\left(\frac{N_t}{n(1-q)} \right)^{\hat{\boldsymbol{\gamma}}} - 1 \right]$$

Whereby, in the code of Fig 4.3, “m” = $\frac{N_t}{n(1-q)}$

and “n” = N_t and, still in the same code, “U” represents the predictive distribution derived from a whole set of \hat{x}_q ’s which are in turn derived from a whole set of $\hat{\boldsymbol{\sigma}}$ and $\hat{\boldsymbol{\gamma}}$ being simulated (“alphas” and “xis” respectively in the code)

Another way that this may also get a point-estimate through the formulae (see [2] Beirlant et al) is to estimate the percentiles, by letting z_p = upper p^{th} percentile of $\text{GPD}_{\boldsymbol{\gamma}, \boldsymbol{\sigma}}(x-t)$; then the estimate of z_p is:

$$\hat{x}_p = t + \frac{\hat{\boldsymbol{\sigma}}}{\hat{\boldsymbol{\gamma}}} \left[\left(\frac{P(X > t)}{p} \right)^{\hat{\boldsymbol{\gamma}}} - 1 \right] \equiv$$

$$\hat{x}_q = t + \frac{\hat{\boldsymbol{\sigma}}}{\hat{\boldsymbol{\gamma}}} \left[\left(\frac{n(1-q)}{N_t} \right)^{-\hat{\boldsymbol{\gamma}}} - 1 \right]$$

where the probability $P(X > t)$ is greater than a value p and $P(X > t)$ is estimated by the sample proportion exceeding t .

That is $P(X > t) = N_t / n$ and $p = (1 - q)$ and inverting by making the exponent γ negative.

Let us say for instance that we would like to position our threshold at the 99.05th percentile, this means that the sample proportion $[(n - N_t) / n] = 0.9905$, since $n = 928$, $N_t = 928 \cdot (1 - 0.9905) = 8.8$, i.e. we ought to have approx. 9 observations above our threshold.

By choosing 2126 GWh, there is consistency with the results in paragraph 4.2.2 as that is the point of minimum variance and by using the parameters $\hat{\gamma} = 0.2869$ $\hat{\sigma} = 768.76$

In the above equation, then we get:

$$\hat{x}_{0.9905} = 2126 + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{928(1 - 0.9905)}{9} \right)^{-\hat{\gamma}} - 1 \right] = 2141.9 \text{ GWh}$$

Let us now operate more into the tail, say at the 99.75th percentile, therefore expecting 2 or 3 observations at this level.

$$\hat{x}_{0.9975} = 2126 + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{928(1 - 0.9975)}{3} \right)^{-\hat{\gamma}} - 1 \right] = 2331.1 \text{ GWh}$$

From the simulations above on fitting the GPD (Fig 4.3), the predicted simulated distributions are shown in the graphs. There one may remark that the computations at $\hat{\sigma} = 768.76$ (the mode, in Fig 4.3) might have the tendency to underestimate the percentiles at the upper end of the tail (compare 2331.1 with the empirical 3724.6 at the 0.9970 percentile), therefore the value of 908.5 for sigma seems to be more appropriate. More experimenting on the sensitivity of the sigma (see coding in Fig 4.3 the value of 0.04 in “alphas”) would be necessary and then benchmark

to the Table 3.6 (derived from Eq 3.12). More research in this area is necessary.

4.4 Relationship between MEF and the Tail of the GPD

In paragraph 4.2.2, the relationship between the Mean Excess Function and the tail probability was shown in detail following the works of [23] Kedem et al.

There it was shown that there is a relationship between the Mean Excess Function (MEF)

$e_t = E[(X - t) | X > t]$ and the tail probability $p_t = P(X > \tau | X > t)$ for some threshold τ conditional that we only consider excess losses above t (= 484 GWh in our case).

The relationship that was considered was

$$e_t = E[X - t | X > t] = \beta_{\hat{\theta}}(t) \cdot P[X > \tau | X > t]$$

$$e_t = \beta_{\hat{\theta}}(t) \cdot p_t$$

As shown in Table A1.1 in Appendix A, that the mean

excess function for the GPD is given by $e_t = \frac{\sigma + \gamma t}{1 - \gamma}$,

following the arguments of [23] Kedem et al, by means of partial derivatives with respect to γ and σ respectively and using the Fisher Information Matrix and its inverse, as well as invoking the Delta Method, we obtained the variance of the maximum likelihood estimate of $\beta_{\hat{\theta}}(t)$ and resulting in the finding of τ that minimizes this variance. Experimenting, we found initially that the threshold where the tail of the GPD starts effecting the mean excess

function, is $\tau=449$ (while for the Log Normal it was 484). The corresponding estimate for $\beta_{\hat{\theta}}(t)$ being 1253.5.

Testing further, choosing a threshold of 550, we got estimates of $\hat{\gamma} = 0.5102$ $\hat{\sigma} = 272.75$; the Q-Q plot is shown in Fig 4.4 below. The fit of the extreme values appears to be quite good. As a subjective interpretation, the value of 550 GWh seems to coincide with the suppression of the outlying GWh mentioned in Chapter 3 Fig 3.9 (see paragraph above figure) as the background loss within an extreme value that “misbehaved”.

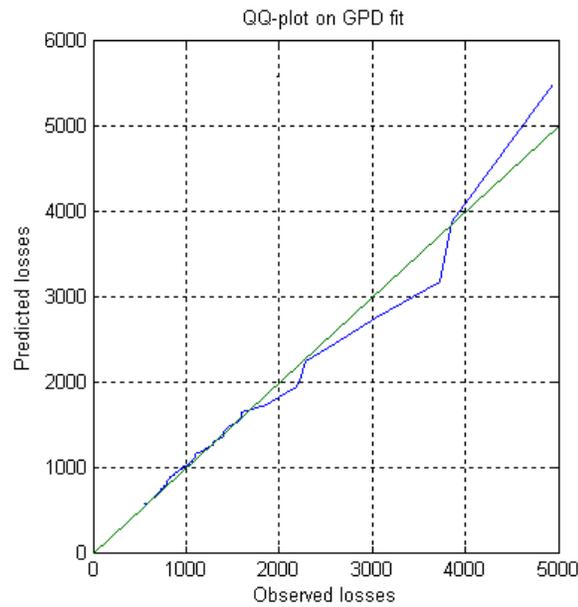


Fig 4.4 Q-Q Plot GPD $\hat{\gamma} = 0.5102$ $\hat{\sigma} = 272.75$ and $t = 550$

Extra assessments into the relationship, yielded a threshold at 850 GWh at which the GPD tail shows the best relationship with the mean excess over the threshold; this estimates the $\beta_{\hat{\theta}}(t)$ at 5310.5 GWh

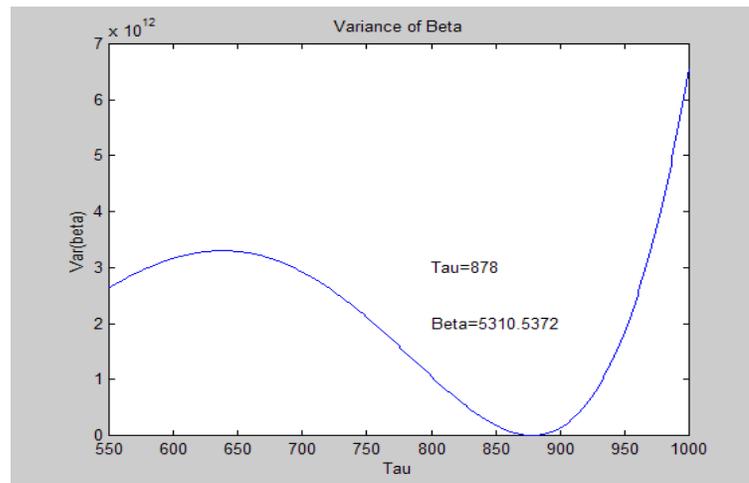


Fig 4.5 Minimum Variance found at $t = 878$

4.5 The Dirichlet Process

As seen in Fig 3.10 of Chapter 3, in the assessment at when the Mean Excess Function becomes linear becomes difficult. [10] De Waal and [11] De Waal et al worked on that challenge and utilised the method of the Negative Differential Entropy (NDE). There the choice of the threshold (using the POT method) is applied to model extremes through the NDE of the Dirichlet process using a Bayesian approach. This methodology also can be used as a goodness of fit technique.

Let x_1, \dots, x_k be k ordered observations exceeding the threshold t of a random sample of n observations from an unknown distribution with a distribution function $F_X(x | t)$. The aim is to estimate $F_X(x | t)$ if we assume a proposed distribution $\text{GPD}_{\mu, \sigma}(x-t)$. The $F_X(x | t)$ then is modelled as a Dirichlet process with the GPD as its parameters. Then from [20] Honkela, [11] De Waal et al, gets (see Eq C2.14 in Appendix C):

$$\text{NDE} = \text{E}[\text{Log } p(\mathbf{p})]$$

$$\text{E}[\text{Log } p(\mathbf{p})] = J_k$$

$$J_k = -\text{Log } Z(\mathbf{u}) + \sum_{i=1}^n (u_i - 1) [\Psi_0(u_i) - \Psi_0(u_0)] \quad \text{Eq 4.33}$$

Subsequently, as proposed by [11] De Waal et al, one needs to select k (i.e. the threshold) such that the NDE, in Eq 4.33 is at minimum, conversely this means that the information is at maximum (see the principles of entropy in Appendix C paragraphs 2.8 and 2.9).

A set of results is given in Fig 4.6 here below, together with the algorithm used.

As explained above, this kind of method provides the means to select, at the minimum NDE, the threshold with the GPD parameters that were estimated. By substituting the GPD parameters with new estimates, new levels of NDE are obtained; higher NDE levels would indicate a poorer GPD fit. Not sufficient credit is given to this method in this thesis, suffice it to say that it was experimented with and at prima-facie it looks promising. A more detailed rendition is given in Appendix C paragraphs 2.8 and 2.9

The results obtained from the graph in Fig 4.6 indicated that the most contributing values to fit of the GPD tail were the 6 largest extremes.

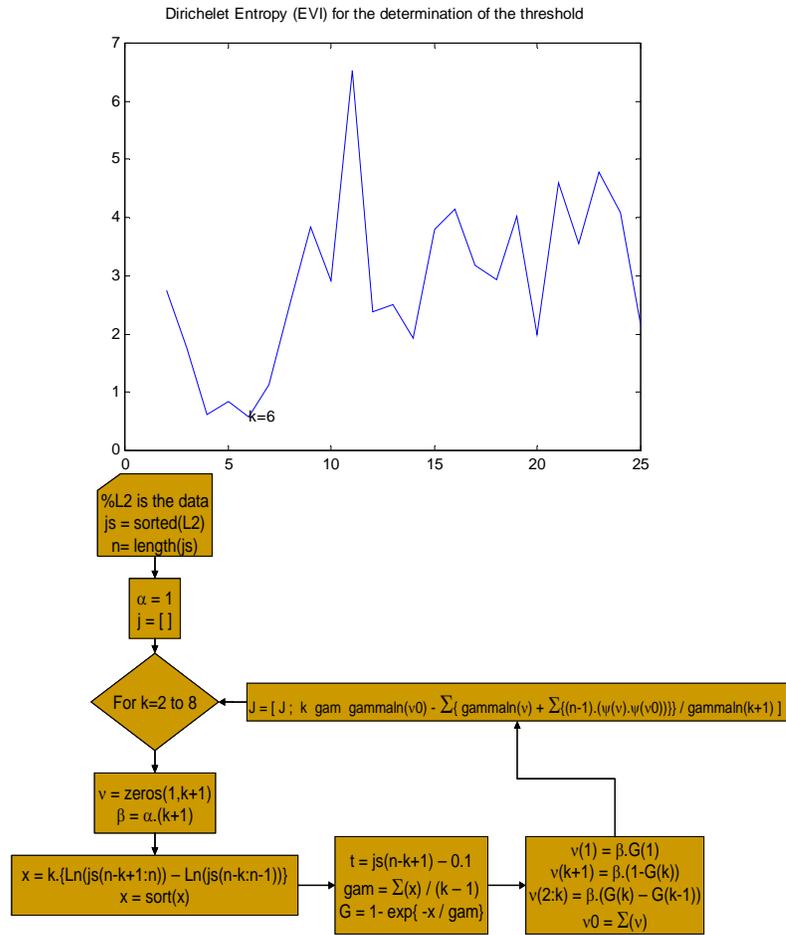


Fig 4.6 Graphic Result & Matlab Algorithm of NDE

CHAPTER 5

Conclusions

5.1 Categorisation

The means of using Cluster Analysis provided an initial method to classify large losses incurred by the GUs. In particular the Two-Way Joining method (results shown in Fig 2.3) provided initial “limits” with which these categories could be formed. These were practically applied in our business as what we termed “layers” for the GWh Losses.

The yearly total System GWh Loss indicated that a Loglogistic distribution fit is appropriate with a threshold of 1763 GWh.

This was shown to be useful but not sufficient; hence the usage of EVT became necessary for predicting extreme values in a more detailed manner.

5.2 Fitting of the Tail

The semi-parametric (Eq 3.8 and Figures 3.13 to 3.15) and full-parametric POT methodology proved very useful in the provision for the GPD fit of the tail of the GWh Losses. Figures 3.13 to 3.15, with particular emphasis on the latter provide the highlight of Chapter 3 with an interesting methodology to estimate the initial parameters (the 3-LM method). Chapter 3 concluded with the final adopted model for the GWh Loss quantiles being:

$$\hat{x}_q = 1841.8 + \frac{908.5}{0.2802} \left[\left(\frac{928(1-q)}{11} \right)^{-0.2802} - 1 \right]$$

for GWh Losses above 765.8 GWh.

Illustrated by Fig 3.20 and tabulated in Table 3.6

5.3 Bayesian Methods

Classical methods allowed us to estimate the GPD parameters (by 3LM methodology) and infer on the distribution GPD ($y \mid \sigma, \gamma, t$), however as pointed out in Chapter 4, this did not make allowance for the errors incurred when estimating σ, γ , inducing a false expectation of the predictive distribution, as the classical methodology did not cater for the fact that a future value is a stochastic event in itself (see Eq 4.31).

The Dirichlet methodology provides an interesting angle to the Bayesian philosophy in analysing the problem of the GWh Losses.

5.4 General

From an engineering perspective other interesting findings was that further research in the extremes with the introduction of covariates such as the Load Factor (LF) is a necessity. The assumptions in this thesis are that the LF is constant and the Installed Capacity (IC) does not change, which implies that the forced outages, UCLF (the GWh Losses) are in stationary mode of “bathtub hazard function”; what happens if, as is expected in the near

future, these are not constant? For instance (see pp 89-90 for more details):

1] IC changes, i.e. New Capacity (large, significant generating units) is installed; this introduces high “infant mortality” rate (i.e. higher than expected UCLF) which “lifts” the function LF vs UCLF, therefore higher than expected losses \Rightarrow a different γ , possibly different MDI? This increase in capacity is expected in 2011.

2] the LF changes according to the increase in demand and according to the LF vs UCLF function, the GWh losses (UCLF) would increase.

Care ought to be taken of the changes in γ [i.e. in the behaviour of the losses] due to time – but in our case it’s actually due to changes in LF that in turn, changes with time.

Closing Comment

The bullets given in page vii) at the beginning of the thesis were fully investigated and answered. Extreme Value Theory (EVT) methods did quantify the meaning of “Large” (or “excessive”) GWh Losses. Within the preamble of EVT and using Cluster Analysis, it was possible to categorise the losses into “layers”. A scientific model was developed (see 5.2 above) which needs to be periodically validated and maintained. Latest Statistical techniques (such as the Dirichlet one) were researched and applied with promising results. And in conclusion, as having provided the answers above, it is felt that EVT resolved our challenge. In addition, it opened pockets (as pointed in various parts of the thesis) of new areas of research.

APPENDIX A

Notation and Classic EVT Workings

1 Notation

Most of the work in this part of the Appendix is referenced to [2] and [3] Beirlant, [13] Embrechts and [25] McNeil. The more practical and applied workings of EVT are particularly referenced to [2] and [3] Beirlant while the more rigorous theoretical ones are referred to [13] Embrechts.

Let X be a continuous random variable (rv), then $F_X(x)$ is its CDF, i.e. $F_X(x) = P(X \leq x)$

The tail, or survivor function is denoted by:

$1 - F_X(x) = P(X > x)$ and where it exists, the probability density function (pdf) is $f_X(x)$ and satisfies

$$F_X(x) = \int_{-\infty}^x f_X(x).dx \quad \text{A1.0}$$

For $q \in (0 ; 1)$, the q -th quantile of the distribution of X is:

$$F^{-1}(q) = \inf\{x \in \mathfrak{R} : F_X(x) \geq q\} \quad \text{A1.1}$$

The expectation of X is,

$$E[X] = \int_{-\infty}^{+\infty} x.f_X(x).dx \quad \text{A1.2}$$

The variance of X is,

$$\text{Var}[X] = E[(X - E[X])^2] \quad \text{A1.3}$$

The covariance of X and Y is,

$$\text{Cov} [X, Y] = E [(X - E[X]) \cdot (Y - E[Y])] \quad \text{A1.4}$$

The conditional expectation of Y , given X is,

$$E [Y|X=x] = \int_{-\infty}^{+\infty} y \cdot f_{Y|X}(y|x) \cdot dy \quad \text{A1.5}$$

2 Classical EVT

In studying the maxima of rv's (or minima), it is important to find the limiting distribution of these maxima (or minima). It is hence with this objective in mind that statisticians of note have researched the possible distributions of the maxima. The objective being twofold [2] Beirlant:

1] find all possible (non-degenerate) distributions G that can appear as a limit. This is known as the **Extremal Limit** problem.

2] characterize the distributions F for which there exist sequences $\{a_n; n \geq 1\}$ and $\{b_n; n \geq 1\}$ such that

$P((M_n - b_n) / a_n \leq x) \rightarrow G_X(x)$ holds for any such specific limiting distribution [2] Beirlant, where

$M_n = \max(X_1, X_2, \dots, X_n)$ be the maximum of the sample of n . In this thesis, X could be associated to the GWh Losses out of a sample of n GU's in a particular year.

$$\therefore P(M_n \leq x) = P(X_1 \leq x, X_2 \leq x, \dots, X_n \leq x) = F^n(x)$$

1] Has been resolved in the works of [15] Fisher et al known as the Fisher-Tippet Theorem

2] Has been dealt with by [13] Embrechts and [2] Beirlant as follows

One can now find sequences of \mathfrak{R} , $a_n > 0$ and $b_n > 0$ such that $(M_n - b_n) / a_n$, i.e. the sequence of normalised maxima, converges in distribution.

If $G_X(x)$ is a non-degenerate distribution function of X , which will specify a unique type of distribution, and [13] Embrechts

$$P((M_n - b_n) / a_n \leq x) = F^n(a_n x + b_n) \rightarrow G_X(x), \text{ as } n \rightarrow \infty \quad \text{A2.0}$$

then we say that:

**F is in the maximum domain of attraction (MDA) of G,
i.e.
F \in MDA (G)**

Two rv's U and V , are of the same type (i.e. equality in type) iff $U \stackrel{d}{=} a \cdot V + b$

re-scaling re-location

This means same type of distribution under same scaling and location

In terms of their CDF's, F_U and F_V , this means:

$$F_U(x) = F_V((x - b)/a) \quad \text{A2.1}$$

This means that rv's of the same type have the same CDF's, up to possible changes of scale and location [25] McNeil.

It also means that if G is the possible limiting distribution function for the sequence $(M_n - b_n) / a_n$, then the set of such distribution functions exhibiting attraction to their limits is called the domain of attraction of G [2] Beirlant.

2.1 The Generalized Extreme Value Distribution and Index (GEV & EVI)

The GEV of a rv X is given by [2] Beirlant:

$$G_{\gamma}(x) = \begin{cases} \exp \{ -(1 + \gamma x)^{-1/\gamma} \} , & \text{if } \gamma \neq 0 \\ \exp \{ -\exp\{-x\} \} , & \text{if } \gamma = 0 \end{cases} \quad \gamma \in \mathfrak{R} \quad \text{A2.2}$$

where $1 + \gamma x > 0$ and γ is the shape parameter and is also termed the **Extreme Value Index** (EVI). The EVI forms an integral and fundamental part of EVT analyses.

In A2.2, x can be replaced by $x' = (x - \mu) / \sigma$, in which case the GEV is termed the **Standard Generalized Extreme Value** Distribution (SGEV) with the following conditions:

$$\begin{aligned} x &> \mu - (\sigma / \gamma) && \text{for } \gamma > 0 \\ x &< \mu - (\sigma / \gamma) && \text{for } \gamma < 0 \\ x &\in \mathfrak{R} && \text{for } \gamma = 0 \end{aligned}$$

Here γ is called the **shape** parameter, μ the **location** parameter and σ the **scale** parameter

Since this parameterization is continuous in γ , three extremal types of distribution can be derived (by using A2.1, [15] Fisher, [13] Embrechts and [2] Beirlant using the Helly-Bray Theorem):

$$\begin{aligned}
\gamma > 0 &\Rightarrow \text{Fréchet: } G_\gamma((x-1)/\gamma) = \Phi_{1/\gamma}(x) \\
\gamma < 0 &\Rightarrow \text{Weibull: } G_\gamma(-(x+1)/\gamma) = \Psi_{-1/\gamma}(x) \\
\gamma = 0 &\Rightarrow \text{Gumbel: } G_0(x) = \Lambda(x)
\end{aligned}$$

By substitution in A2.2, the following CDF's are obtained:

$$\text{Fréchet: } \Phi_\alpha(x) = \begin{cases} 0 & x \leq 0 \\ \exp\{-x^{-\alpha}\} & x > 0 \end{cases} \quad \alpha > 0 \quad \text{A2.3} \\
\gamma > 0$$

$$\text{Weibull: } \Psi_\alpha(x) = \begin{cases} \exp\{-(-x)^\alpha\} & x \leq 0 \\ 1 & x > 0 \end{cases} \quad \alpha > 0 \quad \text{A2.4} \\
\gamma < 0$$

$$\text{Gumbel: } \Lambda(x) = \exp\{-e^{-x}\} \quad x \in \mathfrak{R} \quad \text{A2.5} \\
\gamma = 0$$

By differentiating the CDF (using A1.0) the following pdf's can be obtained:

$$\text{Fréchet: } \phi_\alpha(x) = \begin{cases} 0 & x \leq 0 \\ \alpha x^{-\alpha-1} \cdot \exp\{-x^{-\alpha}\} & x > 0 \end{cases} \quad \alpha > 0 \quad \text{A2.6}$$

Depicted below in Fig A1.1

$$\text{Weibull: } \psi_{\alpha}(x) = \begin{cases} \alpha(-x)^{\alpha-1} \cdot \exp\{-(-x)^{\alpha}\} & x \leq 0 \\ 0 & x > 0 \end{cases} \quad \alpha > 0 \quad \text{A2.7}$$

Depicted below in Fig A1.2

$$\text{Gumbel: } \lambda(x) = e^{-x} \cdot \exp\{-e^{-x}\} \quad x \in \mathfrak{R} \quad \text{A2.8}$$

Depicted below in Fig A1.3

In the Fréchet domain, the:

1] Burr distribution is characterized by:

for $x > 0$; $\eta, \tau, \lambda > 0$:

$$F_X(x) = 1 - \left[\eta / (\eta + x^{\tau}) \right]^{\lambda}$$

$$f_X(x) = -\lambda \tau [x^{\tau-1}] \left[\eta / (\eta + x^{\tau}) \right]^{\lambda-1}$$

EVI: $1/(\lambda\tau)$

2] Generalised Pareto (GP) distribution is characterized by:

for $x > 0$; $\sigma, \gamma \neq 0$:

$$F_X(x) = 1 - \left[1 + (\gamma x / \sigma) \right]^{-1/\gamma}$$

$$f_X(x) = (1 / \sigma) \left[1 + (\gamma x / \sigma) \right]^{-(1/\gamma)-1}$$

EVI: γ

3] Pareto (Pa) distribution is characterized by:

for $x > 1$; $\gamma > 0$ for the mean to exist and $x > 2$ for the variance to exist:

$$F_X(x) = 1 - [x]^{-1/\gamma}$$

$$f_X(x) = (1 / \gamma) [x]^{-(1/\gamma)-1}$$

EVI: γ

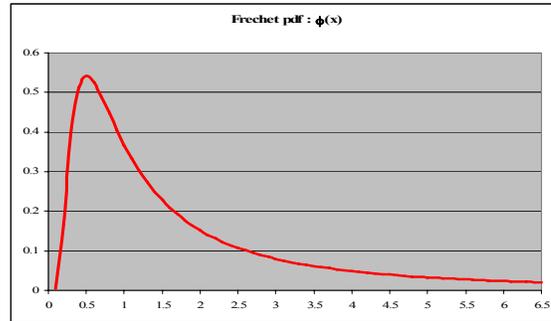


Fig A1.1: Fréchet's pdf (GEV with $\gamma = 1$)

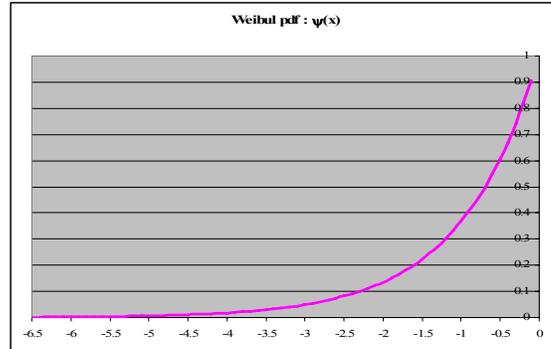


Fig A1.2: pdf of Weibull (GEV with $\gamma = -1$)

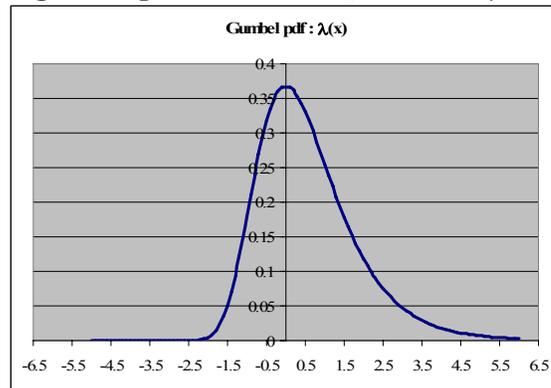


Fig A1.3: pdf of Gumbel (GEV with $\gamma = 0$)

2.2 The Fréchet-Pareto Case: $\gamma > 0$ [2] Beirlant

In this part, attention is focused on this particular domain of the GEV distribution. In some publications this type is also called the *EVD type II*. Subclasses of this type are called the *Hall Class of distributions*.

Since in this kind of domain, the value of γ is not known, [2] Beirlant recommends that from a statistical perspective, the analyst ought to work with the Quantile functions to estimate the γ .

When looking at this domain, it is important to define one of the most important underlying distributions, the Generalised Pareto distribution or GPD.

The Generalised Pareto (GPD) distribution [13] Embrechts

There are special circumstances whereby the maxima derived from a series that behaves as a GPD follow a GEV of the form:

$$\text{GPD}_{\gamma, \sigma}(x) = \begin{cases} 1 - (1 + \gamma x / \sigma)^{-1/\gamma}, & \text{if } \gamma \neq 0 \\ 1 - \exp\{-x / \sigma\}, & \text{if } \gamma = 0 \end{cases} \quad x \in (0, \infty), \gamma \in \mathfrak{R} \quad \text{A2.9}$$

From above, if $\gamma = 0$ then it's Exponential, however, when $\gamma < 0$ then

$\text{GPD}_{\gamma, \sigma}(x) = 1 - (1 + \gamma x / \sigma)^{-1/\gamma}$ and $x \in (0, -\sigma/\gamma)$ and the distribution becomes known as a Pareto II type

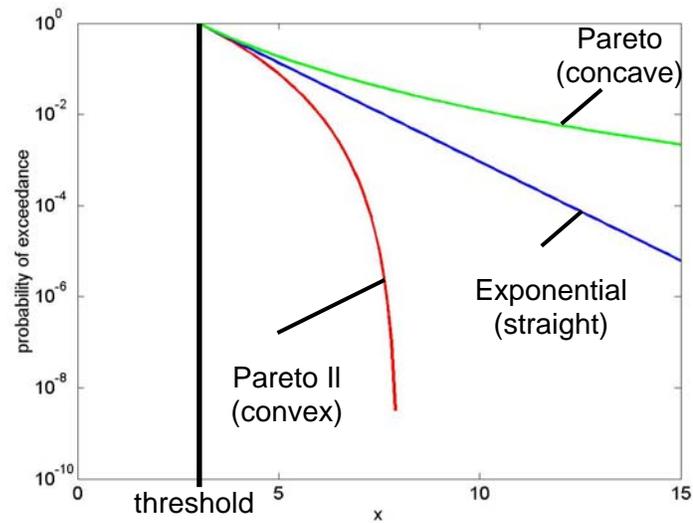
Usually the GPD ([31] Pickands) is used with a given threshold t ; in that case, x in A2.9 is replaced by $(x - t)$,

whereby $(x - t) \geq 0$ for $\gamma \geq 0$ and $0 \leq (x - t) \leq -\sigma/\gamma$ for $\gamma < 0$.

Refer to the POT method below for more information on the threshold t .

Under certain conditions the GP becomes a Strict Pareto (SP) with the following CDF:

$$SP_{1/\gamma}(x) = 1 - x^{-1/\gamma}, \text{ if } x > 1, \gamma > 0$$



from: van Gelder PHAJM

2.3 Methods of Block Maxima (BM) and Peak-Over-Threshold (POT)

In the EDA phase of the analytical process there are two classical groups in dividing the data. Both groups divide the data into consecutive blocks, but:

- i] the one that focuses on the series of Maxima (or Minima) in the blocks is termed **Block Maxima** (Minima) (BM), and
- ii] the one that focuses on the series of events exceeding a certain High (or Low) Threshold is termed the **Peak-Over-Threshold** (POT) or also known as the *Probability View*.

It is also proposed in this thesis that the Block Minima is referred to as Bm and the Threshold for the Minima group be referred to as the Trough-Under-Threshold (TUT) method; in this case it is likely that, more often than not, the probability density function is bounded (e.g. at zero) and therefore more research would be needed in this area.

In both these groups, the series are modeled separately from the rest of the observations, [2] Beirlant, [13] Embrechts, [25] McNeil and parametric estimation for the quantiles is used.

These methods deal with the aspect of tail estimations. It encompasses all values of the EVI (γ). While the BM method is inspired by the limiting behaviour of the normalised maximum of a rv, the POT method considers the conditional distribution of the excesses over a relatively high threshold [2] Beirlant.

A third approach (to the BM and POT) called the Quantile method may also be used [2] Beirlant.

As pointed out in [2] Beirlant, the utilization of the set of maxima is a weakness in the sense that not the whole data set is utilized. This is compounded in determining the block-size especially in the case of Time-Series. To deal with the BM problem, POT was one of the methods developed to deal with it.

When dealing with Time-Series and one structures the series into a time dependent model (such as AR or GARCH dealing with Returns or squared>Returns (catering for the conditional volatility) respectively, say [see Appendix B, for more information on Returns]), then the Residuals can be analysed using EVT.

Tail estimation of parameters

Out of the numerous methods in estimating the GEV families parameters, the most important ones are reflected below, [13] Embrechts, [2] Beirlant, [21] Hosking:

I] Maximum Likelihood Estimation (MLE)

The log-likelihood of a sample Y_i from a GEV, is given by:

$$\begin{aligned} & \log L(\sigma, \gamma, \mu) \\ &= -m \ln(\sigma) - \left(\frac{1}{\gamma} + 1\right) \sum_{i=1}^m \ln\left(1 + \gamma \frac{Y_i - \mu}{\sigma}\right) - \sum_{i=1}^m \ln\left(1 + \gamma \frac{Y_i - \mu}{\sigma}\right)^{-\frac{1}{\gamma}} \quad \text{A2.10} \end{aligned}$$

Provided $1 + \gamma(Y_i - \mu) / \sigma > 0$, when $\gamma = 0$, the log-likelihood function reduces to

$$\begin{aligned} \log L(\sigma, \gamma, \mu) \\ = -m \ln(\sigma) - \sum_{i=1}^m e^{\left(-\frac{Y_i - \mu}{\sigma}\right)} - \sum_{i=1}^m \left(\frac{Y_i - \mu}{\sigma}\right) \end{aligned} \quad \text{A2.11}$$

[2] Beirlant

The MLE for (σ, γ, μ) are derived by maximizing A2.10 – A2.11 in equating the partial derivatives (w.r.t .the parameters) of A2.10 to zero and solving for the parameters.

A condition for MLE method is that the data must be free of the parameters that need estimating, this is usually referred to as regularity.

The GEV is known to be “non-regular” for $\gamma \neq 0$.

III] Probability Weighted Moments (PWM)

The PWM estimator for (σ, γ, μ) is solution to the simultaneous moments equations below [2] Beirlant, p134:

$$M_{1,0,0} = \mu - \sigma \cdot \{1 - \Gamma(1 - \gamma)\} / \gamma \quad \text{A2.12}$$

$$2M_{1,1,0} - M_{1,0,0} = \sigma \cdot \{\Gamma(1 - \gamma)(2^\gamma - 1)\} / \gamma \quad \text{A2.13}$$

$$\begin{aligned} (3M_{1,2,0} - M_{1,0,0}) / (2M_{1,1,0} - M_{1,0,0}) \\ = (3^\gamma - 1) / (2^\gamma - 1) \end{aligned} \quad \text{A2.14}$$

The asymptotic consistent estimator for $M_{1,r,0}$ is:

$$\hat{M}_{1,r,0} = \frac{1}{n} \sum_{i=1}^n \left(\frac{i}{n+1}\right)^r Y_{i:n} \quad \text{A2.15}$$

By using A2.15, $M_{1,0,0}$ corresponds to the arithmetic mean which would estimate μ ; one would then proceed to compute $M_{1,1,0}$ and $M_{1,2,0}$ by using A2.15, the LHS of

A2.14 is then solved numerically to estimate γ , subsequently A2.13 is solved for σ .

For both methods above, one can apply inferential techniques to obtain confidence intervals on the estimators [2] Beirlant p137.

III] Regular Variation Approach (RVA)

If expected $\gamma > 0$ then one may utilize this type of estimation for γ . This estimator is essentially based on the same principles as the Pickands estimator even though it bears some resemblance to the Hill estimator.

$$\hat{\gamma}_{m,n}^{(RVA)} = \frac{1}{m} \sum_{i=1}^m \ln(X_{i,n}) - \ln(X_{m+1,n})$$

IV] L-Moments (L-M)

In the works of [21] Hosking, one may see that the use of L-M is an efficient method in estimating parameters of a wide range of distributions from small samples. The Probability Weighted Moments (PWM) are the precursors to L-M. The L-M are linear combinations of PWM that have simple interpretations as measures of location, scale (dispersion) and shape. These linear combinations of PWM make them less subjected to outliers.

If $F_X(x)$ is given then, the PWM are, by definition:

$$\beta_r = \int x \{F_X(x)\}^r \cdot dF_X(x), \quad r = 0, 1, 2, \dots$$

The L-M are linear combinations of β_r transformed by means of shifted Legendre polynomials, which are orthogonal on the interval (0;1) with a constant weight function.

$$\therefore \left. \begin{aligned} \lambda_1 &= \beta_0 \\ \lambda_2 &= 2\beta_1 - \beta_0 \\ \lambda_3 &= 6\beta_2 - 6\beta_1 + \beta_0 \\ \lambda_4 &= 20\beta_3 - 30\beta_2 + 12\beta_1 - \beta_0 \end{aligned} \right\} \text{A2.16}$$

The LM ratios are defined as, for $0 < \tau < 1$: $\tau = \lambda_2 / \lambda_1$
and $\tau_r = \lambda_r / \lambda_2$
 τ_3 is a measure of skewness and τ_4 is a measure of kurtosis,
 $-1 < \tau_3$; $\tau_4 < +1$

The L derived Coefficient of Variation is: L-CV = τ

From a sample size n , the PWM can be derived from

$$b_0 = \frac{1}{n} \sum_{i=1}^n X_i$$

$$b_r = \frac{1}{n} \sum_{i=r+1}^n \frac{(i-1)(i-2)\dots(i-r)}{(n-1)(n-2)\dots(n-r)} X_i$$

the β_j PWM can be estimated by b_j , $j=0,1,\dots,r$
subsequently the λ_i can be estimated from ℓ_i derived from
the set of equations A2.16
by substituting b_j for each β_j and for each λ_i linearised
moment required. Subsequently the τ and τ_r ratios can also
be estimated by u and u_r

The workings of [40] van Gelder and [30] Pandey have shown the application of LM in the estimation of the GPD parameters.

The Location (t), the Scale (σ) and the shape (γ) can be then estimated by:

$$\left. \begin{aligned} \hat{\gamma} &= (3 u_3 - 1) / (u_3 + 1) \\ \hat{\sigma} &= (1 - \hat{\gamma}) (2 - \hat{\gamma}) \ell_2 \\ \hat{t} &= \ell_1 - (2 - \hat{\gamma}) \ell_2 \end{aligned} \right\} \quad \text{A2.17}$$

This method when the 3 parameters need estimating is known as the 3-LM method, Pandey [30] et al; in that work the efficiency of this method was illustrated.

When t , the location parameter, is known, e.g. a given threshold, the method reduces to what is termed the 2-LM method and the estimates may be computed as follows:

$$\hat{\gamma} = 2 - \{(\lambda_1 - t) / \lambda_2\}$$

and

$$\hat{\sigma} = (1 - \hat{\gamma}) \cdot (\lambda_1 - t)$$

Pandey [30] states in the workings that LM are efficient estimators of the GPD when using POT methodology to estimate the tail of extremes.

2.3.1 Method of BM

This method is particular to the Fisher-Tippett Theorem which deals with the limit law for the BM with n being the block size.

Let Y_i be an iid GEV rv derived as sample maxima from observations X_j

where $i = 1, 2, \dots, n$ and $j = 1, 2, \dots, m$ (in Fig A1.4 $n=4$ and $m=20$).

By using Eq. A2.2 and substituting x for $(x - \mu)/\sigma$ one can then use the methodologies described above (I] to IV]) to estimate the GEV distribution parameters and corresponding confidence intervals (see II] above) [2] Beirlant p137.

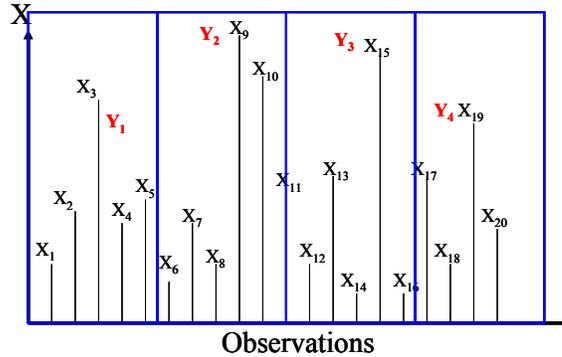


Fig A1.4: Observations vs Exceedances (BM)

The inversion of the GEV distribution function yields the estimates of the extreme quantiles:

$$Q_{Y;p} = \begin{cases} \mu + \sigma/\gamma [(-\log(1-p))^{-\gamma} - 1], & \gamma \neq 0 \\ \mu - \sigma \log(-\log(1-p)), & \gamma = 0 \end{cases}$$

Whereby μ , σ and γ are estimated according to either methods I] to IV].

When the GEV is used as an approximation of the largest observation in a block sample, then:

$$q_{Y;p}^* = \begin{cases} \mu + \sigma/\gamma [(-\log(1-p))^n - 1], & \gamma \neq 0 \\ \mu - \sigma \log(-\log(1-p)^n), & \gamma = 0 \end{cases}$$

where n is the block length, [2] Beirlant

2.3.2 Method of POT

Here one is dealing with the conditional survival function of the exceedances (or peaks) $Y = X - t$, where t is the threshold. In some literature (and above) this is also referred as \mathbf{u}

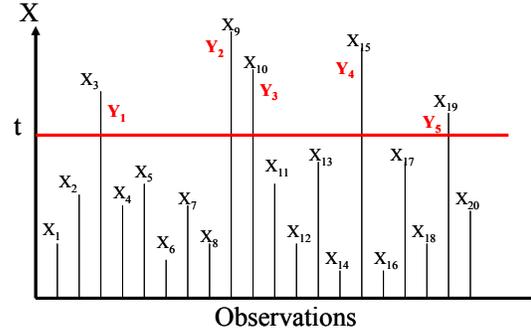


Fig A1.5: Observations vs Exceedances (POT)

Fig A1.5 above depicts the series Y over a threshold t . The differences between the BM and POT methods are clearly visible: the BM method yields Y_1 to Y_4 , while the POT method yields Y_1 to Y_5 (inclusion of X_{10} in the maxima dataset).

Although the ML and PWM present themselves in this paragraph, the methodology utilised here to estimate the EVI, is termed the Elemental Percentile Method (EPM) [2] Beirlant. This method overcomes some of the difficulties in the ML and PWM methods (γ restrictions). In the EPM there are no γ restrictions.

Following up from the visual of Fig A1.5, let Y_i be an iid GEV rv derived as sample maxima from observations X_j where $i = 1, 2, \dots, n$ and $j = 1, 2, \dots, m$.

A level t is chosen as a threshold as a point of departure whereby the exceedances of X are observed above t (see Fig. A1.5).

This means that $P[M < t] = \{P[Y_i < t]\}^N$

Therefore there are two important issues to consider when using the POT method:

- i) the selection of t , and
- ii) the independence of the peaks

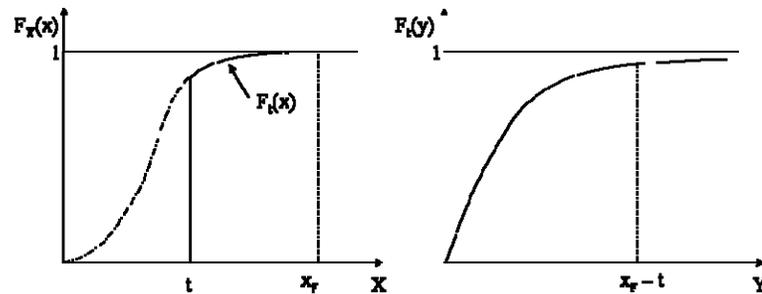


Fig A1.6: CDF of X and Conditional Dist. Function on t

The discussions and debates on the selection of t still ensue today ([11] De Waal, et al). It may be chosen graphically ([2] Beirlant [13] Embrechts) and visually.

In this method one would “choose” a threshold or estimate it by the MEF or EDP techniques (see below). Then one would estimate the parameters of the GPD by the methods **I]** to **IV]** above. This does not go through without challenges, as the estimation of t and the GPD parameters are intertwined.

The selection of this threshold is main issue: if t is too high then there are too few exceedances and therefore too high variance of the parametric estimators; if t is too low the estimators become biased and a GPD approximation is not possible; hence the challenge to obtain an “optimal t ”. The choice of t is critical for a good fit of the excesses to the distribution function. This threshold may be estimated as a trade off between the goodness-of-fit (it must be noted that this increases as t is set higher [for maxima]) and the available number of excesses above t . It may be derived by using the mean squared error of the Hill estimator ([11] De Waal, et al) or by the usage of the graphical choice (Visual Method - VM) which implies a visual determination of a “kink” in the tail of the GPD Q-Q plot; the threshold level is determined by inverting the Q function. A spin-off of this method is the determination of the EVI by isolating the values to the right of the “kink”. Subsequently a linear regressional fit is applied to these values and the estimated slope determines the EVI.

Three methods were researched in this thesis to arrive at a solution for this challenge: the Visual Method (VM), the Mean Excess Function (MEF) method and the Entropy of Dirichlet Process method (EDP) [10] De Waal.

In the POT methodology, at the threshold t one observes the exceedances of t and this means that the distribution of the excesses is given by:

$$F_t(y) = Pr\{X \leq t+y \mid X > t\} = \frac{F_X(t+y) - F_X(t)}{1 - F_X(t)}, y > 0$$

The asymptotic form of $F_t(y)$ was given first by [31] Pickands, which states that if the EVD of F exists, there are constants $c_t > 0$ such that as t tends to either $-\infty$ or $+\infty$, then:

$F_t(c_t \cdot z) \rightarrow \text{GPD}$, as given in Eq A2.9

One benefit of POT over BM is that since each exceedance is associated with a specific event, it is possible to make the parameters σ and γ , in Eq. A2.9 depend on covariates [34] Smith, et al.

For instance, one could be assessing the probability of a certain exceedance in the UCLF, as a function of the Load Factor, which is the energy demand imposed on the installed capacity.

It is generally accepted that from a time-series analysis perspective the POT approach is preferred to the BM one (albeit its challenges: does not handle stochastic volatility well in financial time series).

If we allow time to play an important role in POT, then one can express Eq A2.9 in the form of an intensity set A of exceedances within a time window $(T_1; T_2)$ as:

$$\Lambda(A) = (T_2 - T_1) (1 + \gamma(y - \mu) / \zeta)^{-1/\gamma}$$

The interpretation of these parameters is equivalent to those in Eq. A2.9, suffice it to say that, if T is in years, then it reflects the probability that the set A is “empty” of exceedances or that the probability of an annual maximum is $\leq y$. The GPD can be derived as a consequence of $\Lambda(A)$

which ties in with the POT method. In the author's opinion, research ought to be done in this camp as the distribution of T might be inverse-Gaussian when $(T_1 ; T_2)$ is not considered as fixed but rather as a time variant interval, under which exceedances occur (i.e. the exceedances is the event that triggers the time-interval, e.g. time-to-fail or rather time-to-exceed t).

2.4 Mean Excess Function

This type of diagnostic may be used to test the assumptions on the variable's behaviour under a threshold condition.

As mentioned, the t may be derived by the use of the MEF on the GPD [13] Embrechts. The MEF can be a useful tool for distinguishing distribution functions in their right tails (and its estimations).

Example using the MEF (refer to Fig A1.6):

Let us say that we model Y as a $Max(X) - t \sim Exp(\lambda)$, i.e.

$y_i = Max(x_j) - t$, with CDF: $F(y) = 1 - e^{(-y\lambda)}$

Let $e(t) = 1/\lambda$, be the Mean Excess Function, then

$1/\lambda$ is the mean exceedances above t and can be estimated

$$\text{by } \frac{1}{n} \sum_{i=1}^n y_i$$

Other distributions' MEF's can also be derived, e.g. the Pareto as indicated in the table below, [13] Embrechts.

Distribution	pdf	e(t)
Pareto	$\frac{\alpha \cdot \kappa^\alpha}{x^{\alpha+1}}$	$\frac{\kappa + t}{\alpha - 1}$, $\alpha > 0$
Exponential	$\lambda \cdot e^{-\lambda x}$, $x, \lambda > 0$	$\frac{1}{\lambda}$
Burr	$\frac{\tau \cdot \alpha \cdot \lambda^\alpha (x^{\tau-1})}{(\lambda + x^\tau)^{\alpha+1}}$	$\frac{t}{\alpha\tau - 1}$, $\alpha > 0$
GPD	$(1/\sigma) [1 + (\gamma x/\sigma)]^{-(1/\gamma) - 1}$	$\frac{\sigma + \gamma t}{1 - \gamma}$, $1 > \gamma > 0$

Table A1.1: Mean Excess Functions based on threshold t

From Table A1.1 one would plot various thresholds t on the x -axis versus its relative MEF (y -axis).

In the case of a GPD, from Table A1.1,

$e(t) = [\{\sigma/(1-\gamma)\} + \{\gamma/(1-\gamma)\} \cdot t]$, one would expect that by plotting t vs $e(t)$, one should observe a straight line with slope $\{\gamma/(1-\gamma)\}$. Hence this has the benefit of selecting a threshold t , given that we estimated γ . However some caution needs to be exercised, since (as mentioned before) for large t there are a few observations and therefore a high variability in the mean.

Let a threshold t_0 be of a “high” value and let $(y - t_0)$ follow a GPD with parameters γ and σ with $0 < \gamma < 1$ and the

$E \{(y - t_0) | y > t_0\} = \sigma / (1 - \gamma)$, then $\forall t > t_0$, the MEF is by definition:

$$e(t) = E \{(y - t) | y > t\} = [\sigma - (-\gamma) \cdot (t - t_0)] / (1 - \gamma) \\ = [\sigma + \gamma \cdot (t - t_0)] / (1 - \gamma)$$

which is of the form given in Table A1.1 for the GPD.

Hence for a given γ , $e(\mathbf{t})$ is a linear function of \mathbf{t} and provides a method to infer \mathbf{t}_0 for the GPD.

Let the empirical MEF be

$$\hat{e}(\mathbf{t}) = \frac{1}{N_t} \sum_{i=1}^{N_t} (y_i - t), \text{ where } Y \text{ is the ordered-}X, \text{ then by}$$

plotting $\hat{e}(\mathbf{t})$ on \mathbf{t} we get the Mean Excess plot, expected to be linear at $\mathbf{t} > \mathbf{t}_0$.

It can be shown that a reduction of $\hat{e}(\mathbf{t})$ is

$$\hat{e}(\mathbf{t}) = -t + \frac{1}{N_t} \sum_{i=1}^{N_t} (y_i), \text{ for each of the } N_t \text{ 's, this tends to}$$

simplify the computations.

Although, practically, it may be difficult to interpret the plot because for large \mathbf{t} there are few exceedances as mentioned above, the plot's real purpose is to detect significant shifts in the slope at different \mathbf{t} 's.

More sophisticated methods may be used when sampling Y 's off the X 's especially under a Time Series condition, whereby the peaks ought not to be associated with cyclic behaviour of the variable X (see, for instance, [13] Embrechts p270 on the effects of autocorrelation when using the Hill estimator).

2.5 GEV Mean and Variance

Here the Mean and Variance of the GEV is related to μ and σ (see SGEV in 2.1 above)

$$E[X] = \mu + \sigma \cdot \{ \Gamma(1-\gamma) - 1 \} / \gamma \quad \rightarrow \quad \mu + 0.5772 \sigma$$

for $\gamma \rightarrow 0$

Note that $\psi(1) = \text{diGamma} = -0.5772$, and 0.5772 is Euler's constant

and

$$\text{Var}[X] = \sigma^2 \cdot \{ \Gamma(1-2\gamma) - \Gamma^2(1-\gamma) \} / \gamma^2$$

$$\rightarrow [(\pi^2)/6] \cdot \sigma^2 \quad \text{for } \gamma \rightarrow 0$$

Note that $\psi'(1) = \text{triGamma} = (\pi^2)/6$

$$\text{where } \Gamma(x) = \int_0^{\infty} y^{x-1} e^{-y} dy$$

(See Appendix C paragraph 2.7 for more details)

APPENDIX B

Work on Price

To perform work in the area of electricity prices in a power pool, an understanding of the meaning of Returns is necessary.

Definition A: Returns

Returns are defined as the change in value of the asset plus the cumulative cash flow over the original value of the asset [38] Wilmott

Let S_t be the asset value at unit time t .

Then the Returns from time unit t to time unit $t + 1$ is defined [38] Wilmott:

$$\mathbf{R}_t = (S_{t+1} - S_t) / S_t \qquad \text{B1.0}$$

1. Modelling Returns: First Approach

To guide us in the choice of what parameter would represent the randomness of the Returns, one could select a measure of spread within a certain time differential.

For instance, one could choose the standard deviation of the Returns, defined as

$$\text{StDev}(\mathbf{R}_t) = \sqrt{\frac{1}{n-1} \sum_{t=1}^n (R_t - \bar{R})^2} \qquad \text{B1.1}$$

Where, $\bar{R} = \frac{1}{n} \sum_{t=1}^n R_t$

Assumption 1.1: Let the Returns be Normally distributed,
i.e. $\mathbf{R} \sim \mathbf{N}(\boldsymbol{\mu}; \boldsymbol{\sigma}^2)$

This implies the following:

$$f_{\mathbf{R}}(\mathbf{r}) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\frac{(r-\mu)^2}{2\sigma^2}}$$

Let $\mathbf{Z} = (\mathbf{R} - \boldsymbol{\mu}) / \boldsymbol{\sigma}$, to standardise.

Implying $\mathbf{R} = \boldsymbol{\mu} + \mathbf{Z} \cdot \boldsymbol{\sigma}$ B1.2

With,

$$f_{\mathbf{Z}}(\mathbf{z}) = \frac{1}{\sqrt{2\pi}} e^{-\frac{(z)^2}{2}}, \text{ and } \mathbf{Z} \sim \mathbf{N}(0;1)$$

The Returns are now being expressed by means of (B1.1) a measure of expectation $\boldsymbol{\mu}$ and variation $\boldsymbol{\sigma}$.

1.1 Effect of time upon Returns

It is however expected that the time unit of choice would also have some effect on the behaviour that is attempted to

be modelled (If one samples hourly, daily, weekly,..., the results would be different).

Under the absence of randomness, (B1.2) would be:

$$\mathbf{R} = \boldsymbol{\mu} \quad \text{B1.3}$$

Assumption 1.2: Let δt be a determined time differential (e.g. δt could be a time step of 1 hr, 1 day,...)

$$\mathbf{R} = \boldsymbol{\mu} \cdot \delta t \quad \text{B1.4}$$

if $\delta t = 1$, (B1.3) = (B1.4)

Equation A can now be expressed in the form:

$$\mathbf{R}_t = (\mathbf{S}_{t+1} - \mathbf{S}_t) / \mathbf{S}_t = \boldsymbol{\mu} \cdot \delta t$$

Re-arranging:

$$\mathbf{S}_{t+1} = \mathbf{S}_t (1 + \boldsymbol{\mu} \cdot \delta t) \quad \text{B1.5}$$

Starting at $t = 0$, equation (1.5) becomes after one time step $t = \delta t$,

$$\mathbf{S}_1 = \mathbf{S}_0 (1 + \boldsymbol{\mu} \cdot \delta t) \quad \text{B1.6}$$

after the second time step $t = 2\delta t$,

$$\mathbf{S}_2 = \mathbf{S}_1 (1 + \boldsymbol{\mu} \cdot \delta t) \quad \text{B1.7}$$

Substituting (B1.6) in (B1.7):

$$\mathbf{S}_2 = \mathbf{S}_0 (1 + \boldsymbol{\mu} \cdot \delta t)^2$$

after n time steps $t = n\delta t$

$$\mathbf{S}_n = \mathbf{S}_0 (1 + \boldsymbol{\mu} \cdot \delta t)^n$$

Let $\mathbf{X} = e^{\ln(\mathbf{X})}$, $\mathbf{X}^n = e^{n \cdot \ln(\mathbf{X})}$

therefore $\mathbf{S}_0 \cdot (\mathbf{X})^n = \mathbf{S}_0 \cdot e^{n \cdot \ln(\mathbf{X})}$, by letting $\mathbf{X} = (1 + \boldsymbol{\mu} \cdot \delta t)$, we get:

$$\mathbf{S}_0 (1 + \boldsymbol{\mu} \cdot \delta t)^n = \mathbf{S}_0 \cdot e^{n \cdot \ln(1 + \boldsymbol{\mu} \cdot \delta t)} \quad \text{B1.8}$$

Since $(1 + \mu \cdot \delta t)^n \approx e^{n \cdot \mu \cdot \delta t}$, by Taylor's expansion and Infinite series

and substituting in (B1.8),

$$S_n = S_0 (1 + \mu \cdot \delta t)^n \approx S_0 \cdot e^{n \cdot \mu \cdot \delta t}$$

Then, if after n time steps, let $T = n \cdot \delta t$,

$$S_n = S_0 (1 + \mu \cdot \delta t)^n \approx S_0 \cdot e^{\mu \cdot T} \quad \text{B1.9}$$

1.2 Random representation

In the derivation of equation (B1.9), no variation was taken account of. If now the variation effect is taken into account and imbedding the time component, then equation (B1.1) is affected by $n \cdot \delta t$ terms by using the same argument in the paragraph above.

Since $T = n \cdot \delta t$, $n = T / \delta t$, substituting in (B1.1):

$$\text{StDev}(\mathbf{R}_t) = \sqrt{\frac{\delta t}{T - \delta t} \sum_{i=1}^{T/\delta t} (R_i - \bar{R})^2} \quad \text{B1.10}$$

Hence, the deviation of the Returns is of the order $(\delta t)^{1/2}$, if it were to be represented in equation (B1.4) in taking cognisance of the variation.

From equation (B1.2), the Returns could be modelled as:

$$\mathbf{R}_t = (S_{t+1} - S_t) / S_t = \mu \cdot \delta t + Z \sigma \sqrt{\delta t}$$

Which may be written as:

$(S_{t+1} - S_t) = \underbrace{\mu \cdot S_t \delta t}_{\text{Change in Asset price}} + \underbrace{\sigma S_t Z \sqrt{\delta t}}_{\text{Model representing a Random process}}$	B1.11
---	-------

Another way of looking at equation (B1.10) is:

$$\text{Var}(\mathbf{R}_t) = \mathbf{E}[(R_t - \bar{R})^2] = \sigma^2,$$

Over small time unit intervals, the variance is: $\text{Var}(\mathbf{R}_t)$.

$$\delta t = \sigma^2 \cdot \delta t$$

Therefore the standard deviation of the Returns can be expressed by:

$$\text{Stdev}(\mathbf{R}_t) = \sigma\sqrt{\delta t} \quad \text{B1.12}$$

Combining equations (B1.2), (B1.4) and (B1.12), the same result as equation (B1.11) can be obtained.

The model represented in equation B1.11 is fundamental in modelling the behaviour of returns.

- Remarks 1:*
- 1.1] The prices themselves take on discrete values and change at fixed point in time*
 - 1.2] Changes in the values of prices over time are uncertain or random*
 - 1.3] The following approximations apply:*
 - a) the random process is continuous over time*
 - b) the spot prices vary continuously*

2. Stochastic Processes

Definition 2.1: Markov Process (MP)

A Markov Process is a stochastic process where only the value of a variable at present time t , is relevant for predicting the future [38] Wilmott.

In statistical terms, it's the conditional distribution of $X(t)$, given the information up until $\tau < t$, depends only on $X(\tau)$. [38] Wilmott

Definition 2.2: Wiener Process (WP) or Brownian Motion

It is a particular kind of MP and is given as the limiting process of a random walk as the time differential between the steps tends to zero. [38] Wilmott

In statistical terms:

If $W \sim \text{WP}$, then:

$$1) \Delta W = Z\sqrt{\Delta t} \text{ and } Z \sim N(0;1) \quad \text{B2.1}$$

2) Values of ΔW , for any two different short time intervals Δt are independent $\therefore \Delta W$ are not correlated over time.

Properties of a WP:

Let $W \sim \text{WP}$, then:

$$\begin{aligned} E[\Delta W] &= E[Z\sqrt{\Delta t}] \\ &= E[Z] \cdot E[\sqrt{\Delta t}] \\ &= 0 \cdot E[\sqrt{\Delta t}] \\ &= 0 \end{aligned}$$

$$\text{Var}[\Delta W] = E[\{\Delta W - E[\Delta W]\}^2]$$

The expected value of ΔW is zero (see above), hence:

$$\begin{aligned} \text{Var}[\Delta W] &= E[\{\Delta W\}^2] \\ &= E[\{Z\sqrt{\Delta t}\}^2] \\ &= \Delta t \cdot E[\{Z\}^2] \text{ but } E[Z^2] = \text{Var}(Z) = 1 \\ &= \Delta t \end{aligned}$$

Definition 2.3: Generalised Wiener Process (GWP)

A GWP for a variable X , is defined as the summation of a drift and a stochastic component, in the form of:

$$dx = a.dt + b.dW$$

where,

$$a \text{ and } b \in \mathfrak{R}$$

$$W \sim WP$$

$$dW = Z\sqrt{\Delta t}$$

Properties of a GWP

- If $b = 0$, then $dx/dt = a$ (constant). By integrating, $x = a.t + x_0$; $x_0 = x(0)$

Hence, X has an expected drift rate of “ a ”, per unit time.

- If $a = 0$, then $dx = b \cdot Z\sqrt{\Delta t}$, this is a WP with zero drift and variance rate of b^2 , per unit time.

Definition 2.4: Itô Process (IP)

An IP is a GWP where “ a ” and “ b ” are functions of time “ t ” and a variable X expressed in the following form:

$$dx = a(x;t).dt + b(x;t).dW$$

Lemma: (Itô’s Lemma)

Suppose that dx follows an IP, then:

Some function dG of X and t follows:

$$dG = \left(\frac{\partial G}{\partial x} a + \frac{\partial G}{\partial t} + \frac{1}{2} \cdot \frac{\partial^2 G}{\partial x^2} b^2 \right) dt + \frac{\partial G}{\partial x} b \cdot dW \quad B2.2$$

3. Modelling Returns: second method

Modelling Returns as a Generalised Wiener Process

Let

S_t = Spot price @ time t

t = time of observation

μ = drift rate

σ = volatility

$dW = Z \sqrt{\Delta t}$

and $dS_t = (S_{t+1} - S_t)$

\therefore Looking at the form of a GWP and it could be said that S_{t+1} is the stochastic price following a GWP given S_t .

Then from Definition 2.3,

$$\begin{aligned} dS_t &= \mu S_t dt + \sigma S_t dW \\ &= \mu S_t dt + \sigma S_t Z \sqrt{\Delta t} \quad , dt \ll 1 \end{aligned} \quad \text{B3.1}$$

or as $dt \rightarrow 1$,

$$S_{t+1} - S_t = \mu S_t \delta t + \sigma S_t Z \sqrt{\delta t}$$

which is similar to Eq. B1.11, which is similar to Eq. B3.1 when $\delta t \rightarrow 0$ (see [38] Wilmott p61 last two paragraphs of 3.7).

But Eq. B3.1 lacks continuity and therefore cannot be solved using normal calculus (remember: Z is stochastic, $Z \sim N(0;1)$).

Hence, Eq. B3.1 can be solved by either using a numerical method (such as Monte Carlo simulation) or Stochastic integration (e.g. using the Gamma Function, its Lemma and moment Generating Functions).

The important point of using a GWP, is that now build up a continuous-time model instead of discrete time events.

Due to the exponential properties of the spot prices (e.g. Eq. B1.9, $\therefore \ln(S_n/S_0) = \mu T$), returns are generally modelled in terms of the logs.

Hence, the widely accepted model for returns, equities, currencies, commodities and indices, is expressed in terms of the stochastic equation:

$$\boxed{dS_t = \mu S_t dt + \sigma S_t dW} \quad \text{B3.2}$$

This is a continuous-time model of an asset price, and forms the foundation of Finance Theory (notice the similarity with Eq B1.11 and B3.1).

Using Itô's Lemma, Eq. B3.2 can be expressed in terms of $\ln(S_t)$

$$\text{Let } G = \ln(S_t); \quad \frac{\partial G}{\partial S_t} = \frac{1}{S_t}; \quad \frac{\partial^2 G}{\partial S_t^2} = -\frac{1}{S_t^2}; \quad \frac{\partial G}{\partial t} = 0;$$

$$a = \mu S_t \text{ and } b = \sigma S_t$$

Substituting in Eq. B3.2, we get:

$$\begin{aligned}
d\{\ln(S_t)\} &= \left(\frac{\partial G}{\partial S_t} \mu S_t + \frac{\partial G}{\partial t} + \frac{1}{2} \cdot \frac{\partial^2 G}{\partial S_t^2} \sigma^2 S_t^2 \right) dt \\
&+ \frac{\partial G}{\partial S_t} \sigma S_t \cdot dW \\
&= \left(\mu - \frac{1}{2} \sigma^2 \right) dt + \sigma \cdot dW
\end{aligned} \tag{B3.3}$$

Therefore, $\ln(S_t)$ follows a GWP with rates:

$$\text{drift} = \mu - \frac{1}{2} \sigma^2 \text{ and variance} = \sigma^2$$

\therefore if $dt = T - t$, this means:

$$\begin{aligned}
d\{\ln(S_t)\} = \ln S_T - \ln S_t &\sim N\left\{\left(\mu - \frac{1}{2} \sigma^2\right)(T - t); \sigma^2(T - t)\right\} \\
\therefore \ln \left\{ \frac{S_T}{S_t} \right\} &\sim N\left\{\left(\mu - \frac{1}{2} \sigma^2\right)(T - t); \sigma^2(T - t)\right\}
\end{aligned}$$

From Eq. B3.3,

$$\ln \left\{ \frac{S_T}{S_t} \right\} = \left(\mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (W_T - W_t)$$

$$\therefore \boxed{S_T = S_t \cdot \exp\left\{ \left(\mu - \frac{1}{2} \sigma^2 \right) (T - t) + \sigma (W_T - W_t) \right\}}$$

Hence, the spot price at time T, contingent on the spot price at t, was derived.

In addition:

$$\begin{aligned} E[S_T] &= S_t \cdot \exp\left\{\left(\mu - \frac{1}{2}\sigma^2\right)(T-t)\right\} \cdot E[\exp\{\sigma(W_T - W_t)\}] \\ &= S_t \cdot \exp\left\{\left(\mu - \frac{1}{2}\sigma^2\right)(T-t)\right\} \cdot \exp\left\{\frac{1}{2}\sigma^2(T-t)\right\} \end{aligned}$$

$$\therefore E[S_T] = S_t \cdot e^{\mu \cdot (T-t)}$$

$$\therefore E[S_T] = S_t \cdot e^{\mu \cdot dt} \quad \text{B3.4}$$

(Compare this result to Eq. B1.9 for interest)

Equation B3.4 implies the following important points:

- The expected spot prices grow exponentially over time with an expected return μ (remember the Nominal Annual continually Compounded $A = P \cdot e^{rt}$, where P = Investment, r = Interest and t = maturity time)

➤ The spot prices are always positive

- No mean reversion was represented
- No seasonality was modelled in Eq. B3.4
- The volatility is constant

REMARKS:

- ❖ A point of interest here is that the violation of the price positivity, would destroy Eq. B3.2 which forms the basis of Finance Theory (e.g. fair pricing of all types of options would be destroyed and infer chaotic behaviour in the derivatives markets).

The Australian market experimented at paying the customers to take the energy for production purposes. This induces negative pricing, destroying Eq. B3.2.

The argument still stands that if the customer uses the energy still (as it's not storable), then why not sell it at the very minimal unit price (e.g. R1, US\$ 1, €1, A\$1, £1, ¥1, etc...).

- ❖ Another interesting aspect is the distribution of the Returns. Is it important for $\frac{\delta S}{S}$ to be $N(\mu; \sigma^2)$?

Let $Y = \frac{\delta S}{S}$ be a random variable with a determined distribution. What matters as far as transaction costs, is not the mean of Y , nor its standard deviation ([38] Wilmott p346, 24.11) but $|\bar{Y}|$ (the absolute average value of the relative returns).

- ❖ Let ${}^A R_t$ be the arithmetic representation of the Returns (also termed *Net Returns*) and ${}^G R_t$ the geometric representation (also termed *Log Returns*) of the Returns. Then mathematically they can be expressed [42] van Zyl as:

$${}^A R_t = \frac{S_{t+1} - S_t}{S_t} \quad \text{and} \quad {}^G R_t = \ln \left(\frac{S_{t+1}}{S_t} \right)$$

$$\begin{aligned} \therefore {}^G R_t &= \ln \left(\frac{S_{t+1} - S_t + S_t}{S_t} \right) = \ln (1 + {}^A R_t) \\ &= {}^A R_t - \frac{{}^A R_t^2}{2} + \frac{{}^A R_t^3}{3} - \frac{{}^A R_t^4}{4} + \dots \end{aligned}$$

[17] Giordano

If ${}^A R_t \ll 1$, then

$${}^G R_t \approx {}^A R_t$$

(However the problem comes into using the standard deviation of the Arithmetic returns, as we'll see below)

Also,

$$\begin{aligned} {}^G R_t &= \ln (1 + {}^A R_t) \\ {}^G R_t \ln(e) &= \ln (1 + {}^A R_t), \text{ since } \ln(e) = 1 \end{aligned}$$

i.e.

$$\ln (\exp\{{}^G R_t\}) = \ln (1 + {}^A R_t)$$

$$\therefore \exp\{{}^G R_t\} = 1 + {}^A R_t$$

$$\boxed{\exp\{{}^G R_t\} - {}^A R_t = 1}$$

This is an exact relationship between the arithmetic and geometric interpretations of the Returns

Scenario 1 (S1): Take a change between 100 @ time t, down to 20 @ time t+1, then

$${}^A\mathbf{R}_t = \frac{S_{t+1} - S_t}{S_t} = (20 - 100)/100 = -80\% ;$$

$${}^G\mathbf{R}_t = \ln \left(\frac{S_{t+1}}{S_t} \right) = \ln(20/100) = -1.61$$

Scenario 2 (S2): Take a change between 20 @ time t, up to 100 @ time t+1, then

$${}^A\mathbf{R}_t = \frac{S_{t+1} - S_t}{S_t} = (100 - 20)/20 = 400\% ;$$

$${}^G\mathbf{R}_t = \ln \left(\frac{S_{t+1}}{S_t} \right) = \ln(100/20) = +1.61$$

This clearly indicates that taking the standard deviation of all the ${}^A\mathbf{R}_t$ induces artificial bias in the distribution of the Net Returns (different values [-80% ; 400%] for the same change of 80).

Hence expressing the volatility as a percentage of the Log Returns seems the more plausible thing to do. ***However, this could result in a debate in terms of Eq. B1.11 and Eq. B3.1***

APPENDIX C

1. Exploratory Data Analysis (EDA)

In EDA, some methods in Data Mining were used:

- Data exploration, i.e. investigating:
 - the Problem Space: Extreme GWh losses events occurring in the production of electricity
 - the Solution Space: application of EVT to understand the behaviour of these extreme events
 - the Data Space itself: data collection, preparation, use of EDA techniques
- Data preparation
 - Data cleansing: Care and caution was taken so as no data tampering happened.
 - Meticulous scrutiny of the data was carried out to assure that:
 - No duplication occurred (software transfer between media)
 - There were no inconsistencies (e.g. same acronym for different Power Stations, like Mt for both Matimba and Matla)
 - Default values were correct (e.g. a “blank” for missing values and not a zero)
- Data transformation
 - Transforming UCLF percentages into GWh losses
 - Encoding by scale augmentation: Clustering of GWh losses into event categories (such as Main Event, Semi-catastrophic and Catastrophic)
 - Basic data enhancement such as deriving Total GWh losses for each year over the period, descriptive statistics and basic plots.

The working files are named: “Units 1990-2005.xls” and “GWh Losses EDA v3.xls”, “Workbook.xls” and “Workbook (Entropy-GEV).xls”

Software Used:

StatisticA for Windows v 5.1

Matlab v5.3 Used at the Risk Laboratory at the University of the Free State

ForecastPro for Windows

Excel 2002 Including macros and Visual Basic coding

Powerpoint 2002

Word 2002

2. General Statistical Work

2.1 Bayes Theorem

From Bayes Theorem:

$$f_{X|Y}(x|y) = f_{X,Y}(x,y) / f_Y(y) \quad \text{C2.0}$$

When X and Y are independent:

$$f_{X,Y}(x,y) = f_X(x) \cdot f_Y(y) \quad \text{C2.1}$$

By substituting C1.1 in C1.0

$$f_{X|Y}(x|y) = f_X(x)$$

2.2 Binomial Distribution

Usually expressed as the probability of successes, in this thesis it is expressed as the probability of failures.

Let:

X (an integer value) be the No. of failures in the sample $X = \{0, 1, \dots, n\}$

p = success rate

$q = 1 - p$ = failure rate

n = sample size

Then the Binomial Distribution, given n and q is expressed by:

$$B(n; q) ; P(X = x) = \frac{n!}{x!(n-x)!} q^x (1-q)^{n-x} \quad \text{C2.2}$$

and $P(X = x)$ is interpreted as the probability of x failure(s) out of n objects

2.3 Poisson Distribution

This distribution is derived from a Poisson process which exists if one can observe discrete events in a certain continuous window (e.g. defects per inch or per second or per cubic metre).

The Poisson model [$Psn(\lambda)$] is derived as the limit of the Binomial as $n \rightarrow \infty$ and $q \rightarrow 0$ and the product $n \cdot q = \lambda$ being constant, the expectation $E[x] = n \cdot q$

The Poisson Distribution, given λ , is expressed by:

$$Psn(\lambda): P(X = x) = \frac{e^{-\lambda} \cdot \lambda^x}{x!} \quad C2.3$$

Example: Say we have observed, in the Catastrophic category, 1 event over the period of 930 Unit Years, then $q = 1/930 = 0.00107$, if in a particular year we have a fleet of 64 GU's then $E[x] = 64 \cdot q = 0.0688$, therefore by using Eq C2.3, the chance of having zero Catastrophic events in a particular year with 64 GU's is:

$$Psn(0.068): P(X = 0) = \exp(0 - 0.0688) \cdot 1 / 1 = 0.9335$$

2.4 Relationship between the Poisson and Binomial Distributions

Let X_1 and X_2 be two iid $Psn(\lambda_i)$ rv's, and let $Y = X_1 + X_2$

From C1.0, we get:

$$f_{X|Y}(x|y) = P(X_1 = x_1, Y = y) / P(Y = y)$$

$$= P(X_1 = x_1, X_2 = y - x_1) / P(Y = y)$$

From C1.1, we get:

$$\begin{aligned}
f_{X_1|Y}(x|y) &= [P(X_1 = x_1) \cdot P(X_2 = y - x_1)] / P(Y = y) \\
&= \frac{\lambda_1^{x_1} e^{-\lambda_1} \cdot \lambda_2^{y-x_1} e^{-\lambda_2}}{x_1! \cdot (y-x_1)!} \\
&= \frac{(\lambda_1 + \lambda_2)^y e^{-\lambda_1 - \lambda_2}}{y!} \\
&= \frac{y!}{x_1!(y-x_1)!} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2} \right)^{x_1} \left(\frac{\lambda_2}{\lambda_1 + \lambda_2} \right)^{y-x_1} \\
&= \frac{y!}{x_1!(y-x_1)!} \left(\frac{\lambda_1}{\lambda_1 + \lambda_2} \right)^{x_1} \left(1 - \frac{\lambda_1}{\lambda_1 + \lambda_2} \right)^{y-x_1} \quad \text{C2.4}
\end{aligned}$$

Therefore, given the sum Y of X_1 and X_2 being two iid $Psn(\lambda_i)$ rv's, the conditional distribution of X_i is binomial (see Eq1.2 in main body of thesis) with parameters $n = y$ and $q = (\lambda_i) / (\lambda_1 + \lambda_2)$

Expanding for $Y = \sum_{i=1}^n X_i$

$$\begin{aligned}
f_{X_1|Y}(x|y) \\
&= \frac{\left(\sum_{i=1}^n X_i \right)!}{x_1! \left(\sum_{i=1}^n X_i - x_1 \right)!} \left(\frac{\lambda_1}{\sum_{i=1}^n \lambda_i} \right)^{x_1} \left(1 - \frac{\lambda_1}{\sum_{i=1}^n \lambda_i} \right)^{\sum_{i=1}^n X_i - x_1} \\
&\quad \text{C2.5}
\end{aligned}$$

Therefore, given $Y = \sum_{i=1}^n X_i$ of all X_i being n iid $Psn(\lambda_i)$ rv's, the conditional distribution of X_i is binomial with parameters $n = y$ and $q = (\lambda_i) / \sum_{i=1}^n \lambda_i$

Note here that the joint pdf may be constructed by the product of the conditional and the marginal.

$$\therefore f_{X,Y}(x,y) = f_{X|Y}(x|y) \cdot f_Y(y)$$

2.5 Quantiles

From A1.1,

For $q \in (0 ; 1)$, the q -th quantile of the distribution of a rv X is:

$$F^{-1}(q) = \inf\{x \in \mathfrak{R} : F_X(x) \geq q\}$$

Exponential Distribution (Gumbel domain)

Let X be exponentially distributed with pdf

$$f_X(x) = \lambda \cdot \exp(-\lambda x), \text{ for } \lambda > 0 \text{ and } x \geq 0.$$

Hence, its CDF (of X) is:

$$F_X(x) = 1 - \exp(-\lambda x), \text{ as given (see Appendix A Eq. A1.0).}$$

Consequently, $Q_x(p) = \inf\{x : P(X \leq x) \geq p\}$, from A1.1 above.

Thus, p -th Quantile, for any given $0 < p < 1$, is the root of $F_X(x) = p$, i.e.

$$1 - \exp(-\lambda x) = p \text{ or } \exp(-\lambda x) = 1 - p,$$

$$\text{hence } -\lambda x = \ln(1 - p)$$

$$\text{Therefore, } Q_x(p) = -[\{\ln(1 - p)\} / \lambda]$$

Since λ is a constant,

for a **Q-Q plot**,

use $\{-[\{\ln(1 - p)\} ; x\}$ as $\{\text{Horiz. ; Vert.}\}$ co-ordinates

Weibull Distribution (Weibull domain)

Let X , essentially positive, be Weibull distributed with the following CDF

$$F_X(x) = 1 - \exp(-\lambda x^\tau), \text{ } x > 0$$

$$\text{Therefore: } 1 - \exp(-\lambda x^\tau) = p \text{ or } \exp(-\lambda x^\tau) = 1 - p$$

$$\text{Hence: } (-\lambda x^\tau) = \ln(1 - p),$$

$$\text{Therefore } \tau \cdot \ln(x) = \ln[(-1/\lambda) \ln(1 - p)]$$

$$\ln [Q_x(p)] = 1/\tau \ln [(-1/\lambda) \ln (1-p)]$$

Since λ τ are constants,

for a **Q-Q plot**, use

$\{ \ln [-\ln (1-p)]; \ln (x) \}$ as { Horiz.;Vert. } co-ordinates

Pareto Distribution (Fréchet domain)

Let X , essentially positive, be Pareto distributed, then

$$F_X(x) = 1 - x^{(-1/\gamma)}, x > 0$$

$$\text{Therefore: } 1 - x^{(-1/\gamma)} = p \text{ or } x^{(-1/\gamma)} = 1 - p$$

$$\text{Hence: } (-1/\gamma) \ln (x) = \ln (1 - p),$$

$$\text{Therefore } \ln (x) = -\gamma \ln (1 - p)$$

$$\ln [Q_x(p)] = -\gamma \ln (1 - p) \quad \text{C2.6}$$

Since γ is a constant,

for a **Q-Q plot**, use

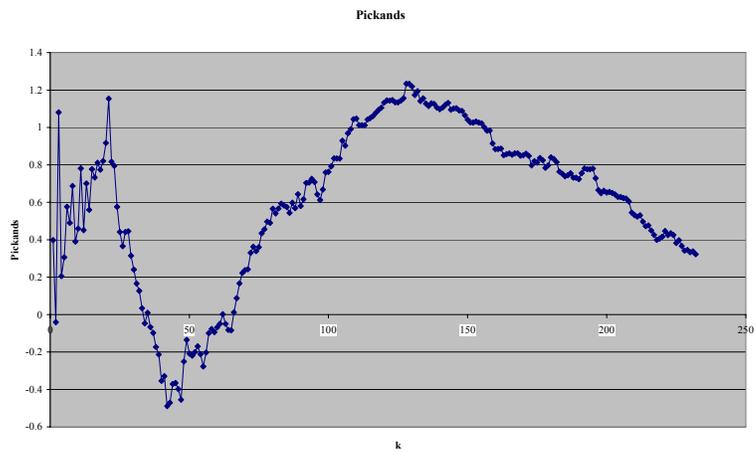
$\{ -[\ln (1-p)]; \ln (x) \}$ as { Horiz. ; Vert. } co-ordinates

2.6 Pickands Estimator

This estimator for the EVI is given by:

$$\text{EVI}_k = \hat{\gamma}_{P,k} = \frac{1}{\text{Ln}(2)} \text{Ln} \left\{ \frac{X_{n-k+1} - X_{n-2k+1}}{X_{n-2k+1} - X_{n-4k+1}} \right\}, k_{\max} \text{ is } n/4$$

Utilising the model above on the GUs GWh losses, the results of EVI_k , plotted against k , are shown in the graph here below:



The large volatility of the EVI is evident, and by the time that the limit of observations was reached, there was no stability in the indicator. A possibility is that it may have reached it at a value of between 0.2 and 0.4.

In [2] Beirlant, it is mentioned that more efficient changes in this estimator are being proposed (such as Segers[2004]).

2.7 Gamma Series Functions

It is possible to estimate the Gamma function near a point by using a series expansion at that point.

To be able to do that one needs to invoke some important findings.

2.7.1 Euler's Function

In 1730, Euler introduced the following definition:

$$\Gamma(x) = \int_0^1 [-\ln(t)]^{x-1} dt \quad \text{or} \quad \Gamma(x) = \int_0^{\infty} t^{x-1} \cdot e^{-t} dt$$

by substituting $u = -\ln(t)$ in the 1st function.

2.7.2 The Weierstrass Formula

The relation $p^x = e^{x \ln(p)} = e^{x[\ln(p) - 1/2 - \dots - 1/p]} \cdot e^{x + x/2 + \dots + x/p}$, involves:

$$\Gamma_p(x) = \frac{1}{x} \cdot \frac{1}{x+1} \cdot \frac{2}{x+2} \dots \frac{p}{x+p} p^x$$

$$\Gamma_p(x) = \frac{1}{x} \cdot \frac{e^x}{x+1} \cdot \frac{e^{x/2}}{x+2} \dots \frac{e^{x/p}}{1 + \frac{x}{p}} \left[e^{x\{\ln(p) - 1/2 - \dots - 1/p\}} \right]$$

Euler's constant (also called the Euler-Mascheroni constant) is defined as:

$$\varepsilon = \lim_{p \rightarrow \infty} \left(1 + \frac{1}{2} + \dots + \frac{1}{p} - \ln(p) \right) = 0.5772156649\dots$$

and the Weierstrass formula for the Gamma Function is (from Weierstrass theorem):

$\forall x \in \mathfrak{R}^+$, $\notin \{0, \mathfrak{Z}^-\}$ (i.e. all real numbers except 0 and negative integers)

$$\frac{1}{\Gamma(x)} = x.e^{\varepsilon.x} \prod_{p=1}^{\infty} \left(1 + \frac{x}{p} \right) e^{-\frac{x}{p}} \quad \text{C2.7}$$

by taking the logs of C2.7, the following is obtained:

$$-\ln[\Gamma(x)] = \ln(x) + \varepsilon.x + \sum_{p=1}^{\infty} \left(\ln \left(1 + \frac{x}{p} \right) - \frac{x}{p} \right), \text{ or}$$

$$\ln[\Gamma(x)] = -\ln(x) - \varepsilon.x - \sum_{p=1}^{\infty} \left(\ln \left(1 + \frac{x}{p} \right) - \frac{x}{p} \right) \quad \text{C2.8}$$

by differentiating C2.8

$$\begin{aligned} \frac{d}{dx} \{ \ln[\Gamma(x)] \} &= -\frac{1}{x} - \varepsilon + \sum_{p=1}^{\infty} \left(\frac{1}{p} - \frac{1}{x+p} \right) \\ &= -\varepsilon + \sum_{p=1}^{\infty} \left(\frac{1}{p} - \frac{1}{x+p-1} \right) \end{aligned}$$

for $x \neq 0, -1, -2, \dots$

$$= -\varepsilon + \sum_{p=1}^{\infty} \left(\frac{x-1}{p(x+p-1)} \right)$$

for $x \neq 0, -1, -2, \dots$

$$\Psi(x) = \frac{d}{dx} \{ \ln[\Gamma(x)] \} = -\varepsilon + \sum_{p=1}^{\infty} \left(\frac{x-1}{p(x+p-1)} \right) \quad \text{C2.9}$$

for $x \neq 0, -1, -2, \dots$

The equation C2.9 is defined as the *psi* or **digamma function** for any non-zero or negative integer

One may continue differentiating to obtain **Polygamma** functions:

$$\Psi'(x) = \frac{d}{dx} \{ \Psi(x) \} = \sum_{p=1}^{\infty} \left(\frac{1}{(x+p-1)^2} \right)$$

$$\Psi''(x) = \frac{d}{dx} \{ \Psi'(x) \} = - \sum_{p=1}^{\infty} \left(\frac{2}{(x+p-1)^3} \right)$$

or, in general form, the **Polygamma** can be expressed as:

$$\Psi_n(x) = \sum_{p=1}^{\infty} \left(\frac{(-1)^{n+1} n!}{(x+p-1)^{n+1}} \right) \quad \text{C2.10}$$

this means that equation C2.9 is usually expressed in the form:

$$\Psi_0(x) = \Psi(x) = -\varepsilon + \sum_{p=1}^{\infty} \left(\frac{x-1}{p(x+p-1)} \right) \quad \text{C2.11}$$

$$\Psi_0(x) = \Psi(x) = -\varepsilon + \sum_{k=1}^{x-1} \left(\frac{1}{k} \right) = -\varepsilon + H_{x-1}, \text{ where } H_x \text{ is}$$

a harmonic number

For a continuous x , equation C2.11 can be expressed as

$$\Psi_0(x) = \int_0^{\infty} \left(\frac{e^{-t}}{t} - \frac{e^{-xt}}{1-e^{-t}} \right) dt, \text{ or also as}$$

$$\Psi_0(x+1) = -\varepsilon + \int_0^1 \left(\frac{1-t^x}{1-t} \right) dt$$

$\Psi_1(x)$ is defined as the *trigamma function*.

Special cases for the *digamma* and *trigamma* :

$$\Psi_0(1) = \Psi(1) = -\varepsilon$$

$$\Psi_0\left(\frac{1}{2}\right) = \Psi\left(\frac{1}{2}\right) = -\varepsilon - 2.Ln(2)$$

$$\Psi_0\left(\frac{1}{2} + x\right) = \Psi_0\left(\frac{1}{2}\right) + 2 \cdot \sum_{k=1}^x \left(\frac{1}{2k-1} \right) = -\varepsilon + H_{x-\frac{1}{2}}$$

$$\Psi_1(1) = \frac{\pi^2}{6},$$

NB Other Theorems/Corollary of interest:

Legendre's Theorem:

$$\Gamma(x) \cdot \Gamma\left(x + \frac{1}{2}\right) = \sqrt{\pi} \Gamma(2x)$$

Gauss' Theorem:

$$\Gamma(x) \cdot \Gamma\left(x + \frac{1}{n}\right) \cdot \Gamma\left(x + \frac{2}{n}\right) \dots \Gamma\left(x + \frac{n-1}{n}\right) = (2\pi)^{\frac{(n-1)}{2}} \cdot n^{\frac{1}{2}-nx} \cdot \Gamma(nx)$$

Euler's Corollary (by setting $x = 1/n$ in Gauss'):

$$\Gamma\left(\frac{1}{n}\right) \cdot \Gamma\left(\frac{2}{n}\right) \dots \Gamma\left(\frac{n-1}{n}\right) = \frac{(2\pi)^{\frac{(n-1)}{2}}}{\sqrt{n}}$$

2.8 Entropy

Entropy referred here is Statistical Entropy. It originates from the works in thermodynamics by L Boltzmann, an Austrian physicist who was researching entropy using probability theory. In later works, the definition of Statistical Entropy was defined in terms of a macrostate variable to be considered as an expression of a function of microstate variables, or mathematically:

$$\mathcal{H}(\mathbf{p}) = -\lambda \sum_{i=1}^k [p_i \cdot \text{Log}(p_i)] \quad \text{C2.12}$$

Where, $\mathbf{p} = \{p_1, p_2, \dots, p_k\}$ is the probability density vector of element I; i.e. p_i is the probability that i will be in a given microstate and all p_i 's are evaluated for the same macrostate; λ is a constant (Boltzmann constant in thermodynamics), but may be set arbitrarily to 1 without affecting the concept of entropy in Statistical Mechanics. Since all p_i 's are probabilities between 0 and 1, this implies

that by taking the Log, the results would be negative, to counteract this effect, a negative sign is placed in front of the equation. **The Log is taken to the base 2 to reflect the presence/absence of the element i in the microstate.**

If all p_i 's are equal (e.g. distributed Uniformly), then:

$$\mathcal{H}(\mathbf{p}) = -\lambda \sum_{i=1}^k [p_i \cdot \text{Log}(p_i)] = -\lambda \{k \cdot p \text{Log}(p)\}, \text{ since all}$$

p 's are equal, $k \cdot p = 1$ and $p = 1/k$ therefore the entropy equation reduces to:

$$\mathcal{H}(p) = \lambda \{\text{Log}(k)\}$$

Hence, under this condition, the relevant factor becomes the number of i 's (states in microstate).

The larger the Entropy, the more unpredictable the outcome.

Although not utilised in the thesis, the Kullback-Leibler (KL) information-theoretic measure is worth mentioning. The KL is a value of similarity between a statistical model and a true distribution. In some cases, the statistical model would be the observed distribution while the true one may be generated (say by a simulating process). The KL value is essentially positive and zero when the 2 distributions coincide, but caution needs to be exercised as it is not a metric (it does not satisfy the triangle of inequality and is not symmetric; it is a convex function of the "true" distribution).

The KL may be thought of as the relative entropy of one distribution \mathbf{p} with another distribution \mathbf{q} . One may think of the KL (using Log_2) as the observed average number of failures by maintaining events from a distribution \mathbf{p} with a maintenance plan based on the distribution \mathbf{q} .

Since the KL is defined as the difference between an approximating entropy and the source entropy (with the latter always smaller), as an experiment approaches, through experience, the distribution given, the KL decreases towards zero.

However since the KL in itself might be misleading (if source entropy is 1 and KL is 0.1, then the latter is small; if source entropy is 0.1 and KL is 0.1, then the latter is relatively large). Hence the Relative Kullback is generally utilised as: $100 (KL / \mathcal{H})$, where \mathcal{H} is the source entropy (referred to as the arc source entropy, this can be interpreted in our case as the minimum average number of fail/succeed tests which must be performed to determine a maintenance plan).

An interesting topic but outside the realm of this thesis.

2.9 Dirichlet Process

2.9.1 Distributional Properties

A few definitions need mentioning, namely the Multinomial distribution one and the Dirichlet one.

The Multinomial distribution is a discrete distribution which gives the probability of choosing a collection of m items from a set of n items with repetitions and the probabilities of each choice given by $\mathbf{p} = \{p_1, p_2, \dots, p_n\}$, these probabilities form the parameters of the Multinomial

distribution:
$$p_X(\mathbf{x}) = n! \prod_{i=1}^n \frac{p_i^{x_i}}{x_i!}$$

The Dirichlet distribution is the conjugate prior of the parameters of the Multinomial distribution. The pdf of the

Dirichlet for variables $\mathbf{p} = \{p_1, p_2, \dots, p_n\}$, with parameters $\mathbf{u} = \{u_1, u_2, \dots, u_n\}$, is defined as:

$$\text{Dir}(\mathbf{p}; \mathbf{u}) = \frac{1}{Z(\mathbf{u})} \prod_{i=1}^n p_i^{u_i-1} \quad \text{C2.13}$$

with $\mathbf{p} = \{p_1, p_2, \dots, p_n\} \geq \mathbf{0}$, $\sum_{i=1}^n p_i = 1$

and $\mathbf{u} = \{u_1, u_2, \dots, u_n\} > \mathbf{0}$,

$$\text{where } Z(\mathbf{u}) = \frac{\prod_{i=1}^n \Gamma(u_i)}{\Gamma(\sum_{i=1}^n u_i)}$$

The parameters \mathbf{u} can be interpreted as ‘‘prior observation counts’’ for events governed by \mathbf{p} .

Let $u_0 = \sum_{i=1}^n u_i$, then the mean and variance of equation

C2.13 are:

$$E[p_i] = \frac{u_i}{u_0} \text{ and } \text{Var}[p_i] = \frac{u_i(u_0 - u_i)}{u_0^2(u_0 + 1)}$$

If $u_i \rightarrow \mathbf{0}$, then $\text{Dir}(\mathbf{p}; \mathbf{u})$ becomes non-informative and p_i 's stay the same if all u_i 's are scaled with the same multiplicative constant, but $\text{Var}[p_i]$ will get smaller as u_i 's increase.

2.9.2 Negative Differential Entropy

Define the **Negative Differential Entropy** (NDE) as $E[\text{Log } p(\mathbf{p})]$ and the expectation $E[\text{Log } p_i]$, by reducing this expectation over a two dimensional space of the Dirichlet distribution represented by:

$$(p; 1-p) \sim \text{Dir}(u_i; u_0 - u_i)$$

the expectation is then given by:

$$E[\text{Log } p_i] = \int_0^1 \frac{\Gamma(u_0)}{\Gamma(u_i) \cdot \Gamma(u_0 - u_i)} p^{u_i-1} (1-p)^{u_0-u_i-1} \text{Log } p \, dp$$

Using the digamma functions, [20] Honkela evaluates the expectation as:

$$E[\text{Log } p_i] = \Psi_0(u_i) - \Psi_0(u_0)$$

Honkela utilises the above equation to evaluate the NDE as:

$$\begin{aligned} E[\text{Log } p(\mathbf{p})] &= E \left[\text{Log} \frac{1}{Z(\mathbf{u})} \prod_{i=1}^n p_i^{u_i-1} \right] \\ &= \left[-\text{Log } Z(\mathbf{u}) + \sum_{i=1}^n (u_i - 1) E[\text{Log } p_i] \right] \\ &= -\text{Log } Z(\mathbf{u}) + \sum_{i=1}^n (u_i - 1) [\Psi_0(u_i) - \Psi_0(u_0)] \quad \text{C2.14} \end{aligned}$$

2.9.3 Comparative Formulae Comparison between Honkela equation C2.14 and equation (2) in [11] De Waal, et al

From equation C2.12

$$\mathcal{H}(\mathbf{p}) = -\lambda \sum_{i=1}^n [p_i \cdot \text{Log}(p_i)], \text{ setting } \lambda = 1, \text{ we get}$$

$$\mathcal{H}(\mathbf{p}) = -\sum_{i=1}^n [p_i \cdot \text{Log}(p_i)] = -E[\text{Log } p_i], \sum_{i=1}^n p_i = 1$$

$$\therefore E[\text{Log } p_i] = -\sum_{i=1}^n [p_i \cdot \text{Log}(p_i)],$$

Since $p_i \sim \text{Dir}(\mathbf{p}; \mathbf{u})$,

$$\begin{aligned} \mathcal{H}(\mathbf{p}) &= E[\text{Log } p_i] = E \left[\text{Log} \left\{ \frac{1}{Z(\mathbf{u})} \prod_{i=1}^n p_i^{u_i-1} \right\} \right] \\ &= E \left[\text{Log} \left\{ \frac{\Gamma \left(\sum_{i=1}^n u_i \right)}{\prod_{i=1}^n \Gamma(u_i)} \prod_{i=1}^n p_i^{u_i-1} \right\} \right] \\ \mathcal{H}(\mathbf{p}) &= -\text{Log} \left\{ \frac{\prod_{i=1}^n \Gamma(u_i)}{\Gamma \left(\sum_{i=1}^n u_i \right)} \right\} + \sum_{i=1}^n (u_i - 1) E[\text{Log } p_i] \quad , \end{aligned}$$

$$\text{but } u_0 = \sum_{i=1}^n u_i$$

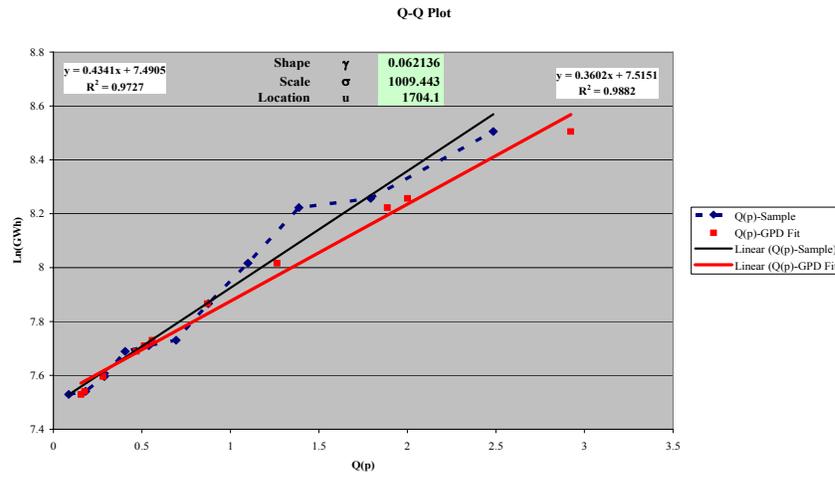
$$\therefore \mathcal{H}(\mathbf{p}) = \text{Log } \Gamma(u_0) - \sum_{i=1}^n \text{Log } \Gamma(u_i) + \sum_{i=1}^n (u_i - 1) \text{E}[\text{Log } p_i]$$

$$\begin{aligned} \therefore \mathcal{H}(\mathbf{p}) &= \\ \text{Log } \Gamma(u_0) - \sum_{i=1}^n \text{Log } \Gamma(u_i) + \sum_{i=1}^n (u_i - 1) [\Psi_0(u_i) - \Psi_0(u_0)] & \quad \text{C2.15} \end{aligned}$$

Which is similar to (2) in [11] De Waal et al, with $u_i = v_i$ and $p_i = y_i$ and $n = k+1$

Equations C2.14 and C2.15 are equivalent

2.10 Wobbles



By original 3-LM with a threshold of 1704 GWh (although not a good threshold choice, at $k=8$): we can see the wobble (blue dotted line). The issue here would be to establish if the wobbles are important underlying distributional phenomena, and not manufactures of the sample, [19] Hernandez-Campos.

3 Bayesian Methods

3.1 Fisher Information Matrix (FIM)

To arrive to the FIM, it is necessary to define the **Score Function** (V). V is the partial derivative with respect to a parameter θ of the Likelihood function.

Let X be a r.v. and its corresponding Likelihood be $L(X|\theta)$, then the score function is:

$$V = \frac{\partial}{\partial \theta} \ln[L(X|\theta)] = \frac{1}{L(X|\theta)} \cdot \frac{\partial}{\partial \theta} L(X|\theta) \quad \text{C3.1}$$

V is a function of θ and X and is a sufficient statistic for θ .

Sufficiency criterion: If $T(X)$ is sufficient for θ then $f_X(X|\theta) = g\{T(X), \theta\} \cdot h(X)$ for some functions g and h .

Also, $E[V] = 0$

The variance of V is defined as the Fisher Information and is denoted by $I(\theta)$. Therefore:

$$\text{Var}[V] = I(\theta) = E \left[\left\{ \frac{\partial}{\partial \theta} \ln[L(X|\theta)] \right\}^2 \mid \theta \right] \quad \text{C3.2}$$

It is worth noting that $0 < I(\theta) < \infty$ and $I(\theta)$ is not a function of a particular observation.

Hence the $I(\theta)$ is the amount of information that an observed r.v. X carries about a parameter θ , upon which, $L(\theta; X)$ i.e. its Likelihood, depends.

If $L(X|\theta) = f_X(X|\theta)$ and the condition

$\int \frac{\partial^2}{\partial \theta^2} f_X(X|\theta) dx = 0$ is met, then C3.2 may be expressed as:

$$I(\theta) = -E \left[\frac{\partial^2}{\partial \theta^2} \text{Ln}[f_X(X|\theta)] \right] \quad \text{C3.3}$$

Since this is the 2nd partial derivative of the Ln of f with respect to θ , $I(\theta)$ may be interpreted as measure of the spread near the maximum likelihood estimate of θ (even if the sign is negative). This kind of information became known as the Fisher Information Metric is a type of Riemannian metric on the space of probabilities.

Properties: If two r.v.'s, X and Y are independent, then:

$$I_{X;Y}(\theta) = I_X(\theta) + I_Y(\theta)$$

Interpreted, this means that provided two r.v.'s are independent, then the variance of their sum, is the sum of their variances.

From C3.3 and the sufficiency criterion as well as the fact that $h(X)$ is independent of θ , we get:

$$\frac{\partial^2}{\partial \theta^2} \text{Ln}[f_X(X|\theta)] = \frac{\partial^2}{\partial \theta^2} \text{Ln}[g\{T(X), \theta\}] \quad \text{and if } T = t_X(x)$$

is a statistic, then

$I_T(\theta) \leq I_X(\theta)$ with $I_T(\theta) = I_X(\theta) \Leftrightarrow T$ is a sufficient statistic. The inequality (Cramer-Rao) indicates that the reciprocal of the Fisher Information, is an asymptotic lower bound on the variance of any unbiased estimator for θ .

When θ is an m vector, then the Fisher Information becomes a $m \times m$ Fisher Information Matrix (FIM) with elements:

$$[I(\theta)]_{i,j} = -E \left[\frac{\partial^2}{\partial \theta_i \partial \theta_j} \text{Ln}[f_X(X|\theta)] \right] \quad \text{C3.4}$$

$[I(\theta)]_{i,j}$ is positive definite symmetric defining θ in the m-dimensional space. Same definition as above (in bold underlined) but catering for multidimensionality.

Let $\theta = (\mu; \sigma)$, i.e. a 2 parameter vector, then, from C3.4, $[I(\theta)]_{i,j}$ is a 2 x 2 FIM with

$$\begin{aligned} [I(\theta)]_{i,j} &= -E \left[\begin{array}{cc} \frac{\partial^2}{\partial \theta_1 \partial \theta_1} \text{Ln}[f_X(X|\theta)] & \frac{\partial^2}{\partial \theta_1 \partial \theta_2} \text{Ln}[f_X(X|\theta)] \\ \frac{\partial^2}{\partial \theta_2 \partial \theta_1} \text{Ln}[f_X(X|\theta)] & \frac{\partial^2}{\partial \theta_2 \partial \theta_2} \text{Ln}[f_X(X|\theta)] \end{array} \right] \\ &= -E \left[\begin{array}{cc} \frac{\partial^2}{\partial \mu^2} \text{Ln}[f_X(X|\mu; \sigma)] & \frac{\partial^2}{\partial \mu \partial \sigma} \text{Ln}[f_X(X|\mu; \sigma)] \\ \frac{\partial^2}{\partial \sigma \partial \mu} \text{Ln}[f_X(X|\mu; \sigma)] & \frac{\partial^2}{\partial \sigma^2} \text{Ln}[f_X(X|\mu; \sigma)] \end{array} \right] \quad \text{C3.5} \end{aligned}$$

Example 1: Log Normal case

for a Log Normal r.v. X , by transformation $Y = \text{Ln}(X)$, $Y \sim N(\mu; \sigma^2)$

i.e. the pdf is given by: $f_Y(y) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y-\mu)^2}{2\sigma^2}}$,

where μ and σ^2 are the log-mean and log-variance. Then

the Likelihood function is: $f_Y(y|\theta) = \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(y_i-\mu)^2}{2\sigma^2}}$

$$f_Y(y|\theta) = \frac{1}{(\sqrt{2\pi}\sigma)^n} e^{-\frac{\sum_{i=1}^n (y_i - \mu)^2}{2\sigma^2}},$$

and hence the Log-Likelihood is:

$$\begin{aligned} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{n}{2} \text{Ln}\{2\pi\sigma^2\} - \frac{1}{2\sigma^2} \sum_{i=1}^n (y_i - \mu)^2 \\ &= -\frac{1}{2} \text{Ln}\{\sigma^2\} - \frac{1}{2\sigma^2} (y - \mu)^2 + \text{Constant} \end{aligned}$$

using partial derivatives on the Log-Likelihood with respect to μ and σ^2 , we get:

$$\begin{aligned} \frac{\partial}{\partial \mu} \text{Ln}\{f_Y(y|\theta)\} &= \frac{1}{\sigma^2} (y - \mu) && \text{and} \\ \frac{\partial}{\partial \sigma} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{1}{\sigma} + \frac{1}{\sigma^3} (y - \mu)^2 \end{aligned}$$

\therefore using matrix C3.5 we get as the elements of $[\mathbf{I}(\theta)]_{ij}$:

$$\begin{aligned} \frac{\partial^2}{\partial \mu^2} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{1}{\sigma^2} && \text{and} \\ \frac{\partial^2}{\partial \mu \partial \sigma} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{2}{\sigma^3} (y - \mu) \\ \frac{\partial^2}{\partial \sigma \partial \mu} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{2}{\sigma^3} (y - \mu) && \text{and} \\ \frac{\partial^2}{\partial \sigma^2} \text{Ln}\{f_Y(y|\theta)\} &= \frac{1}{2\sigma^2} - \frac{3}{\sigma^4} (y - \mu)^2 \end{aligned}$$

Since $[\mathbf{I}(\theta)]_{i,j}$ is an expectation (see C3.5) and since $E[Y] = \mu$, $E[y - \mu] = 0$; also, $E[(y - \mu)^2] = \sigma^2$, we can reduce the four equations above to:

$$[\mathbf{I}(\theta)]_{i,j} = - \begin{bmatrix} -\frac{1}{\sigma^2} & 0 \\ 0 & -\frac{2}{\sigma^2} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sigma^2} & 0 \\ 0 & \frac{2}{\sigma^2} \end{bmatrix} \quad \text{C3.6}$$

$$\text{Det } [\mathbf{I}(\theta)]_{i,j} = \frac{2}{\sigma^4} - 0$$

This implies that the reference prior should be:

$$\pi(\mu, \sigma^2 | y) \propto \left(\frac{1}{\sigma^4} \right)^{\frac{1}{2}} = \frac{1}{\sigma^2}$$

In concordance with the usual prior for a $N(\mu, \sigma^2)$ which is $\pi(\mu, \sigma^2 | x) \propto \left(\frac{1}{\sigma^2} \right)$

Example 2: The GPD case

Let $Y \sim \text{GPD}(\gamma; \sigma)$ where $Y = X - t$ of a r.v. X over a threshold t and assume $\gamma \neq 0$, then:

$$F_Y(y) = 1 - \left[1 - \frac{\gamma}{\sigma} y \right]^{\frac{1}{\gamma}}, \quad \forall y > 0$$

$$\therefore f_Y(y) = \frac{dF_Y(y)}{dy} = \frac{1}{\gamma \sigma} \left[1 - \frac{\gamma}{\sigma} y \right]^{\frac{1}{\gamma} - 1} = \frac{1}{\sigma} \left[1 - \frac{\gamma}{\sigma} y \right]^{\frac{1}{\gamma} - 1}, \quad \forall y > 0$$

Likelihood:

$$f_Y(y|\theta) = \prod_{i=1}^n f_Y(y_i) = \left(\frac{1}{\sigma}\right)^n \prod_{i=1}^n \left(1 - \frac{\gamma y_i}{\sigma}\right)^{\frac{1}{\gamma}-1}$$

Log-Likelihood:

$$Ln\{f_Y(y|\theta)\} = -n \ln \sigma + \left(\frac{1}{\gamma} - 1\right) \sum_{i=1}^n \ln\left(1 - \frac{\gamma y_i}{\sigma}\right) \quad C3.7$$

The “trick” here is in the reduction of the equations into a form of $\left[1 - \frac{\gamma}{\sigma} y\right]^r$, $\forall \gamma < \frac{1}{2}$; the reason being that one may then use the properties of expectations, as developed by Davison AC, see [41] van Noortwijk, when developing the Fisher Information Matrix .

$$\begin{aligned} \sum_{i=1}^n y_i = \bar{y} \cdot \text{constant} = y \quad , \text{ let } y = y \cdot \frac{\gamma}{\sigma} \cdot \frac{\sigma}{\gamma} + \frac{\sigma}{\gamma} - \frac{\sigma}{\gamma} \\ \therefore y = \frac{\sigma}{\gamma} \left[1 - \left\{ 1 - \frac{\gamma y}{\sigma} \right\} \right] \quad C3.8 \end{aligned}$$

Taking 1st partial derivative of the Log-Likelihood w.r.t. γ :

$$\begin{aligned} \frac{\partial}{\partial \gamma} Ln\{f_Y(y|\theta)\} = \\ -\left(\frac{1}{\gamma^2}\right) \ln\left(1 - \frac{\gamma y}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left(\frac{-y}{\sigma}\right) \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} + \text{constant} \end{aligned}$$

Using C3.8 in the equation above, we get:

$$\begin{aligned}
& \frac{\partial}{\partial \gamma} \text{Ln}\{f_Y(y|\theta)\} = \\
& -\left(\frac{1}{\gamma^2}\right) \ln\left(1 - \frac{\gamma y}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left(\frac{-1}{\sigma}\right) \frac{\sigma}{\gamma} \left[1 - \left\{1 - \frac{\gamma y}{\sigma}\right\}\right] \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} \\
& = \\
& -\left(\frac{1}{\gamma^2}\right) \ln\left(1 - \frac{\gamma y}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left[\frac{-1}{\gamma} + \frac{1}{\gamma} \left\{1 - \frac{\gamma y}{\sigma}\right\}\right] \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} \\
& \therefore \\
& \frac{\partial}{\partial \gamma} \text{Ln}\{f_Y(y|\theta)\} = \\
& -\left(\frac{1}{\gamma^2}\right) \ln\left(1 - \frac{\gamma y}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left(\frac{1}{\gamma}\right) \left[1 - \left\{1 - \frac{\gamma y}{\sigma}\right\}\right]^{-1} \quad \text{C3.9}
\end{aligned}$$

Taking 1st partial derivative of the Log-Likelihood (C3.7) w.r.t. σ :

$$\begin{aligned}
\frac{\partial}{\partial \sigma} \text{Ln}\{f_Y(y|\theta)\} = & -\left(\frac{1}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left(\frac{\gamma y}{\sigma^2}\right) \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} \\
& + \text{constant} \quad \text{C3.10}
\end{aligned}$$

Using C3.8 in the equation above, and substituting in C3.10 we get:

$$\begin{aligned}
& \frac{\partial}{\partial \sigma} \text{Ln}\{f_Y(y|\theta)\} = \\
& -\left(\frac{1}{\sigma}\right) + \left(\frac{1}{\gamma} - 1\right) \left(\frac{\gamma}{\sigma^2}\right) \left(\frac{\sigma}{\gamma}\right) \left[1 - \left\{1 - \frac{\gamma y}{\sigma}\right\}\right] \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} \quad \text{C3.11}
\end{aligned}$$

Let $p = \left(\frac{1}{\gamma} - 1\right)$ and $k = \left(1 - \frac{\gamma y}{\sigma}\right)$ and substitute in C3.11, we get:

$$\begin{aligned}
\frac{\partial}{\partial \sigma} \text{Ln}\{f_Y(y|\theta)\} &= -\left(\frac{1}{\sigma}\right) + (p)\left(\frac{\gamma}{\sigma^2}\right)\left(\frac{\sigma}{\gamma}\right)[1 - \{k\}](k)^{-1} \\
&= -\left(\frac{1}{\sigma}\right) + (p)\left(\frac{\gamma}{\sigma^2}\right)\left(\frac{\sigma}{\gamma}\right)\left[-\frac{\{k\}p}{p} + 1\right](k)^{-1} \\
&= -\left(\frac{1}{\sigma}\right) + (p)\left(\frac{\gamma}{\sigma^2}\right)\left(\frac{\sigma}{\gamma}\right)\left[\frac{\{k\}(1 - \frac{1}{\gamma})}{p} + 1\right](k)^{-1} \\
&= -\left(\frac{1}{\sigma}\right) + (p)\left(\frac{\gamma}{\sigma^2}\right)\left(\frac{\sigma}{\gamma}\right)\left[\frac{k}{p} - \frac{k}{\gamma p} + 1\right](k)^{-1} \\
&= -\left(\frac{1}{\sigma}\right) + (p)\left(\frac{\gamma}{\sigma^2}\right)\left(\frac{\sigma}{\gamma}\right)\left(-\frac{1}{p}\right)\left[-k + \frac{k}{\gamma} - p\right](k)^{-1} \\
&= -\left(\frac{1}{\sigma}\right) - \left(\frac{1}{\sigma}\right)\left[-1 + \frac{1}{\gamma} - p(k)^{-1}\right] \\
&= -\left(\frac{1}{\sigma}\right) + \left(\frac{1}{\sigma}\right) - \frac{1}{\sigma} \frac{1}{\gamma} + \frac{1}{\sigma} p(k)^{-1} \\
&= -\frac{1}{\sigma} \frac{1}{\gamma} + \frac{1}{\sigma} p(k)^{-1} \\
\therefore \frac{\partial}{\partial \sigma} \text{Ln}\{f_Y(y|\theta)\} &= -\frac{1}{\sigma} \frac{1}{\gamma} + \frac{1}{\sigma} \left(\frac{1}{\gamma} - 1\right) \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} \quad \text{C3.12}
\end{aligned}$$

Using equation C3.9 and taking its 2nd partial derivative w.r.t. γ , letting $k = (1 - \frac{\gamma y}{\sigma})$ and using equation 3.8, we get:

$$\begin{aligned}
& \frac{\partial^2}{\partial \gamma^2} \text{Ln}\{f_Y(y|\theta)\} = \\
& \frac{2}{\gamma^3} \text{Ln}(k) - \frac{3-\gamma}{\gamma^3} + \frac{1}{\gamma^3} k^{-1} + \frac{1}{\gamma^2} \left(\frac{1}{\gamma} - 1\right) k^{-1} + \frac{2}{\gamma^3} k^{-1} - \frac{k^{-1}}{\gamma^2} + \frac{1}{\gamma^2} \left(\frac{1}{\gamma} - 1\right) \{-k^{-2}\} \\
& = \frac{2}{\gamma^3} \text{Ln}(k) - \frac{3-\gamma}{\gamma^3} + \frac{4}{\gamma^3} k^{-1} - \frac{2}{\gamma^2} k^{-1} + \frac{1}{\gamma^2} \left(\frac{1}{\gamma} - 1\right) \{-k^{-2}\} \\
& = \frac{2}{\gamma^3} \text{Ln}(k) - \frac{3-\gamma}{\gamma^3} + \frac{2(2-\gamma)}{\gamma^3} k^{-1} - \left(\frac{1-\gamma}{\gamma^3}\right) (k^{-2}) \\
& \therefore \frac{\partial^2}{\partial \gamma^2} \text{Ln}\{f_Y(y|\theta)\} = \\
& \frac{2}{\gamma^3} \text{Ln}\left(1 - \frac{\gamma y}{\sigma}\right) - \frac{3-\gamma}{\gamma^3} + \frac{2(2-\gamma)}{\gamma^3} \left(1 - \frac{\gamma y}{\sigma}\right)^{-1} - \left(\frac{1-\gamma}{\gamma^3}\right) \left(1 - \frac{\gamma y}{\sigma}\right)^{-2} \quad \text{C3.13}
\end{aligned}$$

Using equation C3.9 and taking its 2nd partial derivative w.r.t. σ , letting $k = \left(1 - \frac{\gamma y}{\sigma}\right)$ and using equation 3.8, we get:

$$\frac{\partial^2}{\partial \sigma^2} \text{Ln}\{f_Y(y|\theta)\} = \frac{1}{\sigma^2} \frac{1}{\gamma} - \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1\right) \left(1 - \frac{\gamma y}{\sigma}\right)^{-2} \quad \text{C3.14}$$

Since the matrix is symmetric we only need to evaluate one element of the opposite of the trace; using equation C3.12 and taking it's the partial derivative w.r.t. γ , letting $k = \left(1 - \frac{\gamma y}{\sigma}\right)$ and using equation 3.8, we get:

$$\begin{aligned}
& \frac{\partial^2}{\partial \sigma \partial \gamma} \text{Ln}\{f_Y(y|\theta)\} = \\
& \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ \frac{1}{\sigma} \left(\frac{1}{\gamma} - 1 \right) \left(\frac{-1}{\sigma} \right) y \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{-1}{\gamma^2} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \\
& = \\
& \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ \frac{1}{\sigma} \left(\frac{1}{\gamma} - 1 \right) \left(\frac{-1}{\sigma} \right) \frac{\sigma}{\gamma} \left[1 - \left\{ 1 - \frac{\gamma y}{\sigma} \right\} \right] \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{-1}{\gamma^2} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \\
& = \\
& \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ \frac{1}{\sigma} \left(\frac{1}{\gamma} - 1 \right) \left(\frac{-1}{\gamma} \right) (k)^{-2} - \frac{1}{\sigma} \left(\frac{1}{\gamma} - 1 \right) \left(\frac{-1}{\gamma} \right) (k)^{-1} + \frac{1}{\sigma} \left(\frac{-1}{\gamma^2} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \\
& = \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1 - \gamma) (k)^{-2} + \frac{k^{-1}}{\sigma} \left(\frac{1 - \gamma}{\gamma^2} + \frac{1}{\gamma^2} \right) \right\} \\
& = \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1 - \gamma) (k)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2 - \gamma) (k)^{-1} \right\} \\
& \therefore \frac{\partial^2}{\partial \sigma \partial \gamma} \text{Ln}\{f_Y(y|\theta)\} = \\
& \frac{1}{\sigma} \frac{1}{\gamma^2} - \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \quad \text{C3.15}
\end{aligned}$$

The Fisher Information Matrix (FIM) for a GPD is then:

$$[\mathbf{I}(\gamma; \sigma)] = -\mathbf{E} \begin{bmatrix} \text{C3.13} & \text{C3.15} \\ \text{C3.15} & \text{C3.14} \end{bmatrix}$$

$$[\mathbf{I}(\gamma; \sigma)] =$$

$$-\mathbf{E} \begin{bmatrix} \frac{2}{\gamma^3} \text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) - \frac{3 - \gamma}{\gamma^3} + \frac{2(2 - \gamma)}{\gamma^3} \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} - \left(\frac{1 - \gamma}{\gamma^3} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} & \frac{1}{\sigma \gamma^3} - \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^3} \right) (1 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^3} \right) (2 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \\ \frac{1}{\sigma \gamma^3} - \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^3} \right) (1 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^3} \right) (2 - \gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} & \frac{1}{\sigma^2 \gamma} - \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \end{bmatrix}$$

$[I(\gamma; \sigma)] =$

$$E \left[\begin{array}{l} -\frac{2}{\gamma^3} \text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) + \frac{3-\gamma}{\gamma^3} - \frac{2(2-\gamma)}{\gamma^3} \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} + \left(\frac{1-\gamma}{\gamma^3} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \\ -\frac{1}{\sigma \gamma^2} + \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \\ -\frac{1}{\sigma^2 \gamma} + \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \end{array} \right]$$

Using the expectation properties, see [41] van Noordwijk, with respect to y , i.e.

$$E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^r \right] = \frac{1}{1+r\gamma} \quad \text{and} \quad E \left[\text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) \right] = -\gamma \quad \text{and}$$

$$E \left[\left(\frac{1}{(\sigma - \lambda y)^2} \right) \right] = \frac{1}{\sigma^2 (1-2\gamma)}$$

referred to as property I, II and III respectively: P-I, P-II and P-III

and all valid for $\gamma < \frac{1}{2}$.

Hence, taking the expectation of the 1st element of the FIM:

$$E \left[-\frac{2}{\gamma^3} \text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) + \frac{3-\gamma}{\gamma^3} - \frac{2(2-\gamma)}{\gamma^3} \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} + \left(\frac{1-\gamma}{\gamma^3} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right]$$

=

$$-\frac{2}{\gamma^3} E \left[\text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) \right] + \frac{3-\gamma}{\gamma^3} - \frac{2(2-\gamma)}{\gamma^3} E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right] + \left(\frac{1-\gamma}{\gamma^3} \right) E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right]$$

Using P-I and P-II above, we get:

$$= -\frac{2}{\gamma^3} (-\gamma) + \frac{3-\gamma}{\gamma^3} - \frac{2(2-\gamma)}{\gamma^3} \frac{1}{(1-\gamma)} + \left(\frac{1-\gamma}{\gamma^3} \right) \frac{1}{(1-2\gamma)}$$

$$\begin{aligned}
&= \\
&\frac{2\gamma}{\gamma^3} + \frac{1}{\gamma^3} \left\{ \frac{(3-\gamma)(1-\gamma)(1-2\gamma) - 2(2-\gamma)(1-2\gamma) + (1-\gamma)^2}{(1-\gamma)(1-2\gamma)} \right\} \\
&= \frac{2\gamma}{\gamma^3} + \frac{1}{\gamma^3} \left\{ \frac{(-2\gamma + 6\gamma^2 - 2\gamma^3)}{(1-\gamma)(1-2\gamma)} \right\} \\
&= \frac{1}{\gamma^3} \left\{ \frac{2\gamma(1-\gamma)(1-2\gamma) + (-2\gamma + 6\gamma^2 - 2\gamma^3)}{(1-\gamma)(1-2\gamma)} \right\} \\
&= \frac{1}{\gamma^3} \left\{ \frac{2\gamma^3}{(1-\gamma)(1-2\gamma)} \right\} \\
&\therefore E \left[-\frac{2}{\gamma^3} \text{Ln} \left(1 - \frac{\gamma y}{\sigma} \right) + \frac{3-\gamma}{\gamma^3} - \frac{2(2-\gamma)}{\gamma^3} \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} + \left(\frac{1-\gamma}{\gamma^3} \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right] = \frac{2}{(1-\gamma)(1-2\gamma)} \\
&\hspace{15em} \text{C3.16}
\end{aligned}$$

Similarly, taking the expectation of the 2nd element (diagonally) of the FIM:

$$\begin{aligned}
&E \left[-\frac{1}{\sigma^2} \frac{1}{\gamma} + \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right] \\
&= -\frac{1}{\sigma^2} \frac{1}{\gamma} + \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right]
\end{aligned}$$

Using P-I above,

$$\begin{aligned}
&= -\frac{1}{\sigma^2} \frac{1}{\gamma} + \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) \frac{1}{(1-2\gamma)} \\
&= \frac{1}{\sigma^2} \left\{ -\frac{1}{\gamma} + \left(\frac{1}{\gamma} - 1 \right) \left(\frac{1}{(1-2\gamma)} \right) \right\}
\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{\sigma^2} \left\{ -\frac{1}{\gamma} + \frac{1}{\gamma(1-2\gamma)} - \frac{1}{(1-2\gamma)} \right\} \\
&= \frac{1}{\sigma^2} \left\{ \frac{-(1-2\gamma) + 1 - \gamma}{\gamma(1-2\gamma)} \right\} \\
\therefore E \left[-\frac{1}{\sigma^2} \frac{1}{\gamma} + \frac{1}{\sigma^2} \left(\frac{1}{\gamma} - 1 \right) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right] &= \frac{1}{\sigma^2(1-2\gamma)} \quad \text{C3.17}
\end{aligned}$$

Again, in a similar way, taking the expectation of the remaining element of the FIM:

$$\begin{aligned}
&E \left[-\frac{1}{\sigma} \frac{1}{\gamma^2} + \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \right] \\
&= \\
&-\frac{1}{\sigma} \frac{1}{\gamma^2} + \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1-\gamma) E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^{-2} \right] + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2-\gamma) E \left[\left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right] \right\} \\
&= \\
&-\frac{1}{\sigma} \frac{1}{\gamma^2} + \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1-\gamma) \frac{1}{(1-2\gamma)} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2-\gamma) \frac{1}{(1-\gamma)} \right\} \\
&= -\frac{1}{\sigma \gamma^2} \left\{ 1 + (1-\gamma) \frac{1}{(1-2\gamma)} - (2-\gamma) \frac{1}{(1-\gamma)} \right\} \\
&= -\frac{1}{\sigma \gamma^2} \left\{ \frac{(1-2\gamma)(1-\gamma) + (1-\gamma)^2 - (2-\gamma)(1-2\gamma)}{(1-\gamma)(1-2\gamma)} \right\}
\end{aligned}$$

$$\begin{aligned}
&= -\frac{1}{\sigma\gamma^2} \left\{ \frac{\gamma^2}{(1-\gamma)(1-2\gamma)} \right\} \\
\therefore E \left[-\frac{1}{\sigma\gamma^2} + \left\{ -\frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (1-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-2} + \frac{1}{\sigma} \left(\frac{1}{\gamma^2} \right) (2-\gamma) \left(1 - \frac{\gamma y}{\sigma} \right)^{-1} \right\} \right] &= \frac{-1}{\sigma(1-\gamma)(1-2\gamma)}
\end{aligned} \tag{C3.18}$$

Hence the FIM becomes:

$$[I(\gamma; \sigma)] = \begin{bmatrix} \frac{2}{(1-\gamma)(1-2\gamma)} & -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} \\ -\frac{1}{\sigma(1-\gamma)(1-2\gamma)} & \frac{1}{\sigma^2(1-2\gamma)} \end{bmatrix} \tag{C3.19}$$

The determinant of which is:

$$\begin{aligned}
\Delta &= \frac{2}{(1-\gamma)(1-2\gamma)} \cdot \frac{1}{\sigma^2(1-2\gamma)} - \left(-\frac{1}{\sigma(1-\gamma)(1-2\gamma)} \right)^2 \\
&= \frac{1}{\sigma^2(1-\gamma)^2(1-2\gamma)^2} \{ 2(1-\gamma) - 1 \}
\end{aligned}$$

$$\therefore \Delta = \frac{1}{\sigma^2(1-\gamma)^2(1-2\gamma)}$$

Therefore, Jeffreys' Prior for a $Y \sim \text{GPD}(\gamma; \sigma)$, where $Y = X - t$ is:

$$J\{\text{GPD}(\gamma; \sigma)\} = \sqrt{\Delta} = \frac{1}{\sigma(1-\gamma)\sqrt{(1-2\gamma)}}, \tag{C3.20}$$

for $-\frac{1}{2} < \gamma < \frac{1}{2}$

Although the equations of the FIM elements, prior to taking expectations, are different in appearance but not in content, the results of C3.19 and C3.20 are equivalent to the one obtained by [41] van Noortwijk p J4 ($[I(\gamma;\sigma)]$) in this thesis and $[I(\sigma;\gamma)]$ in van Noortwijk), quid est demonstrandum.

Inverting the FIM, let $[I(\theta)]_{ij} = [I(\theta)]$:

$$[I(\gamma;\sigma)]^{-1} = \frac{1}{\Delta} [I(\gamma;\sigma)]^T$$

$$[I(\gamma;\sigma)]^{-1} = \begin{bmatrix} \frac{2\sigma^2(1-\gamma)^2(1-2\gamma)}{(1-\gamma)(1-2\gamma)} & -\frac{\sigma^2(1-\gamma)^2(1-2\gamma)}{\sigma(1-\gamma)(1-2\gamma)} \\ -\frac{\sigma^2(1-\gamma)^2(1-2\gamma)}{\sigma(1-\gamma)(1-2\gamma)} & \frac{\sigma^2(1-\gamma)^2(1-2\gamma)}{\sigma^2(1-2\gamma)} \end{bmatrix}$$

$$[I(\gamma;\sigma)]^{-1} = \begin{bmatrix} 2\sigma^2(1-\gamma) & -\sigma(1-\gamma) \\ -\sigma(1-\gamma) & (1-\gamma)^2 \end{bmatrix} \quad \text{C3.21}$$

or in another form:

$$[I(\gamma;\sigma)]^{-1} = \sigma^2(1-\gamma)^2 \begin{bmatrix} \frac{2}{(1-\gamma)} & -\frac{1}{\sigma(1-\gamma)} \\ -\frac{1}{\sigma(1-\gamma)} & \frac{1}{\sigma^2} \end{bmatrix} \quad \text{C3.22}$$

3.2 The Delta Method (DM)

This method is a general procedure to determine estimates and provides the approximation of standard errors of arbitrary function of normally distributed random variables; it may also be used for the computation of confidence intervals for functions of MLE. This method uses a function that would be too complex to compute and by employing a linear approximation of that complex function, it formulates the variance of the simpler linear function that may be utilised for inference.

Let $\sqrt{n}(\hat{\theta} - \theta) \xrightarrow{L} N[\mathbf{0}; \text{Var}(\hat{\theta})]$, $n \rightarrow \infty$ from MLE theory

Let $g(\theta)$ be a non-linear continuous function of θ , e.g. predicted probabilities from, say, a Log-Normal, a GPD, etc...

Then, using Taylor series as an expansion, we get:

$$g(\hat{\theta}) = g(\tilde{\theta}) + \sum_{i=1}^k \frac{\partial g}{\partial \theta_i} (\hat{\theta}_i - \tilde{\theta}_i) + o(\|\hat{\theta} - \tilde{\theta}\|) \quad \text{C3.23}$$

where, $\tilde{\theta}$ is a value between $\hat{\theta}$ and θ .

$$\text{Let } g'(\tilde{\theta}) = \frac{\partial g}{\partial \theta} = \left[\frac{\partial g}{\partial \theta_1}; \frac{\partial g}{\partial \theta_2}; \dots; \frac{\partial g}{\partial \theta_k} \right]^T, \text{ evaluated at } \tilde{\theta},$$

then Eq C3.23 becomes:

$$g(\hat{\theta}) = g(\tilde{\theta}) + g'(\tilde{\theta})^T (\hat{\theta} - \tilde{\theta}) + o(\|\hat{\theta} - \tilde{\theta}\|)$$

or

$$g(\hat{\theta}) - g(\tilde{\theta}) = g'(\tilde{\theta})^T (\hat{\theta} - \tilde{\theta}) + o(\|\hat{\theta} - \tilde{\theta}\|), \quad \text{representing}$$

the MLE of $g(\theta)$

by taking the variance:

$$Var[g(\hat{\theta}) - g(\tilde{\theta})] = g'(\tilde{\theta})^T Var[\hat{\theta}] g'(\tilde{\theta})$$

$$\text{where } Var[\hat{\theta}] = \sigma^2 \mathbf{D} \quad \text{C3.24}$$

Let g_i' be the i^{th} element of $g'(\hat{\theta})$ and let v_{ij} be the ij^{th} element of the matrix $\sigma^2 \mathbf{D}$, then:

$$Var[g(\hat{\theta})] = \sum_{i=1}^k \sum_{j=1}^k g_i' g_j' v_{ij}$$

Then as $n \rightarrow \infty$,

$$\sqrt{n} [g(\hat{\theta}) - g(\tilde{\theta})] \xrightarrow{L} N\{\mathbf{0}; n\sigma^2 [g'(\tilde{\theta})^T \mathbf{D} g'(\tilde{\theta})]\} \quad , n \rightarrow \infty \quad \text{C3.25}$$

Practically the partial derivatives are evaluated at $\hat{\theta}$ relative to θ .

Since Eq C3.24 can be expressed in terms of the Fisher Information Matrix (Eq 3.2 above), then Eq C3.25 may be expressed as:

$$\sqrt{n} [g(\hat{\theta}) - g(\theta)] \xrightarrow{L} N\{\mathbf{0}; [g'(\theta)^T \mathbf{I}^{-1}(\theta) g'(\theta)]\} \quad , n \rightarrow \infty \quad \text{C3.26}$$

4 General Discussions and Remarks

4.1 Discussion on EDA

Linear Correlations

Correlations were found amongst GU's GWh Losses, eg for Arnot GU3 with the following GU's:

TU1	0.827
KE1	0.799
ML3	0.795
MB5	0.735
LE1	0.733
HE9	0.732
TU4	0.696
HE2	0.645
HE6	0.637
MJ3	0.602
HE1	0.601
ML1	0.595
HE3	0.591

However, these correlations are not necessarily yielding usable information: Coal is not a factor (different and unique sources). Plant equipment and design also not and the same goes for the quality of water. Nodal connections are same for some and totally different for others. At this point in time it is difficult to harness these correlations (future work will be performed using Correspondence Analysis), in other words, for instance, how do we answer the question: "so what that Arnot GU 3 is highly correlated to Tutuka GU 1, in terms of yearly GWh Losses?"

The hypothesis at the moment that the author can theorize is Management intervention and Load Factor (LF) effects. The latter has been mentioned in paragraph 2.3.3, pp.30-31 and illustrated in Fig 2.14 p.30. As stated in that paragraph this would constitute further analyses with a different dataset of a much larger nature. This has already been commenced by the author and just to give an idea, the size of one Power Station file consisting of 6 GU's is 17 Gigabytes!

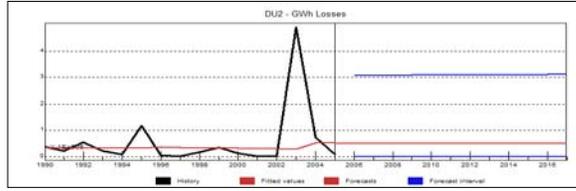
Time Series Analyses

This included analyses of the Autocorrelations and Partial Autocorrelations Functions. A sample of the results for 4 GU's (the others tend to follow similar results and patterns) are illustrated in the next two pages.

The only GU that showed significance (in the 1st order autocorrelation) was Duvha GU 4.

The Ljung-Box statistic indicated significance at the 95% level.

The reason is known to our business: there was a particular managerial intervention which was put into effect from 1996. The trend might be misleading for this interpretation and change-point analysis more appropriate in this case.



Report for DU2

Analysis

- Using rule-based logic the choice was narrowed down to exponential smoothing or Box-Jenkins.
- Series is too short to consider Box-Jenkins.
- Exponential Smoothing is used.

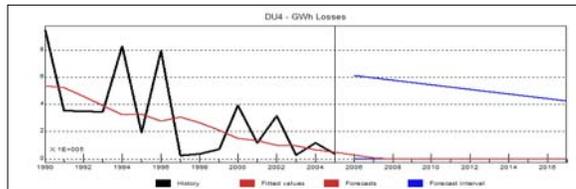
Model Details

Selection
Simple exponential smoothing: No trend, No seasonality

Component	Smoothing Wgt	Final Value
Level	0.05	499760

Within-Sample Statistics

Sample size	16	No. parameters	1
Mean	567318	Std. deviation	1208578.89
R-square	0	Adj. R-square	0
Durbin-Watson	2.04	Ljung-Box(10)	2.3 P=0.01
Forecast error	1247059.53	BIC	1316744.68
MAPE	467.94	RMSE	1207460.19
MAD	534168.34		



Report for DU4

Analysis

- Using rule-based logic the choice was narrowed down to exponential smoothing or Box-Jenkins.
- Series is too short to consider Box-Jenkins.
- Exponential Smoothing is used.

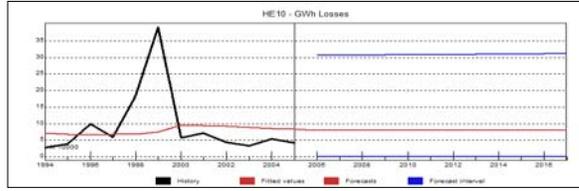
Model Details

Selection
Holt exponential smoothing: Linear trend, No seasonality

Component	Smoothing Wgt	Final Value
Level	0.06474	48106
Trend	0.9998	-21647

Within-Sample Statistics

Sample size	16	No. parameters	2
Mean	310152.76	Std. deviation	304437.36
R-square	0.27	Adj. R-square	0.22
Durbin-Watson	2.46	Ljung-Box(9)	19.1 P=0.98
Forecast error	269720.36	BIC	300037.31
MAPE	178.2	RMSE	252300.29
MAD	197138.88		



Report for HE10

Analysis

- Using rule-based logic the choice was narrowed down to exponential smoothing or Box-Jenkins.
- Series is too short to consider Box-Jenkins.
- Exponential Smoothing is used.

Model Details

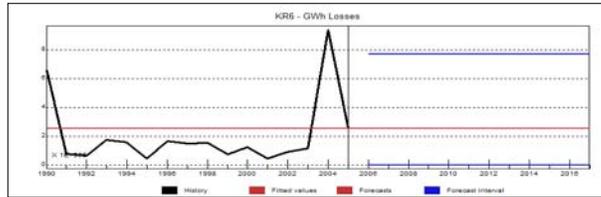
Selection

Simple exponential smoothing: No trend, No seasonality

Component	Smoothing Wgt	Final Value
Level	0.06563	79929

Within-Sample Statistics

Sample size	12	No. parameters	1
Mean	91397.48	Std. deviation	104215.34
R-square	0	Adj. R-square	0
Durbin-Watson	1.48	Ljung-Box(6)	4.3 P=0.36
Forecast error	108509.78	BIC	115223.34
MAPE	82.47	RMSE	103890.2
MAD	66003.92		



Report for KR6

Analysis

- Using rule-based logic the choice was narrowed down to exponential smoothing or Box-Jenkins.
- Series is too short to consider Box-Jenkins.
- Exponential Smoothing is used.

Model Details

Selection

Simple exponential smoothing: No trend, No seasonality

Component	Smoothing Wgt	Final Value
Level	0	256318

Within-Sample Statistics

Sample size	16	No. parameters	1
Mean	205957.17	Std. deviation	244182.91
R-square	0	Adj. R-square	0
Durbin-Watson	1.65	Ljung-Box(10)	1.8 P=0.00
Forecast error	249660.85	BIC	263611.79
MAPE	162.09	RMSE	241733.08
MAD	186434.63		

4.2 Steven's Theorem

The theorem originates from problem that the author was facing when trying to price Options using the Black-and-Scholes model in the realm of large volatilities in Energy Markets. The theorem was presented at the South African Statistical Conference (Cape Town) in November 2001.

“Steven” is an acronym for: **Statistical Estimator for the Volatility – an Evaluation** which is the Title of the presentation.

Steven's Theorem:

If we assume that the α angles formed by the spot prices (S) and the horizontal axis (time) follow a Uniform distribution, then the spot price difference (r) in the returns (R), behaves as a Cauchy distribution.

Implications of Steven's Theorem:

This implies that the distribution of the returns (R) depends on the instantaneous distribution of the Spot prices.

If this is assumed to be $N(\mu;\sigma)$, then (R), by simulation, shows to be Cauchy

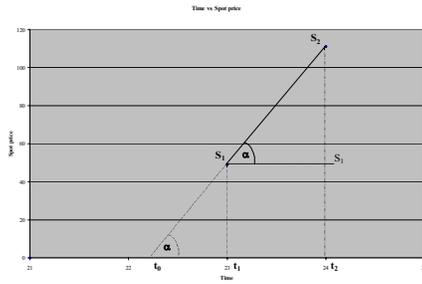
The author chose to prove this geometrically:

One of the definitions for the volatility is that it's the Standard Deviation of the Returns

(R_i) which in turn are defined as:
$$R_i = \frac{S_{i+1} - S_i}{S_i}$$

"the other angle"

19



$$\tan \alpha = \frac{S_2 - S_1}{t_2 - t_1}$$

$$\tan \alpha = \frac{S_1 - 0}{t_1 - t_0}$$

$$\therefore \frac{S_2 - S_1}{S_1} = \frac{t_2 - t_1}{t_1 - t_0}$$

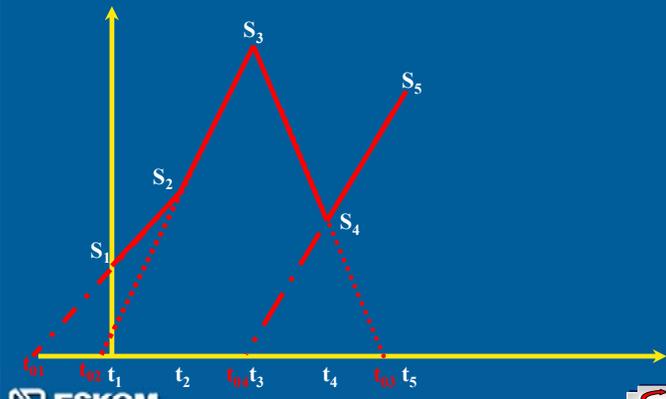
This equates to the instantaneous R_1 , whereby $t_2 - t_1$ would be unitary (e.g. hourly, daily, etc...)

$$\therefore R_1 = \frac{S_2 - S_1}{S_1} = \frac{1}{t_1 - t_0}$$



Illustrated on the price graph

25



"how the other angle behaves"

Platform X @ unitary distance
 $|t_i - t_{i+1}| = 1$

ESKOM

Assume α is Uniformly distributed over

$$-\frac{\pi}{2} \leq \alpha \leq \frac{\pi}{2}$$

Then, for that interval the pdf is: $f_A(\alpha) = \frac{1}{\pi}$

Since $|t_i - t_{i+1}| = 1$, distance, then $\tan \alpha = (r/1)$
 i.e. $\tan^{-1} r = \alpha$, $r = S_2 - S_1$
 Therefore, $g_R(r) \cdot dt = f_A(\alpha) \cdot |d\alpha/dr| \cdot dr$
 $g_R(r) = [1/\pi] \cdot [1/(1+r^2)]$

ESKOM

The Cauchy pdf is given by:

$$f_X(x) = \frac{1}{\pi\tau} \cdot \frac{1}{1 + (x + \mu)^2 / \tau^2}, \quad -\infty < x < +\infty$$

If $\mu = 0$ and $\tau = 1$, then the Cauchy above becomes:

$$f_X(x) = \frac{1}{\pi} \cdot \frac{1}{1 + (x)^2}, \quad -\infty < x < +\infty$$

This is of the form as shown in the last slide [$g_R(r)$].

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